

Shifted Laplace and related preconditioning for finite element approximations of the Helmholtz equation

Ivan Graham and Euan Spence (Bath, UK)

Collaborations with:

Paul Childs (Schlumberger Gould Research),
Martin Gander (Geneva)
Douglas Shanks (Bath)
Eero Vainikko (Tartu, Estonia)

Woudschoten
October 2014

Outline of talk:

- Seismic inversion, HF Helmholtz equation
- (conventional) FE discretization, preconditioned GMRES solvers
- sharp analysis of preconditioners based on absorption
- analytic wavenumber- and absorption-explicit PDE bounds
- a class of (scalable) DD preconditioners, with coarse grids
- a new convergence theory for DD for Helmholtz
- some open theoretical questions

Outline of talk:

- Seismic inversion, HF Helmholtz equation
- (conventional) FE discretization, preconditioned GMRES solvers
- sharp analysis of preconditioners based on absorption
- analytic wavenumber- and absorption-explicit PDE bounds
- a class of (scalable) DD preconditioners, with coarse grids
- a new convergence theory for DD for Helmholtz
- some open theoretical questions

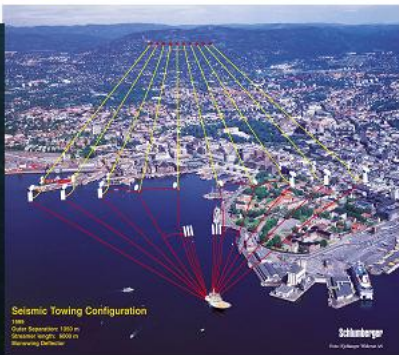
Chandler-Wilde, IGG, Langdon, Spence:

Numerical-asymptotic boundary integral methods in high-frequency acoustic scattering

Acta Numerica 2012

3. "very noisy" 4. "K. O."

Marine seismic



Seismic inversion

Inverse problem: reconstruct material properties of rock under sea bed (characterised by wave speed $c(x)$) from observed echos.

Regularised iterative method: repeated solution of the (forward problem): the wave equation

$$-\Delta u + \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} = f \quad \text{or its elastic variant}$$

Frequency domain:

$$-\Delta u - \left(\frac{\omega}{c}\right)^2 u = f, \quad \omega = \text{frequency}$$

solve for u with approximate c .

Seismic inversion

Inverse problem: reconstruct material properties of subsurface (wave speed $c(x)$) from observed echos.

Regularised iterative method: repeated solution of the (forward problem): the wave equation

$$-\Delta u + \frac{\partial^2 u}{\partial t^2} = f \quad \text{or its elastic variant}$$

Frequency domain:

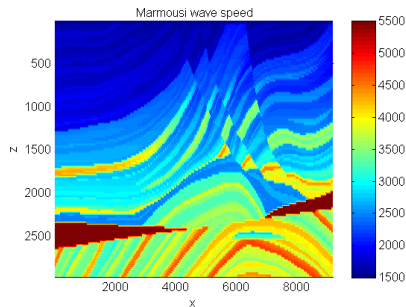
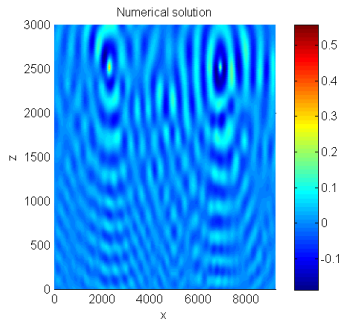
$$-\Delta u - \left(\frac{\omega L}{c}\right)^2 u = f, \quad \omega = \text{frequency}$$

solve for u with approximate c .

Large domain of characteristic length L .

effectively high frequency

Marmousi Model Problem

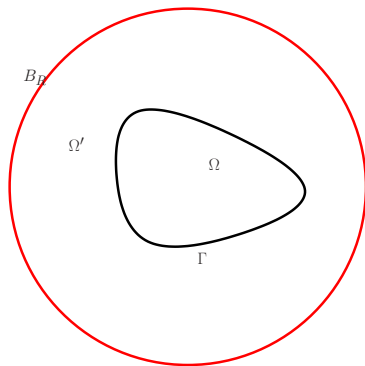


- [P. Childs, Schlumberger (2007)]: Solver of choice based on principle of limited absorption (Erlangga, Osterlee, Vuik, 2004)...
- **This work:** Analysis of this approach and use it to build better methods

Model interior impedance problem

$$\begin{aligned} -\Delta u - k^2 u &= f \quad \text{in bounded domain } \Omega \\ \frac{\partial u}{\partial n} - iku &= g \quad \text{on } \Gamma := \partial\Omega \end{aligned}$$

....Also truncated sound-soft scattering problems in Ω'



Linear algebra problem

- weak form

$$\begin{aligned} a(u, v) &:= \int_{\Omega} (\nabla u \cdot \nabla \bar{v} - k^2 u \bar{v}) - ik \int_{\Gamma} u \bar{v} \\ &= \int_{\Omega} f \bar{v} + \int_{\Gamma} g \bar{v} \end{aligned}$$

- (Fixed order) finite element discretization

$$\mathbf{A} \mathbf{u} := (\mathbf{S} - k^2 \mathbf{M}^{\Omega} - ik \mathbf{M}^{\Gamma}) \mathbf{u} = \mathbf{f}$$

Often: $h \sim k^{-1}$ **but pollution effect:**
for quasioptimality need $h \sim k^{-2} ??$, $h \sim k^{-3/2} ??$

Du and Wu 2013

Melenk and Sauter 2011 (hp)

Linear algebra problem

- weak form **with absorption** $k^2 \rightarrow k^2 + i\varepsilon$,

$$\begin{aligned} a_\varepsilon(u, v) &:= \int_{\Omega} (\nabla u \cdot \nabla \bar{v} - (k^2 + i\varepsilon)u\bar{v}) - ik \int_{\Gamma} u\bar{v} \\ &= \int_{\Omega} f\bar{v} + \int_{\Gamma} g\bar{v} \quad \text{“Shifted Laplacian”} \end{aligned}$$

[Equivalently $k^2 + i\varepsilon \longleftrightarrow (k + i\rho)^2$]

- Finite element discretization

$$\mathbf{A}_\varepsilon \mathbf{u} := (\mathbf{S} - (k^2 + i\varepsilon)\mathbf{M}^\Omega - ik\mathbf{M}^\Gamma)\mathbf{u} = \mathbf{f}$$

Preconditioning with approximations of A_ϵ^{-1} - A very short history

Bayliss, Goldstein & Turkel 83 , Laird & Giles 02.....

Erlangga, Vuik & Oosterlee '04 :

$$B_\epsilon^{-1} = \text{Multigrid approx for } A_\epsilon^{-1}$$

$\epsilon \sim k^2$ (analysis via Fourier eigenvalue analysis)

Kimn & Sarkis '13 used $\epsilon \sim k^2$ to enhance domain decomposition methods

Engquist and Ying, '11 Used $\epsilon \sim k$ to stabilise their **sweeping preconditioner**

Y. A. Erlangga, 2008.

Y. A. Erlangga, C. W. Oosterlee, and C. Vuik, 2006.

Eigenvalues of $(\Delta + k^2(a + ib))^{-1}(\Delta + k^2)$ well clustered when $a \sim 1 \sim b$.

Y. A Erlangga, C. Vuik, and C. W. Oosterlee, 2006

M. B. Van Gijzen, Y. A. Erlangga, and C. Vuik, 2007.

Y. Erlangga and R. Nabben, 2008

A. H. Sheikh, D. Lahaye, and C. Vuik, 2013.

Deflation - $\varepsilon \sim k^2$ Fourier analysis on model Dirichlet problems

S. Cools and W. Vanroose , 2013.

O. Ernst and M. Gander, 2012, $\varepsilon \sim k^2$ for multigrid convergence

Y. A. Erlangga, 2008.

Y. A. Erlangga, C. W. Oosterlee, and C. Vuik, 2006.

Eigenvalues of $(\Delta + k^2(a + ib))^{-1}(\Delta + k^2)$ well clustered when $a \sim 1 \sim b$.

Y. A Erlangga, C. Vuik, and C. W. Oosterlee, 2006

M. B. Van Gijzen, Y. A. Erlangga, and C. Vuik, 2007.

Y. Erlangga and R. Nabben, 2008

A. H. Sheikh, D. Lahaye, and C. Vuik, 2013.

Deflation - $\varepsilon \sim k^2$ Fourier analysis on model Dirichlet problems

S. Cools and W. Vanroose , 2013.

O. Ernst and M. Gander, 2012, $\varepsilon \sim k^2$ for multigrid convergence

Y. A. Erlangga, 2008.

Y. A. Erlangga, C. W. Oosterlee, and C. Vuik, 2006.

Eigenvalues of $(\Delta + k^2(a + ib))^{-1}(\Delta + k^2)$ well clustered when $a \sim 1 \sim b$.

Y. A Erlangga, C. Vuik, and C. W. Oosterlee, 2006

M. B. Van Gijzen, Y. A. Erlangga, and C. Vuik, 2007.

Y. Erlangga and R. Nabben, 2008

A. H. Sheikh, D. Lahaye, and C. Vuik, 2013.

Deflation - $\varepsilon \sim k^2$ Fourier analysis on model Dirichlet problems

S. Cools and W. Vanroose , 2013.

O. Ernst and M. Gander, 2012, $\varepsilon \sim k^2$ for multigrid convergence

Preconditioning with $\mathbf{A}_\varepsilon^{-1}$ and its approximations

$$\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{u} = \mathbf{A}_\varepsilon^{-1} \mathbf{f}.$$

“**Elman theory**” for GMRES requires:

$$\|\mathbf{A}_\varepsilon^{-1} \mathbf{A}\| \lesssim 1, \quad \text{and} \quad \text{dist}(0, \text{fov}(\mathbf{A}_\varepsilon^{-1} \mathbf{A})) \gtrsim 1 \quad \text{any norm}$$

Sufficient condition: $\|\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}\|_2 \lesssim C < 1$.

Preconditioning with $\mathbf{A}_\varepsilon^{-1}$ and its approximations

$$\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{u} = \mathbf{A}_\varepsilon^{-1} \mathbf{f}.$$

“**Elman theory**” for GMRES requires:

$$\|\mathbf{A}_\varepsilon^{-1} \mathbf{A}\| \lesssim 1, \quad \text{and} \quad \text{dist}(0, \text{fov}(\mathbf{A}_\varepsilon^{-1} \mathbf{A})) \gtrsim 1 \quad \text{any norm}$$

Sufficient condition: $\|\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}\|_2 \lesssim C < 1$.

In practice use

$$\mathbf{B}_\varepsilon^{-1} \mathbf{A} \mathbf{u} = \mathbf{B}_\varepsilon^{-1} \mathbf{f}, \quad \text{where} \quad \mathbf{B}_\varepsilon^{-1} \approx \mathbf{A}_\varepsilon^{-1}. \quad \text{Cheaper}$$

Writing

$$\mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A} = \mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon + \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon (\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}),$$

a sufficient condition is:

$$\|\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}\|_2 \quad \text{and} \quad \|\mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon\|_2 \quad \text{small},$$

i.e. $\mathbf{A}_\varepsilon^{-1}$ to be a good preconditioner for \mathbf{A}
and $\mathbf{B}_\varepsilon^{-1}$ to be a good preconditioner for \mathbf{A}_ε .

Preconditioning with $\mathbf{A}_\varepsilon^{-1}$ and its approximations

$$\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{u} = \mathbf{A}_\varepsilon^{-1} \mathbf{f}.$$

“Elman theory” for GMRES requires:

$$\|\mathbf{A}_\varepsilon^{-1} \mathbf{A}\| \lesssim 1, \quad \text{and} \quad \text{dist}(0, \text{fov}(\mathbf{A}_\varepsilon^{-1} \mathbf{A})) \gtrsim 1$$

Sufficient condition: $\|\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}\|_2 \lesssim C < 1$.

In practice use

$$\mathbf{B}_\varepsilon^{-1} \mathbf{A} \mathbf{u} = \mathbf{B}_\varepsilon^{-1} \mathbf{f},$$

$\mathbf{B}_\varepsilon^{-1}$ easily computed approximation of $\mathbf{A}_\varepsilon^{-1}$. Writing

$$\mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A} = \mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon + \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon (\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}),$$

so we require

$$\|\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}\|_2 \quad \text{and} \quad \|\mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon\|_2 \quad \text{small},$$

i.e. **$\mathbf{A}_\varepsilon^{-1}$ to be a good preconditioner for \mathbf{A}**

and **$\mathbf{B}_\varepsilon^{-1}$ to be a good preconditioner for \mathbf{A}_ε** . **Part 1**

Preconditioning with $\mathbf{A}_\varepsilon^{-1}$ and its approximations

$$\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{u} = \mathbf{A}_\varepsilon^{-1} \mathbf{f}.$$

“Elman theory” for GMRES requires:

$$\|\mathbf{A}_\varepsilon^{-1} \mathbf{A}\| \lesssim 1, \quad \text{and} \quad \text{dist}(0, \text{fov}(\mathbf{A}_\varepsilon^{-1} \mathbf{A})) \gtrsim 1$$

Sufficient condition: $\|\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}\|_2 \lesssim C < 1$.

In practice use

$$\mathbf{B}_\varepsilon^{-1} \mathbf{A} \mathbf{u} = \mathbf{B}_\varepsilon^{-1} \mathbf{f},$$

$\mathbf{B}_\varepsilon^{-1}$ easily computed approximation of $\mathbf{A}_\varepsilon^{-1}$. Writing

$$\mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A} = \mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon + \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon (\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}),$$

so we require

$$\|\mathbf{I} - \mathbf{A}_\varepsilon^{-1} \mathbf{A}\|_2 \quad \text{and} \quad \|\mathbf{I} - \mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon\|_2 \quad \text{small},$$

i.e. $\mathbf{A}_\varepsilon^{-1}$ to be a good preconditioner for \mathbf{A}

and $\mathbf{B}_\varepsilon^{-1}$ to be a good preconditioner for \mathbf{A}_ε . Part 2

Theorem 1 (with Martin Gander and Euan Spence)

For Lipschitz star-shaped domains

Quasiuniform meshes:

$$\|\mathbf{I} - \mathbf{A}_\epsilon^{-1} \mathbf{A}\| \lesssim \frac{\epsilon}{k}.$$

Shape regular meshes:

$$\|\mathbf{I} - \mathbf{D}^{1/2} \mathbf{A}_\epsilon^{-1} \mathbf{A} \mathbf{D}^{-1/2}\| \lesssim \frac{\epsilon}{k}.$$

$$\mathbf{D} = \text{diag}(\mathbf{M}^\Omega).$$

So ϵ/k sufficiently small $\implies k$ -independent GMRES convergence.

Shifted Laplacian preconditioner $\varepsilon = k$

Solving $\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}_\varepsilon^{-1} \mathbf{1}$ on unit square

	k	# GMRES
$h \sim k^{-3/2}$	10	6
	20	6
	40	6
	80	6

Shifted Laplacian preconditioner $\varepsilon = k^{3/2}$

Solving $\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}_\varepsilon^{-1} \mathbf{1}$ on unit square

	k	# GMRES
	10	8
$h \sim k^{-3/2}$	20	11
	40	14
	80	16

Shifted Laplacian preconditioner $\varepsilon = k^2$

Solving $\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}_\varepsilon^{-1} \mathbf{1}$ on unit square

	k	# GMRES
	10	13
$h \sim k^{-3/2}$	20	24
	40	48
	80	86

Proof of Theorem 1: via continuous problem

$$a_\epsilon(u, v) = \int_\Omega f\bar{v} + \int_\Gamma g\bar{v}, \quad v \in H^1(\Omega) \quad (*)$$

Theorem (Stability) Assume Ω is Lipschitz and star-shaped. Then, if ϵ/k sufficiently small,

$$\underbrace{\|\nabla u\|_{L^2(\Omega)}^2 + k^2 \|u\|_{L^2(\Omega)}^2}_{=:\|u\|_{1,k}^2} \lesssim \|f\|_{L^2(\Omega)}^2 + \|g\|_{L^2(\Gamma)}^2, \quad k \rightarrow \infty$$

“ \lesssim ” indept of k and ϵ cf. [Melenk 95, Cummings & Feng 06](#)

More absorption: $k \lesssim \epsilon \lesssim k^2$ general Lipschitz domain OK.

Key technique in proof (star-shaped case)

Rellich/Morawetz Identity

$$\mathcal{M}u = \mathbf{x} \cdot \nabla u + \alpha u, \quad \alpha = (d-1)/2$$

$$\mathcal{L}u = \Delta u + k^2 u$$

$$\begin{aligned} \|\nabla u\|_{L^2(\Omega)}^2 + k^2 \|u\|_{L^2(\Omega)}^2 &= -2 \operatorname{Re} \int_{\Omega} (\overline{\mathcal{M}u} \mathcal{L}u) \\ &\quad + \int_{\Gamma} \left[2 \operatorname{Re} \left(\overline{\mathcal{M}u} \frac{\partial u}{\partial n} \right) + (k^2 |u|^2 - |\nabla u|^2)(\mathbf{x} \cdot \mathbf{n}) \right] \end{aligned}$$

Key technique in proof (star-shaped case)

Rellich/Morawetz Identity

$$\mathcal{M}u = \mathbf{x} \cdot \nabla u + \alpha u, \quad \alpha = (d-1)/2$$

$$\mathcal{L}u = \Delta u + k^2 u$$

$$\begin{aligned} \|\nabla u\|_{L^2(\Omega)}^2 + k^2 \|u\|_{L^2(\Omega)}^2 &= -2 \operatorname{Re} \int_{\Omega} (\overline{\mathcal{M}u} \mathcal{L}u) \\ &\quad + \int_{\Gamma} \left[2 \operatorname{Re} \left(\overline{\mathcal{M}u} \frac{\partial u}{\partial n} \right) + (k^2 |u|^2 - |\nabla u|^2)(\mathbf{x} \cdot \mathbf{n}) \right] \end{aligned}$$

cf. “Green’s identity”

$$\|\nabla u\|_{L^2(\Omega)}^2 - k^2 \|u\|_{L^2(\Omega)}^2 = - \int_{\Omega} (\overline{u} \mathcal{L}u) + \int_{\Gamma} \overline{u} \frac{\partial u}{\partial n}$$

Bound for $\|\mathbf{A}_\epsilon^{-1}\|_2$

Fix $\mathbf{f} \in \mathbb{C}^N$, and consider the solution of $\mathbf{A}_\epsilon \mathbf{u} = \mathbf{f}$.

Then $u_h := \sum_j u_j \phi_j$ is FE solution of problem

$$a_\epsilon(u, v) = (f_h, v)$$

with $\|f_h\|_{L_2(\Omega)} \sim h^{-d/2} \|\mathbf{f}\|_2$.

Then

$$\begin{aligned} k h^{d/2} \|\mathbf{u}\|_2 &\sim k \|u_h\|_{L_2(\Omega)} \\ &\leq \|u_h\|_{1,k} \\ &\leq \|u - u_h\|_{1,k} + \|u\|_{1,k} \\ &\leq 2 \|u\|_{1,k} \quad \text{quasioptimality} \\ &\lesssim \|f_h\|_{L_2(\Omega)} \quad \text{stability} \end{aligned}$$

and so

$$\|\mathbf{A}_\epsilon^{-1}\| \lesssim h^{-d} k^{-1}, \quad \text{for all } \epsilon \lesssim k^2$$

PDE Theory to bound the matrix \mathbf{A}_ϵ^{-1}

Fix $\mathbf{f} \in \mathbb{C}^N$, and consider the solution of $\mathbf{A}_\epsilon \mathbf{u} = \mathbf{f}$.

Then $u_h := \sum_j u_j \phi_j$ is FE solution of problem

$$a_\epsilon(u, v) = (f_h, v)$$

with $\|f_h\|_{L_2(\Omega)} \sim h^{-d/2} \|\mathbf{f}\|_2$.

Then

$$\begin{aligned} k h^{d/2} \|\mathbf{u}\|_2 &\sim k \|u_h\|_{L_2(\Omega)} \\ &\leq \|u_h\|_{1,k} && \text{(A)} \\ &\leq \|u - u_h\|_{1,k} + \|u\|_{1,k} \\ &\lesssim 2\|u\|_{1,k} && \text{quasioptimality} \\ &\lesssim \|f_h\|_{L_2(\Omega)} && \text{stability (B)} \end{aligned}$$

and so

$$\|\mathbf{A}_\epsilon^{-1}\| \lesssim h^{-d} k^{-1}, \quad \text{for all } \epsilon \lesssim k^2$$

By H.Wu (2013) (A) \lesssim (B) when $hk^{3/2} \lesssim 1$. (without ϵ)

Corollary

$$\begin{aligned}\|\mathbf{I} - \mathbf{A}_\epsilon^{-1}\mathbf{A}\| &\leq \|\mathbf{A}_\epsilon^{-1}\| \|\mathbf{A}_\epsilon - \mathbf{A}\| \\ &\leq h^{-d}k^{-1} \|\mathbf{A}_\epsilon - \mathbf{A}\| \\ &\lesssim \frac{\epsilon}{k}.\end{aligned}$$

Corollary

$$\begin{aligned}\|\mathbf{I} - \mathbf{A}_\epsilon^{-1}\mathbf{A}\| &\leq \|\mathbf{A}_\epsilon^{-1}\| \|\mathbf{A}_\epsilon - \mathbf{A}\| \\ &\leq h^{-d} k^{-1} \|\mathbf{i}\epsilon\mathbf{M}\| \\ &\lesssim \frac{\epsilon}{k}.\end{aligned}$$

Locally refined meshes:

$$\|\mathbf{I} - \mathbf{D}^{1/2}\mathbf{A}_\epsilon^{-1}\mathbf{A}\mathbf{D}^{-1/2}\| \lesssim \frac{\epsilon}{k}.$$

Same for right preconditioning

Exterior scattering problem with refinement

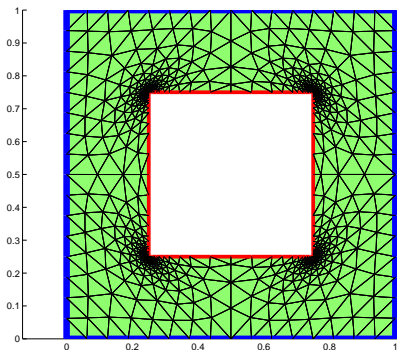
$$h \sim k^{-1},$$

Solving $\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}_\varepsilon^{-1} \mathbf{1}$ on unit square

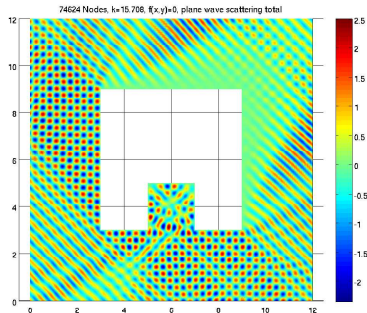
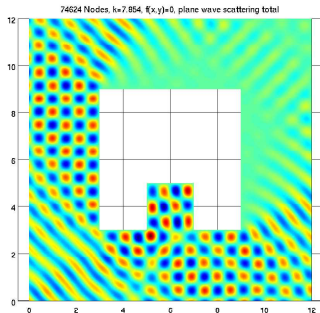
GMRES

with diagonal scaling

k	$\varepsilon = k$	$\varepsilon = k^{3/2}$
20	5	8
40	5	11
80	5	13
160	5	16



A trapping domain



k	$\epsilon = k$	$\epsilon = k^{3/2}$
$10\pi/8$	18	29
$20\pi/8$	19	41
$40\pi/8$	21	60
$80\pi/8$	22	89

Stability result fails when ϵ grows slower than k “quasimodes”

Betcke, Chandler-Wilde, IGG, Langdon, Lindner, 2010

Part 2: How to approximate $\mathbf{A}_\varepsilon^{-1}$?

Engquist & Ying (2012):

“Since the shifted Laplacian operator is elliptic, standard algorithms such as multigrid can be used for its inversion”

Domain Decomposition:

Many non-overlapping methods ($\varepsilon = 0$)

Benamou & Després 1997.....Gander, Magoules, Nataf, Halpern, Dolean.....

General issue: coarse grids, scalability?

Conjecture If ε large enough, classical overlapping DD methods with coarse grids will work (giving scalable solvers).

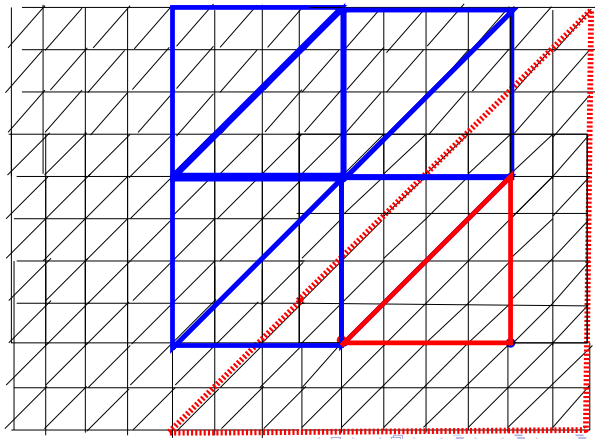
However Classical analysis for $\varepsilon = 0$ (Cai & Widlund, 1992) leads to coarse grid size $H \sim k^{-2}$

Classical additive Schwarz

To solve a problem on a fine grid FE space \mathcal{S}_h

- **Coarse space** \mathcal{S}_H (here linear FE) **on a coarse grid**
- **Subdomain spaces** \mathcal{S}_i **on subdomains** Ω_i , overlap δ

$H_{sub} \sim H$ in this case



Approximation of C^{-1} :

$$\sum_i \mathbf{R}_i^T \mathbf{C}_i^{-1} \mathbf{R}_i + \mathbf{R}_H^T \mathbf{C}_H^{-1} \mathbf{R}_H$$

\mathbf{R}_i = restriction to S_i ,

$$\mathbf{C}_i = \mathbf{R}_i \mathbf{C} \mathbf{R}_i^T$$

Dirichlet BCs

\mathbf{R}_H = restriction to S_H

$$\mathbf{C}_H = \mathbf{R}_H \mathbf{C} \mathbf{R}_H^T$$

Apply to A_ε to get B_ε^{-1}

Coercivity Lemma There exists $|\Theta| = 1$, with

$$\operatorname{Im} [\Theta a_\varepsilon(v, v)] \gtrsim \frac{\varepsilon}{k^2} \|v\|_{1,k}^2. \quad (\star)$$

Projections onto subspaces:

$$a_\varepsilon(Q_i v_h, w_i) = a_\varepsilon(v_h, w_i), \quad v_h \in \mathcal{S}_h, \quad w_i \in \mathcal{S}_i.$$

Coercivity Lemma There exists $|\Theta| = 1$, with

$$\operatorname{Im} [\Theta a_\varepsilon(v, v)] \gtrsim \frac{\varepsilon}{k^2} \underbrace{\|v\|_{1,k}^2}_{\|\nabla u\|_\Omega^2 + k^2 \|u\|_\Omega^2} . \quad (\star)$$

Projections onto subspaces:

$$a_\varepsilon(Q_H v_h, w_H) = a_\varepsilon(v_h, w_H), \quad v_h \in \mathcal{S}_h, \quad w_H \in \mathcal{S}_H .$$

Guaranteed well-defined by (\star) .

Analysis of $\mathbf{B}_\varepsilon^{-1} \mathbf{A}_\varepsilon$ equivalent to analysing

$$Q := \sum_i Q_i + Q_H \quad \text{operator in FE space } \mathcal{S}_h .$$

Convergence results

Assume $\varepsilon \sim k^2$ and overlap $\delta \sim H$.

Theorem IGG, Spence, Vainikko, 2014

For all coarse grid sizes H ,

$$\|Q\|_{1,k} \lesssim 1.$$

Theorem IGG, Spence, Vainikko, 2014

There exists $C > 0$ so that

$$\text{dist}(0, \text{fov}(Q)) \gtrsim 1,$$

provided $kH < C$ (no pollution!).

Hence k -independent GMRES convergence.

Convergence results

Assume $\varepsilon \sim k^2$. and overlap δ .

Theorem IGG, E. Spence, E. Vainikko, 2014

For all coarse grid sizes H ,

$$\|Q\|_{1,k} \lesssim 1.$$

Theorem IGG, E. Spence, E. Vainikko, 2014

There exists $C > 0$ so that

$$\text{dist}(0, \text{fov}(Q)) \gtrsim \left(1 + \frac{H}{\delta}\right)^{-2},$$

provided $kH < C$ (no pollution!).

Numerical experiments: unit square

$$\varepsilon = k^2 \quad h \sim k^{-3/2}, \quad H \sim k^{-1} \quad \delta \sim H$$

Classical additive Schwarz - see later for better!

k	#GMRES
20	14
40	15
60	15
80	17

$$(v_h, Qv_h)_{1,k} = \sum_j (v_h, Q_j v_h)_{1,k} + (v_h, Q_H v_h)_{1,k}$$

$$(v_h, Qv_h)_{1,k} = \sum_j (v_h, Q_j v_h)_{1,k} + (v_h, Q_H v_h)_{1,k}$$

$$(v_h, Q_H v_h)_{1,k} = \|Q_H v_h\|_{1,k}^2 + ((I - Q_H)v_h, Q_H v_h)_{1,k}$$

$$(v_h, Qv_h)_{1,k} = \sum_j (v_h, Q_j v_h)_{1,k} + (v_h, Q_H v_h)_{1,k}$$

$$(v_h, Q_H v_h)_{1,k} = \|Q_H v_h\|_{1,k}^2 + ((I - Q_H)v_h, Q_H v_h)_{1,k}$$

$$((I - Q_H)v_h, Q_H v_h)_{1,k} = \underbrace{a_\varepsilon((I - Q_H)v_h, Q_H v_h)}_{=0, \text{ Galerkin orthogonality}} + L_2 \text{ terms}$$

Bound L^2 terms using duality, regularity \implies condition on kH

$$(v_h, Qv_h)_{1,k} = \sum_j (v_h, Q_j v_h)_{1,k} + (v_h, Q_H v_h)_{1,k}$$

$$(v_h, Q_H v_h)_{1,k} = \|Q_H v_h\|_{1,k}^2 + ((I - Q_H)v_h, Q_H v_h)_{1,k}$$

$$((I - Q_H)v_h, Q_H v_h)_{1,k} = \underbrace{a_\varepsilon((I - Q_H)v_h, Q_H v_h)}_{=0, \text{ Galerkin orthogonality}} + L_2 \text{ terms}$$

Bound L^2 terms using duality, regularity \implies condition on kH

$$(v_h, Qv_h)_{1,k} = \sum_j (v_h, Q_j v_h)_{1,k} + (v_h, Q_H v_h)_{1,k}$$

$$(v_h, Q_H v_h)_{1,k} = \|Q_H v_h\|_{1,k}^2 + ((I - Q_H)v_h, Q_H v_h)_{1,k}$$

$$((I - Q_H)v_h, Q_H v_h)_{1,k} = \underbrace{a_\varepsilon((I - Q_H)v_h, Q_H v_h)}_{=0, \text{ Galerkin orthogonality}} + L_2 \text{ terms}$$

Bound L^2 terms using duality, regularity \implies condition on kH

$$\begin{aligned} |(v_h, Qv_h)_{1,k}| &\gtrsim \sum_j \|Q_j v_h\|_{1,k}^2 + \|Q_H v_h\|_{1,k}^2 \\ &\gtrsim \|v_h\|_{1,k}^2 \end{aligned}$$

$$(v_h, Qv_h)_{1,k} = \sum_j (v_h, Q_j v_h)_{1,k} + (v_h, Q_H v_h)_{1,k}$$

$$(v_h, Q_H v_h)_{1,k} = \|Q_H v_h\|_{1,k}^2 + ((I - Q_H)v_h, Q_H v_h)_{1,k}$$

$$((I - Q_H)v_h, Q_H v_h)_{1,k} = \underbrace{a_\varepsilon((I - Q_H)v_h, Q_H v_h)}_{=0} + L_2 \text{ terms}$$

Galerkin Orthogonality, duality, regularity \implies condition on kH

$$\begin{aligned} \operatorname{Re}(v_h, Qv_h)_{1,k} &\gtrsim \sum_j \|Q_j v_h\|_{1,k}^2 + \|Q_H v_h\|_{1,k}^2 \\ &\gtrsim \left(\frac{\varepsilon}{k^2}\right)^2 \|v_h\|_{1,k}^2 \quad \text{when} \quad Hk \lesssim (\varepsilon/k^2)^2 \end{aligned}$$

Useful Variants

- **Hybrid**: Multiplicative between coarse and local solves
Mandel and Brezina: 1994,96

- **RAS**: only add up once on regions of overlap
Cai & Sarkis, 1999, Kimn & Sarkis 2010

B_ε^{-1} as preconditioner for A_ε $\varepsilon = k^2$

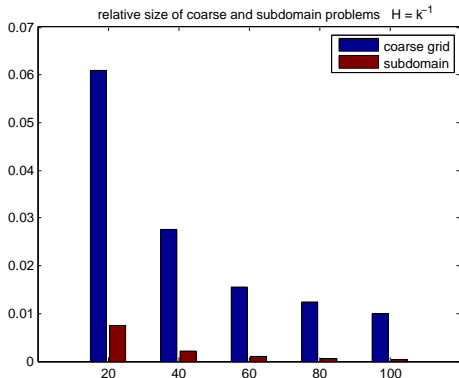
$h \sim k^{-3/2}$, $n \sim k^3$, Hybrid RAS,

$$Hk \sim 1$$

Relative **Coarse** and
subdomain problem size

Scale = 0.07

k	#GMRES
20	8
40	8
60	8
80	8
100	8



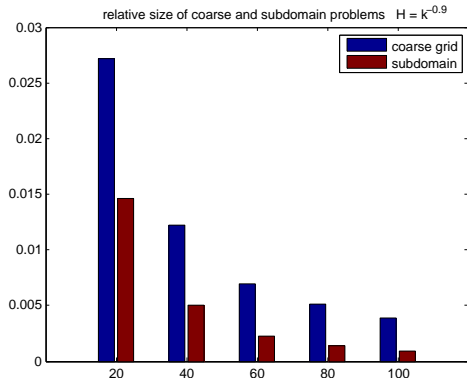
B_ε^{-1} as preconditioner for A_ε $\varepsilon = k^2$

$h \sim k^{-3/2}$, $n \sim k^3$, Hybrid RAS,

$$Hk \sim k^{0.1}$$

Scale = 0.03

k	#GMRES
20	9
40	10
60	10
80	10
100	10



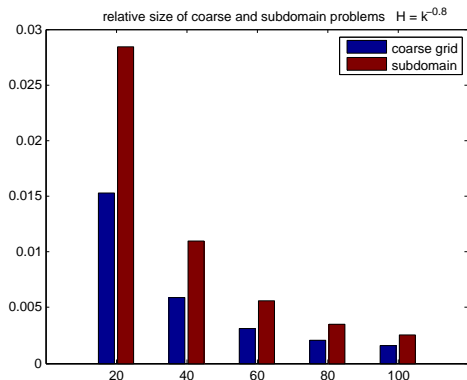
B_ε^{-1} as preconditioner for A_ε $\varepsilon = k^2$

$h \sim k^{-3/2}$, $n \sim k^3$, Hybrid RAS,

$$Hk \sim k^{0.2}$$

Scale = 0.03

k	#GMRES
20	10
40	10
60	11
80	11
100	11



Solving the real problem: B_k^{-1} as preconditioner for A

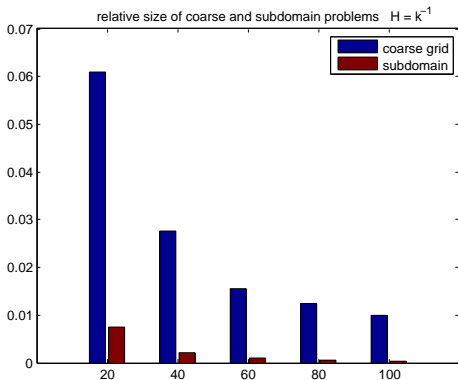
$h \sim k^{-3/2}$, $n \sim k^3$, Hybrid RAS,

$\varepsilon \sim k$ **empirically best choice** (cf. multigrid)

$Hk \sim 1$

k	# GMRES
20	12
40	15
60	20
80	26
100	33

Scale = 0.07



Solving the real problem: B_k^{-1} as preconditioner for A

$h \sim k^{-3/2}$, $n \sim k^3$, Hybrid RAS,

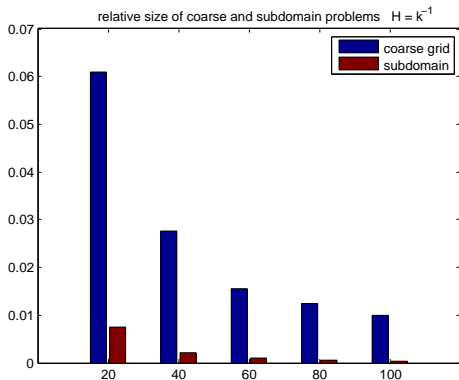
$\varepsilon \sim k$ **empirically best choice** (cf. multigrid)

$Hk \sim 1$

No coarse grid

Scale = 0.07

k	# GMRES
20	58
40	181
60	316
80	434
100	576



Problem becomes “less elliptic” as $\varepsilon \ll k^2$.

local Dirichlet → **local impedance (or PML)** Toselli , 1999

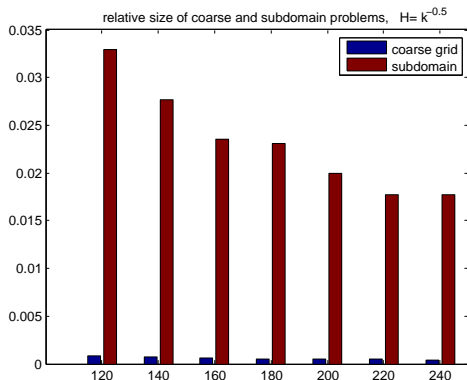
Solving the real problem: B_k^{-1} as preconditioner for A

20 grid points per wavelength, $h \sim k^{-1}$, $n \sim k^2$,

Impedance subdomain problems $Hk \sim k^{0.5}$

Scale = 0.035

k	#GMRES
120	51
140	56
160	59
180	57
200	61
220	64
240	65



#GMRES $\sim \log k$

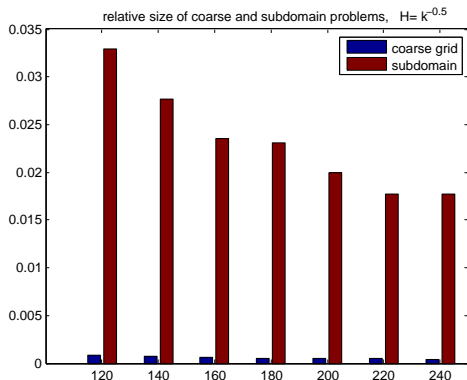
Solving the real problem: B_k^{-1} as preconditioner for A

20 grid points per wavelength, $h \sim k^{-1}$, $n \sim k^2$,

Dirichlet subdomain problems $Hk \sim k^{0.5}$

Scale = 0.035

k	#GMRES
120	487
140	595
160	> 600
180	> 600
200	
220	
240	



Summary

- k and ϵ explicit analysis allows **rigorous explanation** of some empirical observations and formulation of new methods.
- When $\epsilon \in [0, k]$, \mathbf{A}_ϵ^{-1} is optimal preconditioner for \mathbf{A}
- When $\epsilon \sim k^2$, \mathbf{B}_ϵ^{-1} is “optimal” for \mathbf{A}_ϵ ($H \sim k^{-1}$)
- Analysis is for classical DP method - introduce more wavelike components
- When preconditioning \mathbf{A} with \mathbf{B}_ϵ^{-1} , **empirical best choice is**
 $\epsilon \sim k$
- **New framework** for DD analysis for larger k .
- Open questions in analysis when $\frac{\epsilon}{k^2} \ll 1$