High Frequency Solution Behaviour in Wave Scattering Problems

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Context

My talks apply (particularly) to **acoustic waves** — my background is in **outdoor noise propagation** and **noise barriers**.

My talks concern new numerical-asymptotic methods for high frequency wave scattering, that combine numerical analysis ideas and tools with high frequency asymptotics, see



C-W, Graham, Langdon, Spence *Acta Numerica* 21 (2012), 89–305. This talk is the **HF asymptotics** – **numerical methods** are talk two!

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Motivation. Want to factor unknown oscillatory functions into sums of products of **known oscillatory functions** and **unknown non-oscillatory functions**.

Overview

- 1. Wave Equation and Helmholtz Equation
- 2. **Basic Concept** of high frequency asymptotic approximations of **GO** and **GTD**
- 3. **Reflection** canonical problems and high frequency GO approximations
- 4. **Diffraction** canonical problems and high frequency GTD approximations
- 5. The HF Kirchhoff Approximation
- 6. Preparing for NA: Quantifying Non-Oscillatorariness!

1. WAVE EQUATION AND HELMHOLTZ EQUATION

The Wave Equation and Helmholtz Equation

$$\Delta U = \frac{1}{c^2} \frac{\partial^2 U}{\partial t^2} \quad \left(\Delta = \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial x_3^2}\right).$$
If time-dependence is time harmonic, i.e., where $x = (x_1, x_2, x_3)$,
 $U(x, t) = A(x) \cos(\phi(x) - \omega t)$,
for some $\omega = 2\pi f > 0$, with $f =$ frequency, then
 $U(x, t) = \Re \left(u(x)e^{-i\omega t}\right)$
where $u(x) = A(x) \exp(i\phi(x))$ satisfies the Helmholtz equation

$$\Delta u + \mathbf{k}^2 u = 0,$$

with $k = \omega/c$ the wavenumber.

If time-dependence is **time harmonic** then

$$U(x,t) = \Re \left(u(x) \mathrm{e}^{-\mathrm{i}\omega t} \right)$$

for some $\omega = 2\pi f > 0$, with f = frequency, where u satisfies the Helmholtz equation

$$\Delta u + \mathbf{k}^2 u = 0,$$

with $k = \omega/c$ the wavenumber. E.g. if

$$u(x) = \mathrm{e}^{\mathrm{i}kx \cdot d},$$

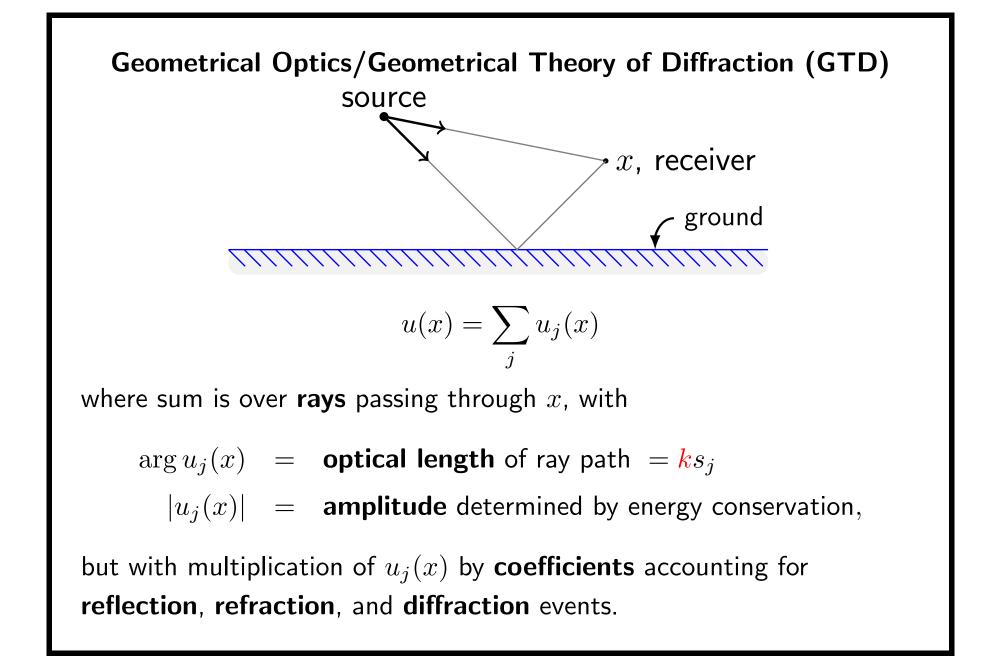
for some **unit vector** d, then

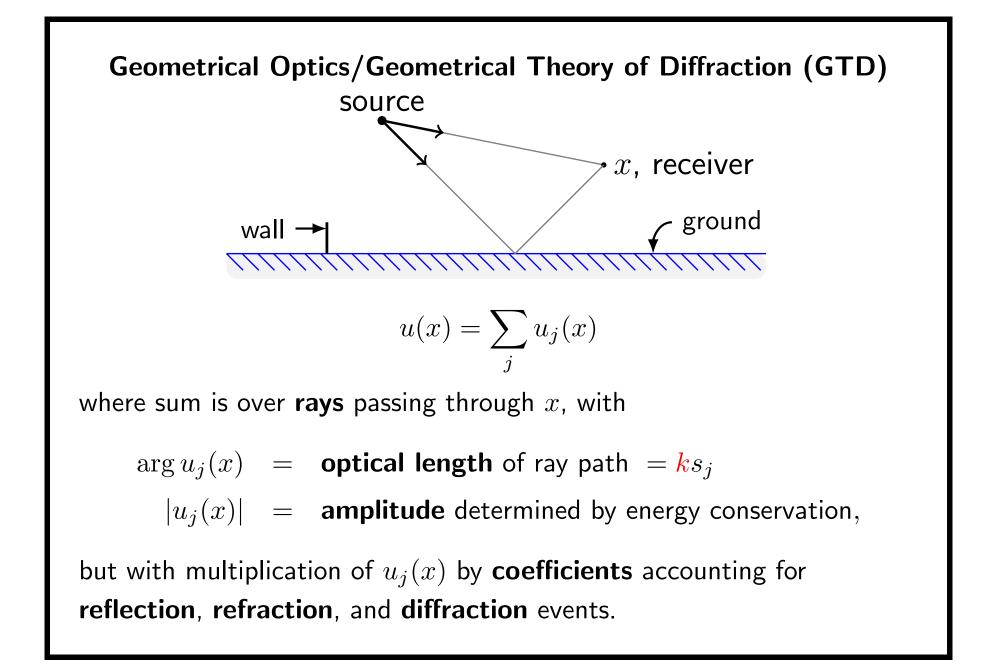
$$U(x,t) = \Re \left(u(x) \mathrm{e}^{-\mathrm{i}\omega t} \right) = \cos(\mathbf{k}x \cdot d - \omega t)$$

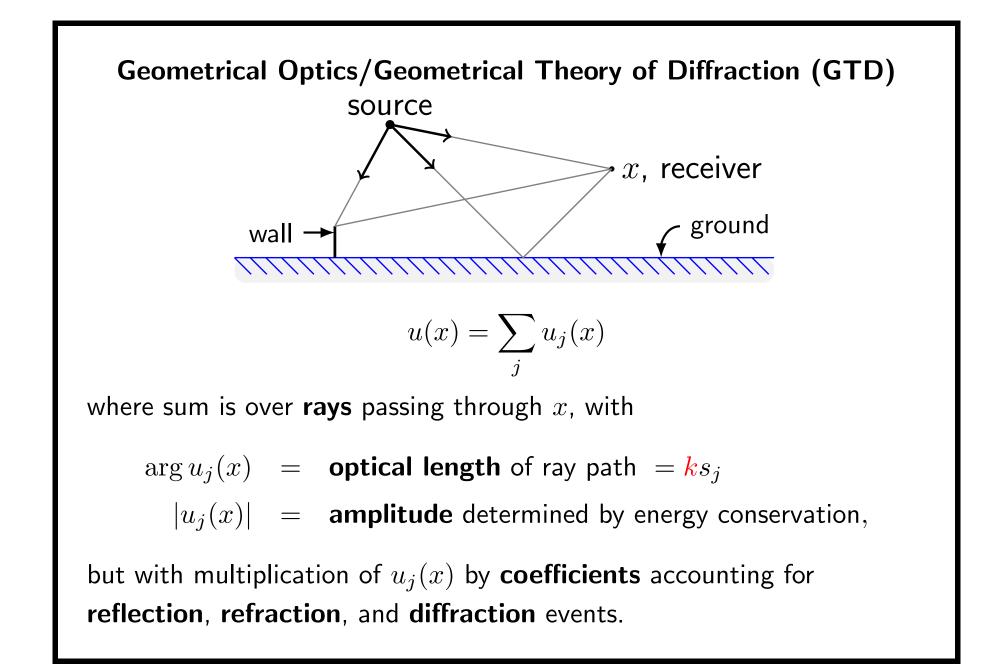
is a **plane wave** travelling in direction d with **wavelength**

$$\lambda = \frac{2\pi}{k} = \frac{c}{f}$$

2. GO AND GTD: THE BASIC CONCEPT







Geometrical Optics/Geometrical Theory of Diffraction (GTD)

$$u(x) = \sum_{j} u_j(x)$$

where sum is over **rays** passing through x, with

$$\arg u_j(x) =$$
optical length of ray path $= ks_j$
 $|u_j(x)| =$ **amplitude** determined by energy conservation,

but with multiplication of $u_j(x)$ by coefficients accounting for reflection, refraction, and diffraction events.

The concept/theory/idea of GO/GTD is that at **high frequency** these interaction events are **local** and so these coefficients can be computed by solving **canonical problems**, with simple geometries and incident fields.

3. REFLECTION: CANONICAL PROBLEMS AND HIGH FREQUENCY GO APPROXIMATIONS^a

^a "Uber die Ausbreitung der Wellen in der drahtlosen Telegraphie", A. Sonmmerfeld, *Ann. Phys.* (1909)

A Canonical Reflection Problem $\Delta u + k^2 u = 0$ $\mathcal{M}_{u^{\text{inc}}(x) = e^{\mathbf{i}\mathbf{k}x \cdot d}}$ $\mathcal{N}^{\text{ref}}(x) = R e^{\mathbf{i}\mathbf{k}x \cdot d'}$ x_2 θ_0 $\cdot \frac{\partial u}{\partial x_2} + \mathbf{i} \frac{\mathbf{k}}{\partial u} = 0$ x_1 $d = (d_1, d_2)$ is direction of **incident** plane wave, $d' = (d_1, -d_2)$ is direction of **reflected** plane wave, β is the admittance in the impedance boundary condition, θ_0 is the **angle of incidence**, R is the **reflection coefficient**.

A Canonical Reflection Problem

$$\Delta u + k^2 u = 0$$

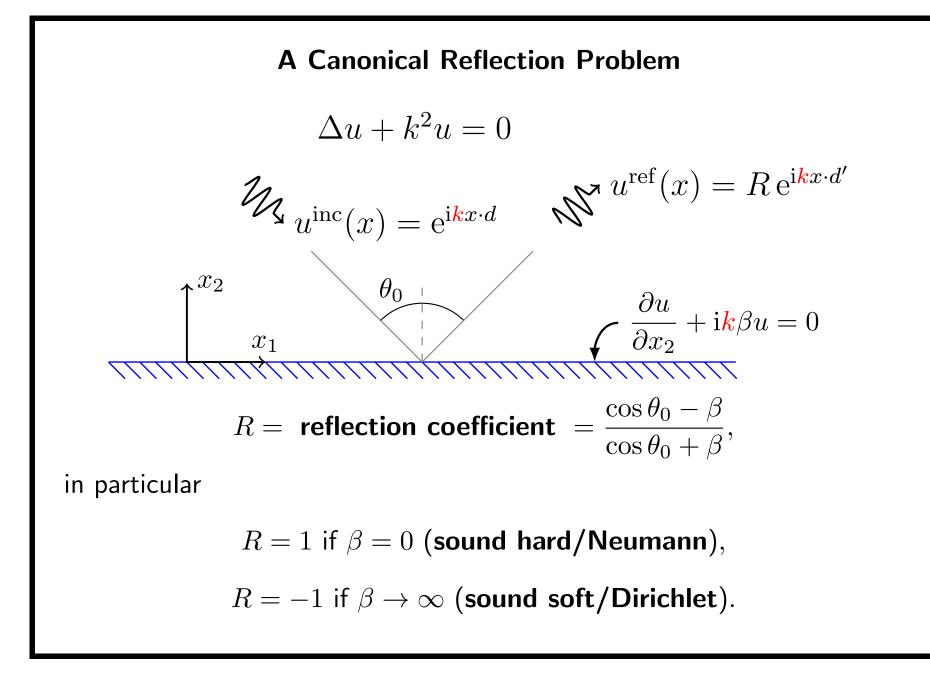
$$M u^{\text{ref}}(x) = R e^{ikx \cdot d'}$$

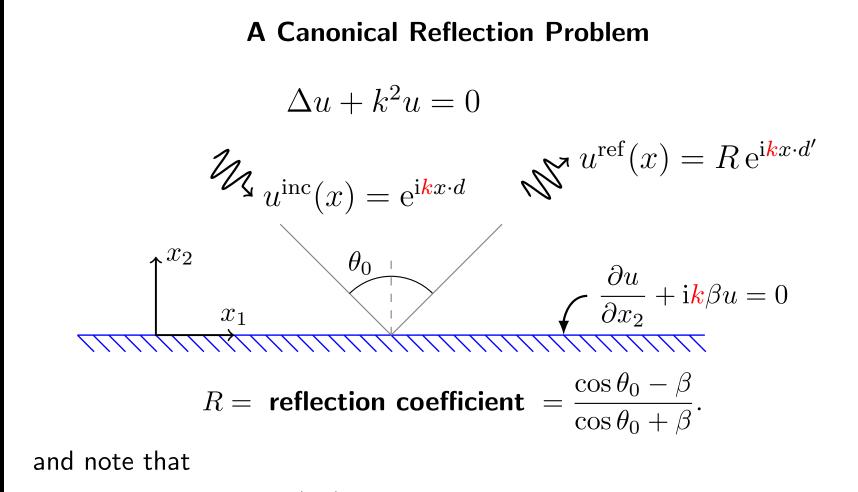
$$u^{\text{inc}}(x) = e^{ikx \cdot d}$$

$$\int \frac{\partial u}{\partial x_2} + ik\beta u = 0$$
The total field is

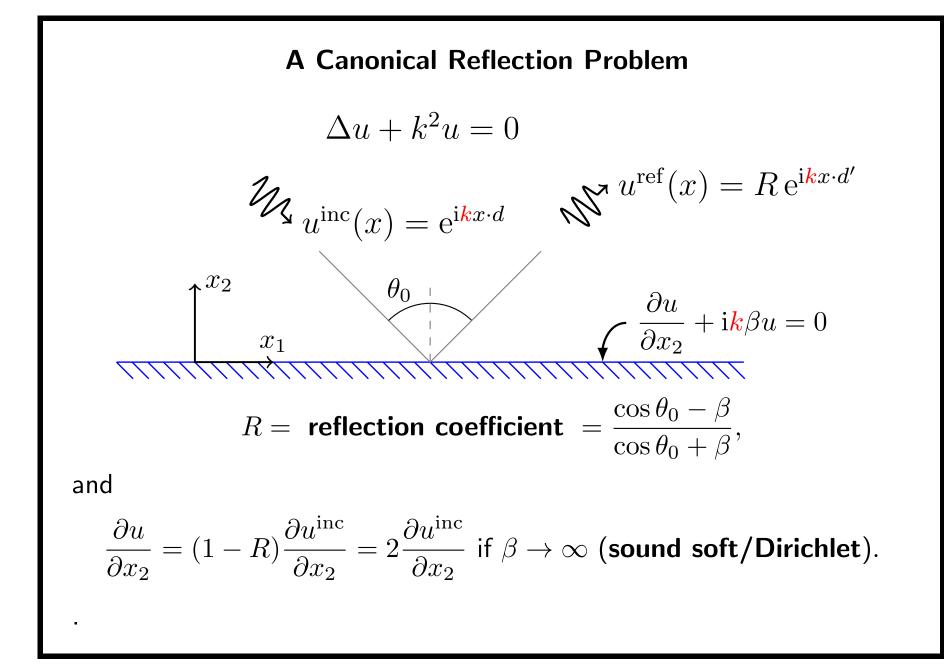
$$u(x) = u^{\text{inc}}(x) + u^{\text{ref}}(x) = e^{ikx \cdot d} + R e^{ikx \cdot d'}$$
where

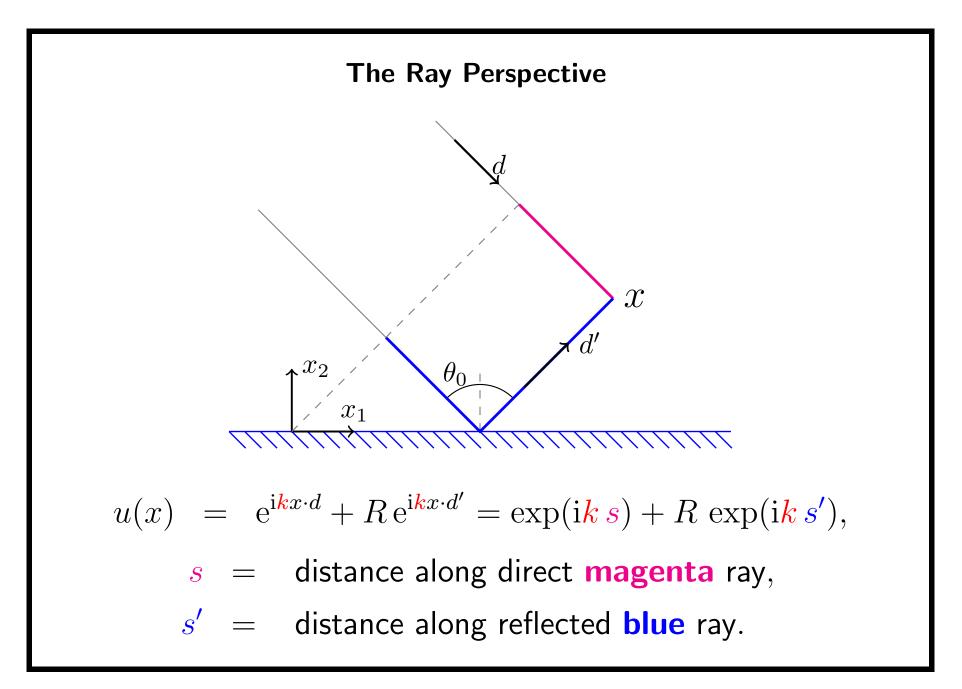
$$R = \text{ reflection coefficient } = \frac{\cos \theta_0 - \beta}{\cos \theta_0 + \beta}.$$



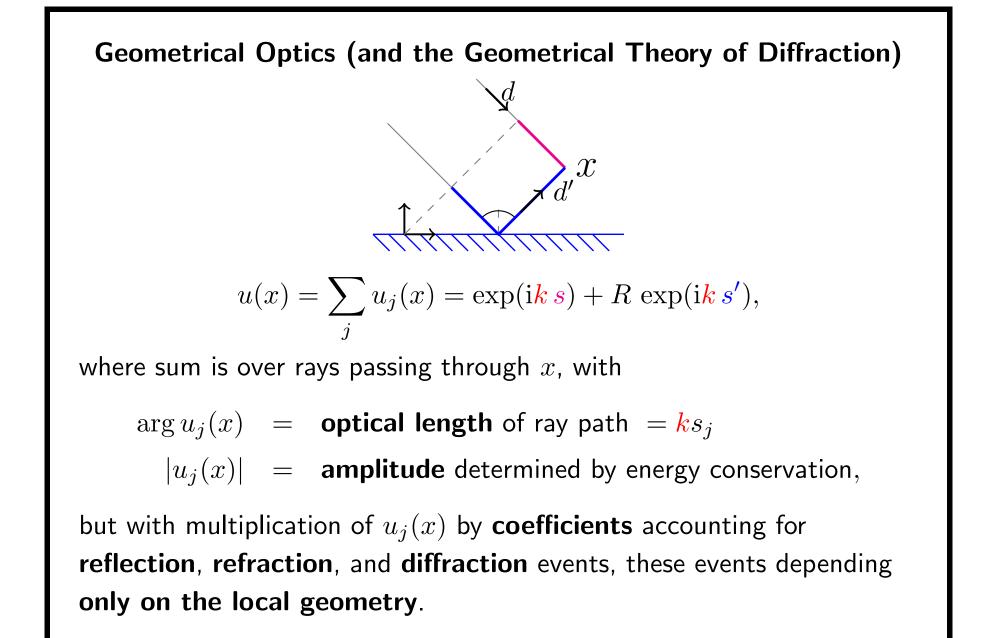


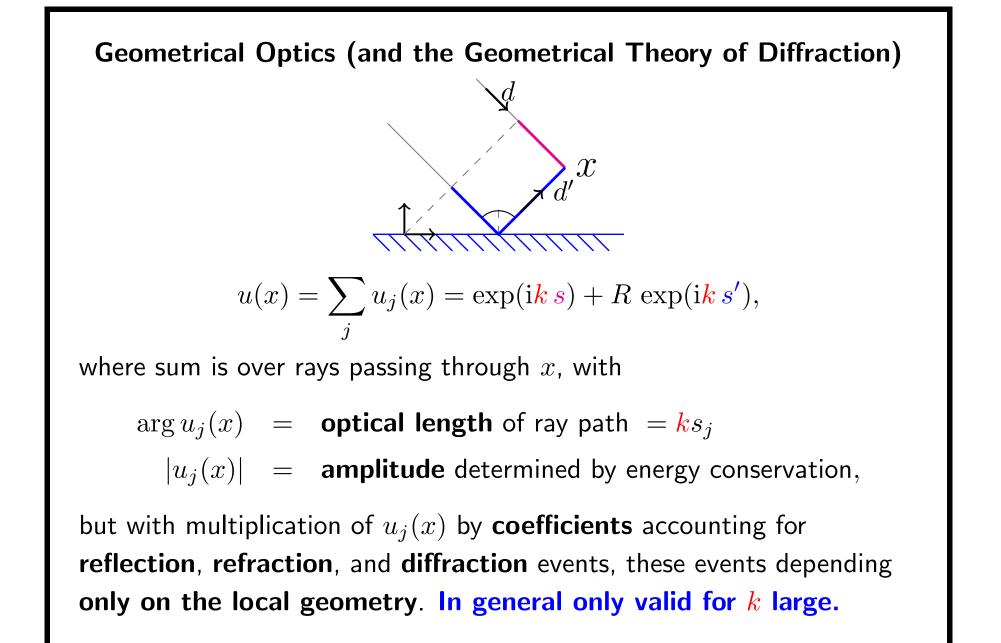
$$|R| \le 1 \quad \Leftrightarrow \quad \Re \beta \ge 0.$$

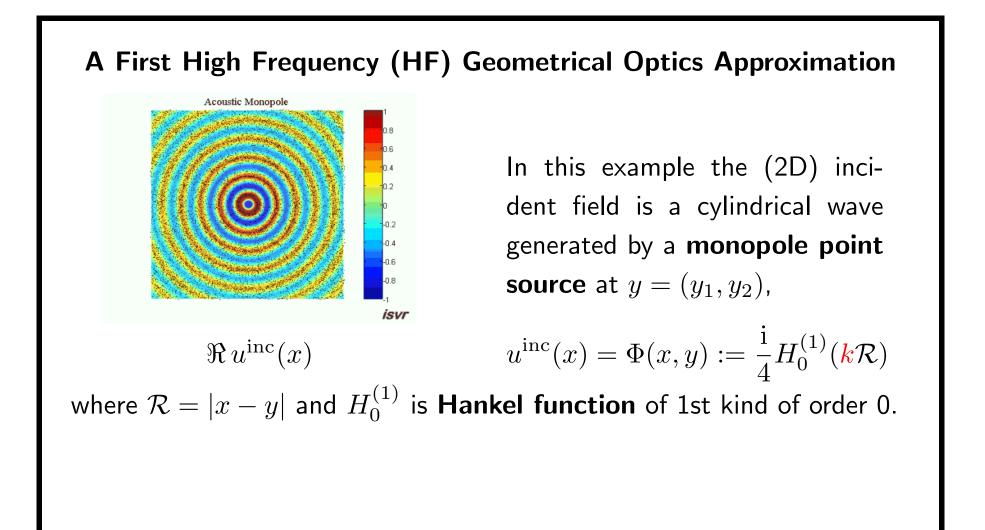


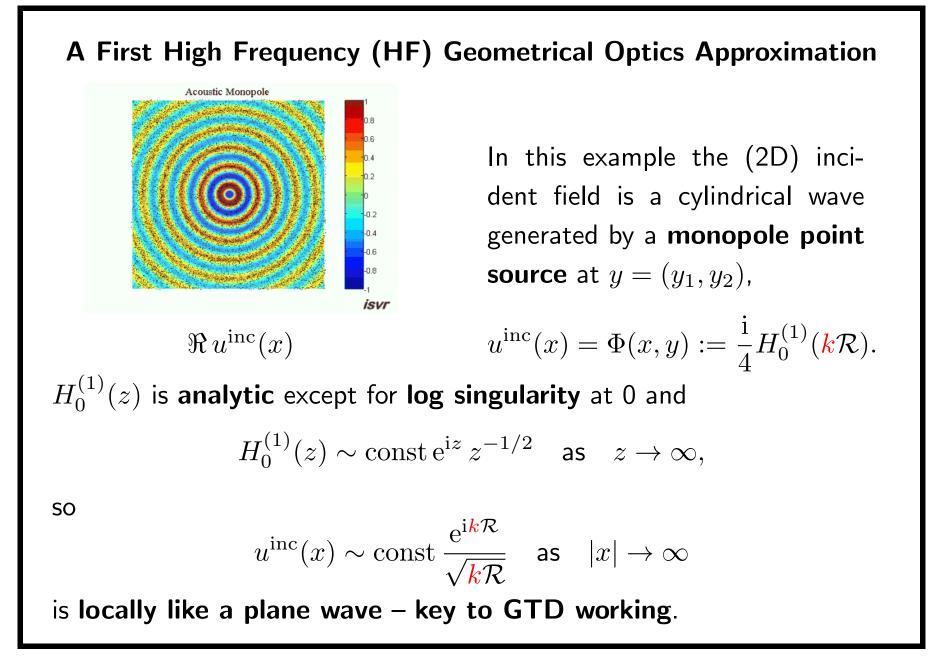


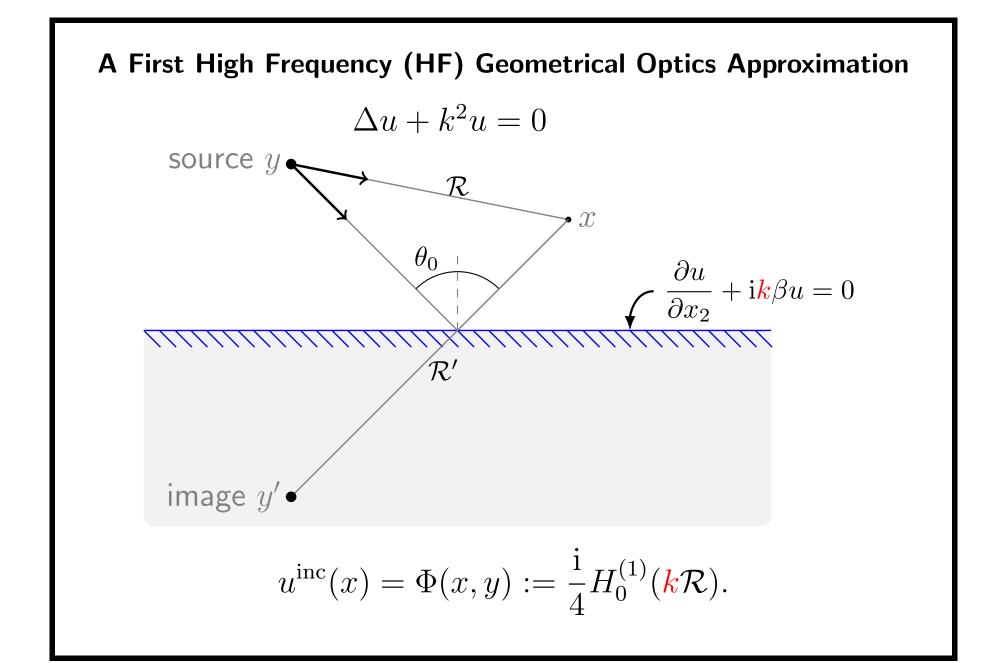
Geometrical Optics (and the Geometrical Theory of Diffraction) $u(x) = \sum_{j} u_j(x)$ where sum is over rays passing through x, with $\arg u_i(x) =$ **optical length** of ray path $= ks_j$ $|u_i(x)| =$ amplitude determined by energy conservation, but with multiplication of $u_i(x)$ by **coefficients** accounting for **reflection**, **refraction**, and **diffraction** events, these events depending only on the local geometry.

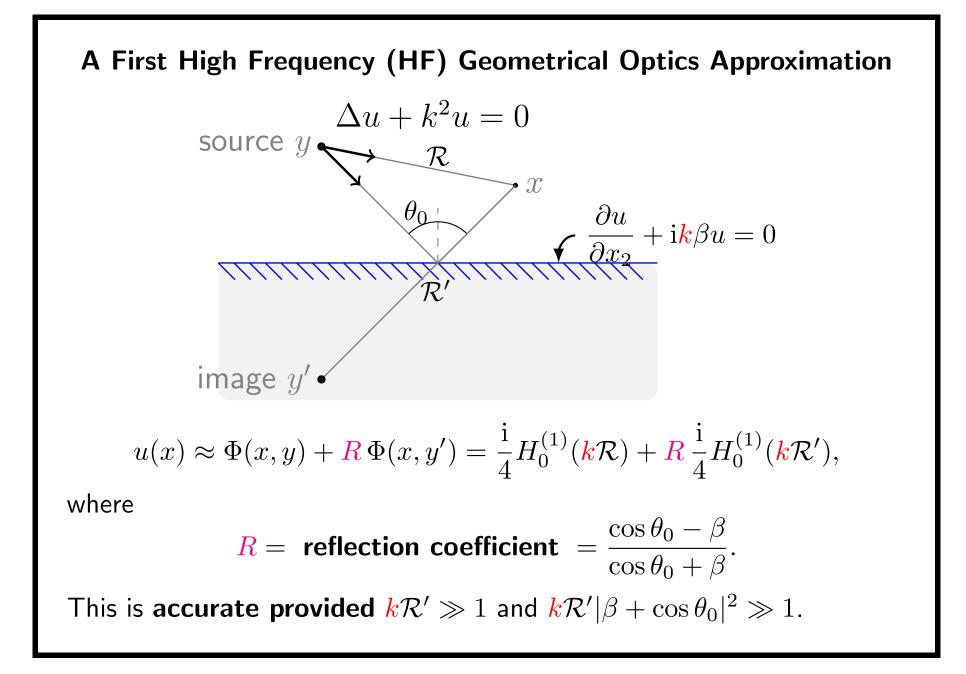


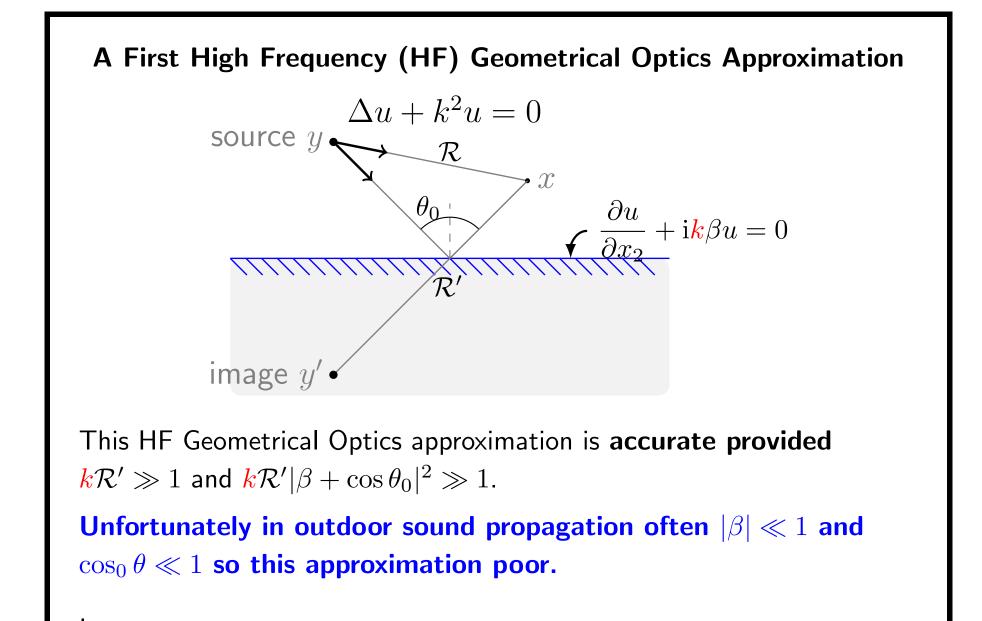


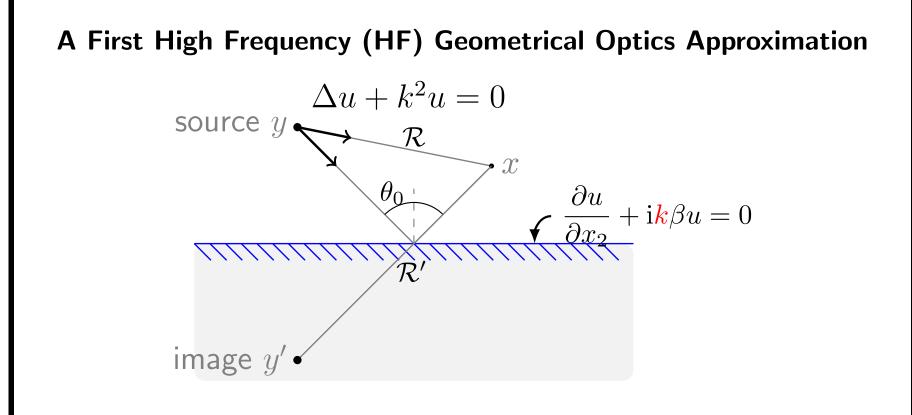




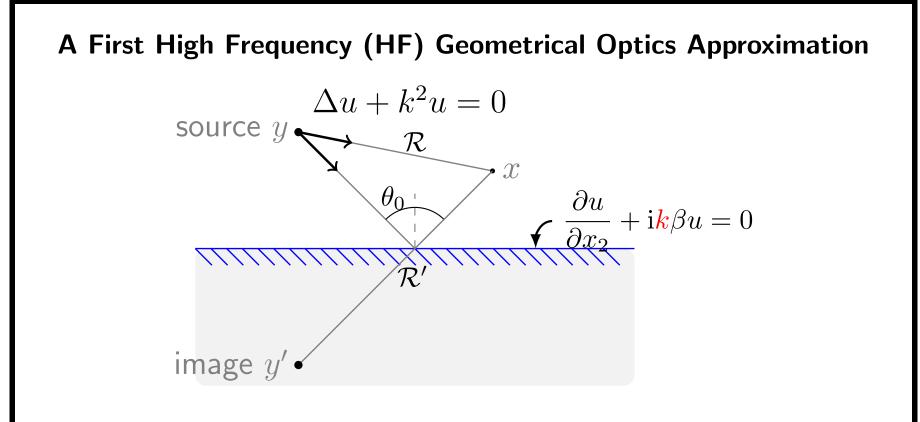






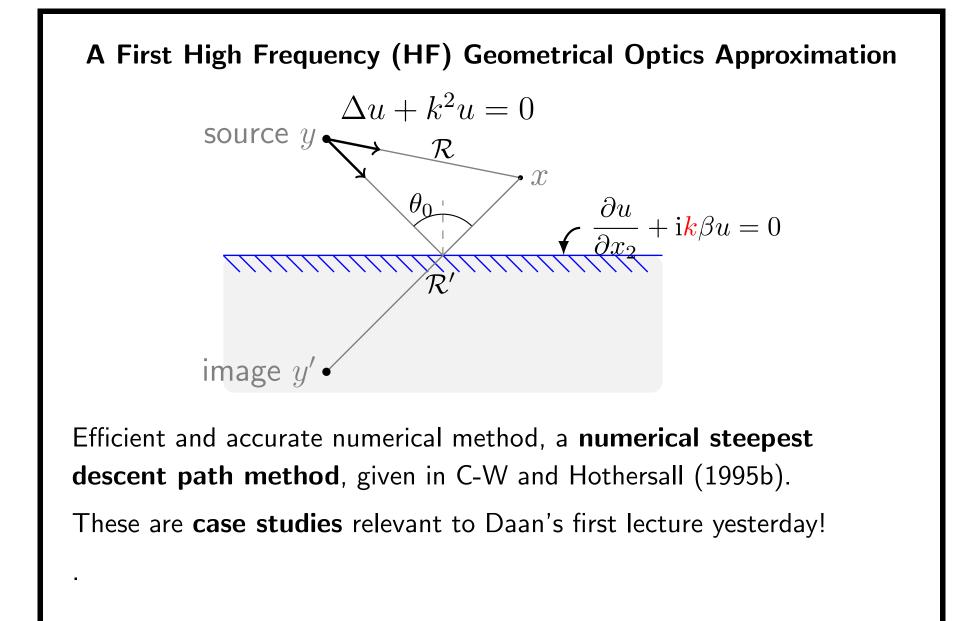


Exact solution as highly oscillatory Fourier integral and its uniform asymptotic expansion for $k\mathcal{R}' \gg 1$ via a steepest descent path method modified for pole near saddle point are given in C-W and Hothersall (1995a).



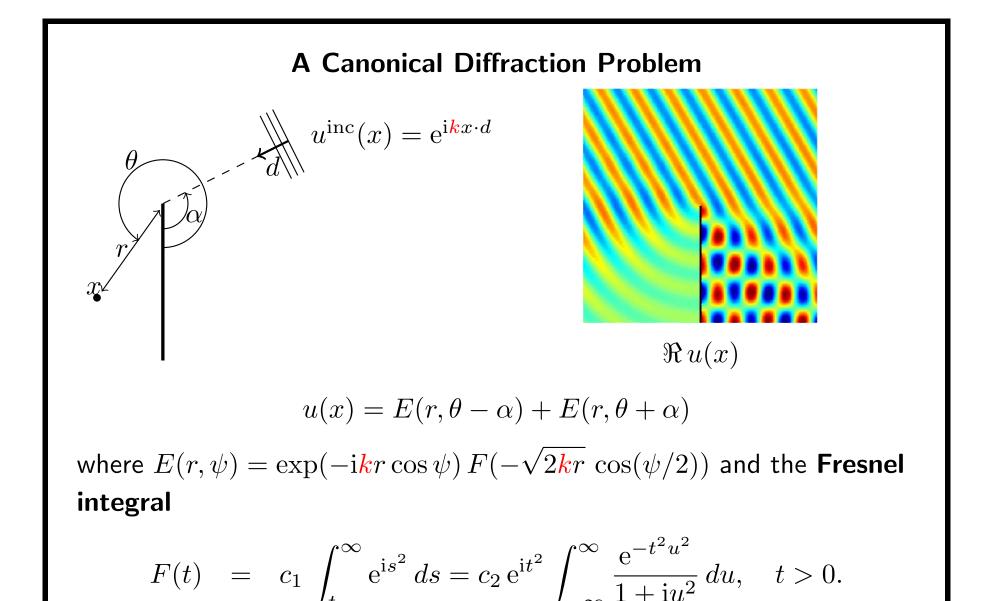
Exact solution and its **uniform asymptotic expansion** for $k\mathcal{R}' \gg 1$ via a **steepest descent path method modified for pole near saddle point** are given in C-W and Hothersall (1995a).^a

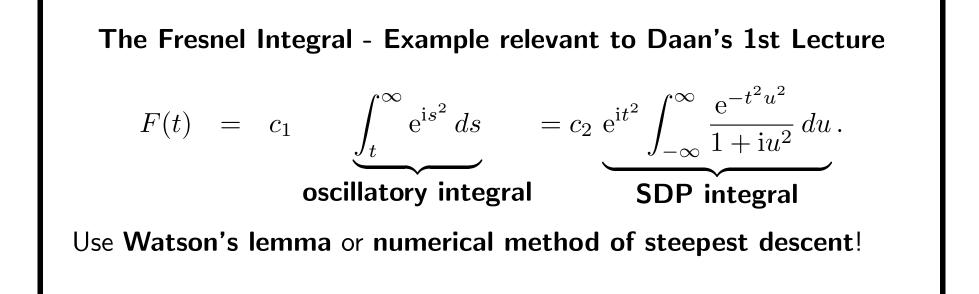
^aExtending "Die Sattelpunktsmethode in der Umgebung eines Pols. Mit Anwendungen auf die Wellenoptik und Akustik", H. Ott, *Annalen Physik*, (1943)!



4. DIFFRACTION: CANONICAL PROBLEMS AND HIGH FREQUENCY GTD APPROXIMATIONS^a

^a "Goemetrical theory of diffraction", J.B. Keller, *JOSA* (1962), "Mathematische Theorie der Diffraction", A. Sommerfeld, *Math. Ann.*, (1896), "The Computation of Conical Diffraction Coefficients in High-Frequency Acoustic Wave Scattering", B.D. Bonner, I.G. Graham, and V.P. Smyshlyaev, *SINUM* (2005)

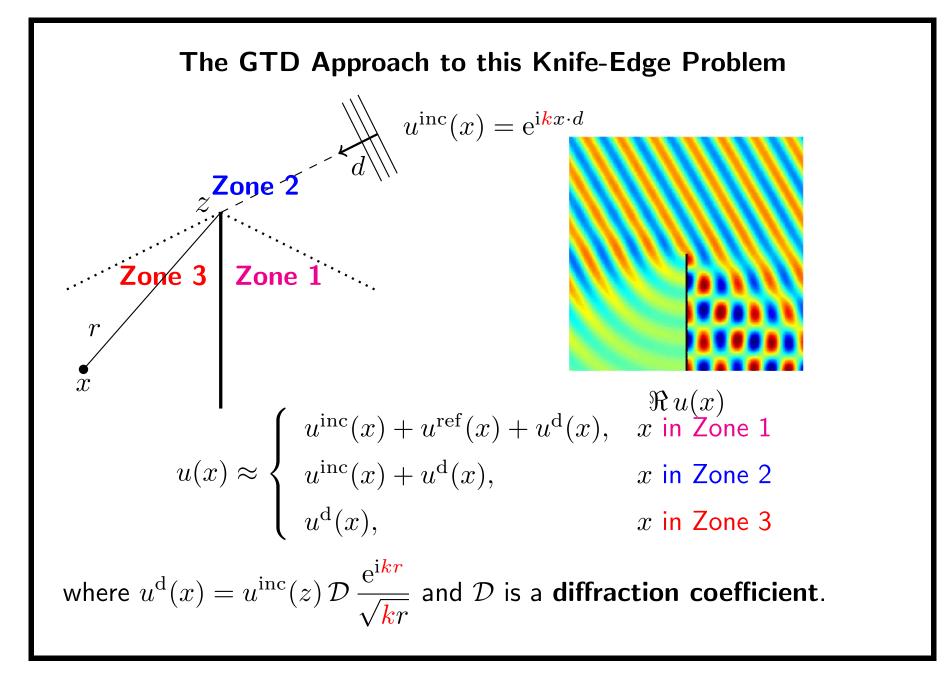




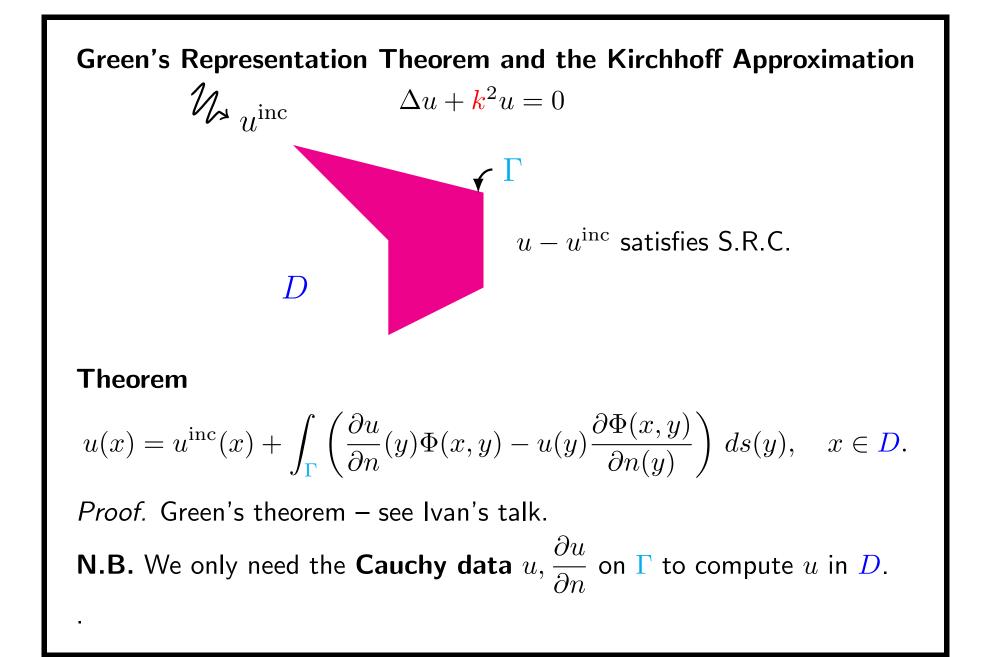
The Fresnel Integral - Example relevant to Daan's 1st Lecture $F(t) = c_1 \qquad \int_t^{\infty} e^{is^2} ds = c_2 e^{it^2} \int_{-\infty}^{\infty} \frac{e^{-t^2 u^2}}{1 + iu^2} du.$ oscillatory integral **SDP** integral Use Watson's lemma or numerical method of steepest descent! Alternatively, based on contour integral arguments dating back to Turing (1945), Alazah, C-W, La Porte, Numer Math (2014) propose the modified truncated midpoint rule $F(t) \approx F_N(t) := \frac{1}{2} + \frac{i}{2} \tan\left(\pi t e^{i\pi/4} / h_N\right) + \frac{t}{\pi} e^{i(t^2 + \pi/4)} h_N \sum_{k=1}^N \frac{e^{-s_k^2}}{t^2 + is_k^2}$ where $s_k = (k - 1/2) h_N$ and $h_N = \sqrt{\pi/(N + 1/2)}$, and show $\frac{|F'(t) - F_N(t)|}{|F(t)|} < 11 \,\mathrm{e}^{-\pi N}, \quad t \in \mathbb{R}.$

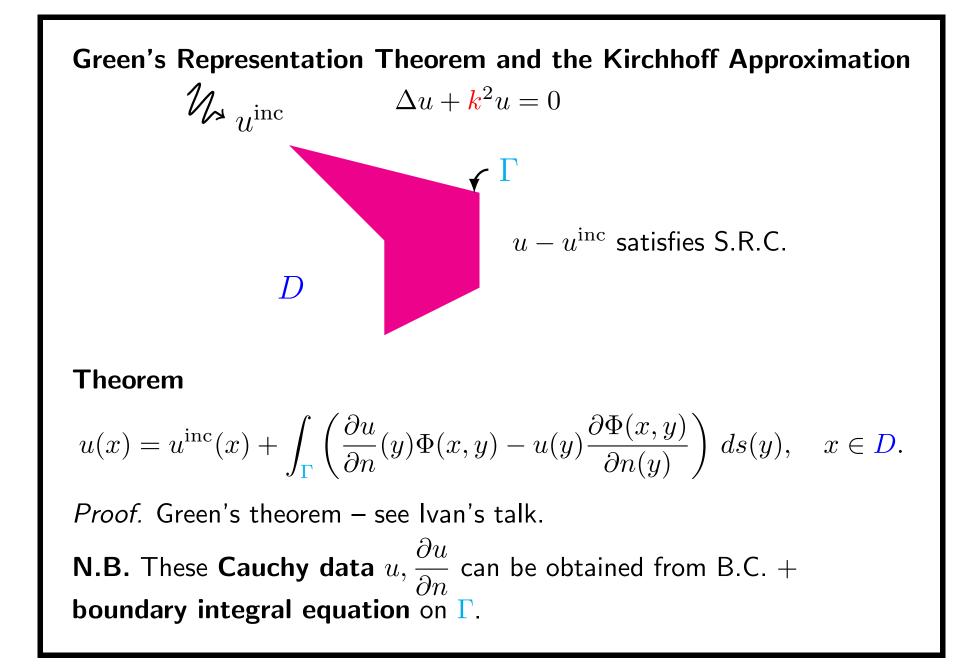
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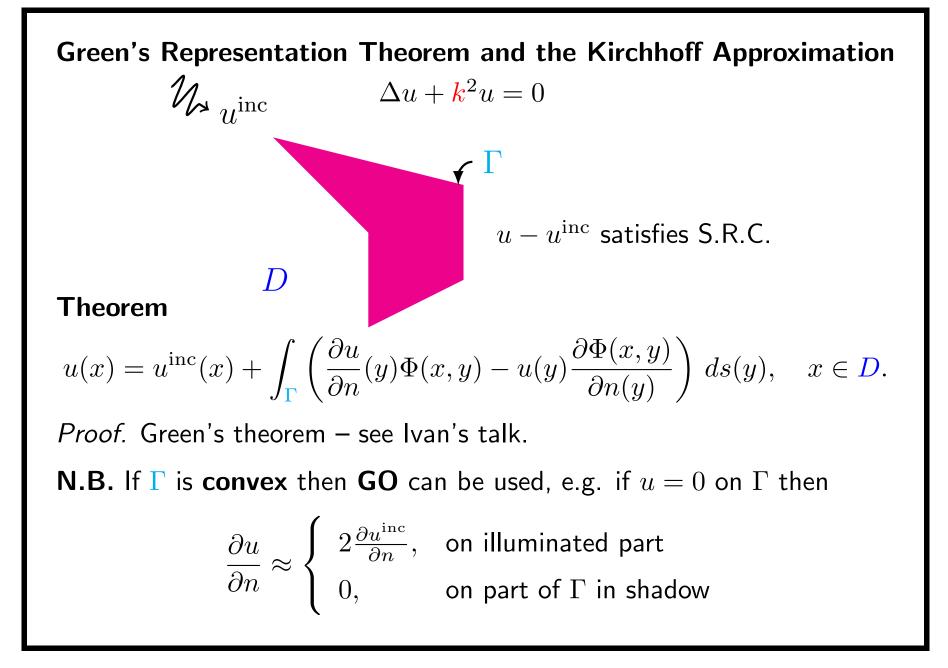
^a "A method for the calculation of the zeta-function", A.M. Turing, *Proc. London Math. Soc.* (1945), and cf. Trefethen and Weideman, *SIAM Rev.* (2014)

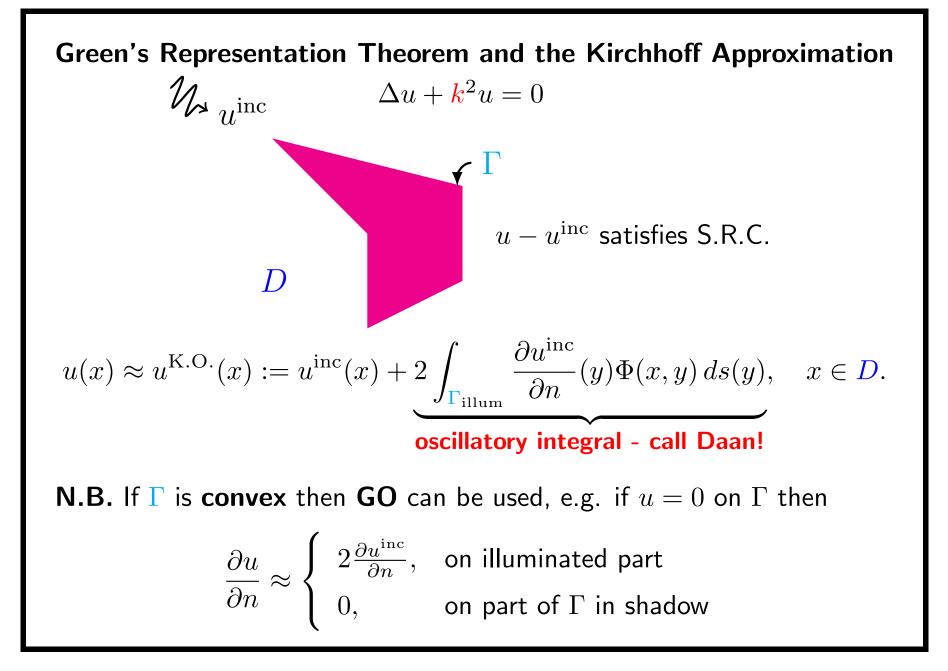


5. THE HF KIRCHHOFF APPROXIMATION









6. PREPARING FOR NA: QUANTIFYING NON-OSCILLATORARINESS!

Motivation. I want to factor **unknown oscillatory functions** into (maybe sums of) products of **known oscillatory functions** and **unknown non-oscillatory functions**.

To make a theory of this I need a **definition**.

Motivation. I want to factor **unknown oscillatory functions** into (maybe sums of) products of **known oscillatory functions** and **unknown non-oscillatory functions**.

Definition. Call $F \in C^{\infty}(0, \infty)$ non-oscillatory if, for some $p_0 > -1$ and $p_{\infty} < 0$, it holds for n = 0, 1, ... that

$$F^{(n)}(t) = \begin{cases} O(t^{p_0 - n}), & t \to 0, \\ O(t^{p_\infty - n}), & t \to \infty. \end{cases}$$

Oscillatory and Non-Oscillatory Functions on $(0, \infty)$ Definition. Call $F \in C^{\infty}(0, \infty)$ non-oscillatory if, for some $p_0 > -1$ and $p_{\infty} < 0$, it holds for n = 0, 1, ... that

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Are these examples??

(i)
$$F(t) = t^{-1/2}$$

(ii) $F(t) = t^{-1/2} e^{it}$
(iii) $F(t) = H_0^{(1)}(t)$
(iv) $F(t) = e^{-it} H_0^{(1)}(t)$

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Are these examples??

(i)
$$F(t) = t^{-1/2}$$
Yes, with $p_0 = p_{\infty} = -1/2$.(ii) $F(t) = t^{-1/2} e^{it}$ No, $F^{(n)}(t) \sim i^n t^{-1/2} e^{it}$ as $t \to \infty$.(iii) $F(t) = H_0^{(1)}(t)$ No, ditto.(iv) $F(t) = e^{-it} H_0^{(1)}(t)$ Yes, with any $-1 < p_0 < 0$ and $p_{\infty} = -1/2$.

Oscillatory and Non-Oscillatory Functions on $(0, \infty)$ Definition. Call $F \in C^{\infty}(0, \infty)$ non-oscillatory if, for some $p_0 > -1$ and $p_{\infty} < 0$, it holds for n = 0, 1, ... that

$$F^{(n)}(t) = \begin{cases} O(t^{p_0 - n}), & t \to 0, \\ O(t^{p_\infty - n}), & t \to \infty. \end{cases}$$

Remark. Non-oscillatory F with $p_{\infty} < -1$, so $F \in L^1(0, \infty)$, are easy to integrate with quadgk.

Compare

$$F(t) = \frac{H_0^{(1)}(t)}{(1+t)^{3/4}} \quad \text{with} \quad F(t) = \frac{e^{-it}H_0^{(1)}(t)}{(1+t)^{3/4}}.$$

Matlab demo ...

Definition. Call $F \in C^{\infty}(0, \infty)$ non-oscillatory if, for some $p_0 > -1$ and $p_{\infty} < 0$, it holds for n = 0, 1, ... that

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Definition. Call F(z) strongly non-oscillatory if it is analytic in $\Re z > 0$ and, for some $p_0 > -1$, $p_{\infty} < 0$, and C > 0, it holds for $\Re z > 0$ that

$$|F(z)| \le \begin{cases} C|z|^{p_0}, & |z| < 1, \\ C|z|^{p_\infty}, & |z| \ge 1. \end{cases}$$

Theorem. If F is strongly non-oscillatory then it is non-oscillatory, with the same values of p_0 and p_{∞} .

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Theorem. If F is strongly non-oscillatory then it is non-oscillatory, with the same values of p_0 and p_{∞} . Example. $F(z) = e^{-iz} H_0^{(1)}(z)$.

Recap

- 1. Wave Equation and Helmholtz Equation
- 2. Basic Concept of high frequency asymptotic approximations of GO and GTD
- 3. **Reflection** canonical problems and high frequency GO approximations
- 4. Diffraction canonical problems and high frequency GTD approximations
- 5. The HF Kirchhoff Approximation
- 6. Preparing for NA: Quantifying Non-Oscillatorariness!

Tomorrow: use this knowledge to design Galerkin methods for boundary integral equations that combine hp-approximation with new oscillatory basis functions to solve (at least some classes of) HF scattering problems with O(1) cost as $k \to \infty$.

References

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