



Discrete adjoint Monte Carlo simulation with reversible random number generators

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Motivation: nuclear fusion in tokamaks



china eu india japan korea russia usa







Didactical example: Heat equation in 1D

Macroscopic view

$$\frac{\partial}{\partial t}\mathcal{T}(x,t) - \frac{\partial^2}{\partial x^2}\mathcal{T}(x,t) + u(x)\mathcal{T}(x,t) = 0$$

Particle view

$$\{Q_{p,\tau}\}_{p=1}^{P} = \left\{ \begin{bmatrix} X_{p,\tau} \\ W_{p,\tau} \end{bmatrix} \right\}_{p=1}^{P}, \quad \tau = 0, \dots, T-1$$

Diffusion step

$$X_{p,\tau+1} = X_{p,\tau} + \sqrt{2\Delta t} \xi_{p,\tau} \quad \xi_{p,\tau} \sim \mathcal{N}(0,1)$$

Reweighting step

$$W_{p,\tau+1} = W_{p,\tau} \exp\left(-\Delta t \,\hat{u}\left(X_{p,\tau+1}\right)\right)$$





Optimization problem

Continuous

$$\min_{u(x)} \mathcal{J}(\mathcal{T}(x,t), u(x,t)) = \int_0^\infty \int_0^L \frac{1}{2} \mathcal{T}(x,t)^2 dx \, dt + \kappa \int_0^L \frac{1}{2} u(x)^2 dx$$

subject to
$$\frac{\partial}{\partial t}\mathcal{T}(x,t) - \frac{\partial^2}{\partial x^2}\mathcal{T}(x,t) + u(x)\mathcal{T}(x,t) = 0,$$

 $\mathcal{T}(x,0) = \mathcal{T}_0(x), \quad \mathcal{T}(0,t) = \mathcal{T}(L,t)$

Discrete

$$\mathcal{J}(\mathcal{T}(x,t), u(x,t)) \approx \hat{\mathcal{J}}(\hat{\mathcal{T}}, \hat{u}) = \Delta t \sum_{\tau=0}^{T} \Delta x \frac{1}{2} \hat{\mathcal{T}}_{\tau}^{\top} \hat{\mathcal{T}}_{\tau} + \nu \Delta x \frac{1}{2} \hat{u}^{\top} \hat{u}$$
$$\hat{\mathcal{T}}_{\tau,n} = \sum_{p=1}^{P} \frac{1}{\Delta x} \mathcal{I}_n \left(X_{p,\tau} \right) W_{p,\tau}$$

MА



Adjoint-based optimization

PDE-constrained optimization

$$\min_{u} \mathcal{J}(q, u), \quad \text{subject to} \quad \mathcal{B}(q; u) = 0$$

Naive application of chain rule

$$\frac{\mathrm{d}\mathcal{J}}{\mathrm{d}u}(q(u),u) = \frac{\partial\mathcal{J}}{\partial u}(q,u) + \frac{\partial\mathcal{J}}{\partial q}(q,u)\frac{\mathrm{d}q}{\mathrm{d}u}(u)$$







Adjoint-based optimization

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▶ Solution: Lagrangian $\mathcal{L}(q, q^*, u) = \mathcal{J}(q, u) + (q^*, \mathcal{B}(q, u))$

$$\begin{split} \mathcal{B}(q,u) &= 0 & \text{State equation} \\ \frac{\partial \mathcal{J}^*}{\partial q}(q,u) + \frac{\partial \mathcal{B}^*}{\partial q}(q,u)q^* &= 0 & \text{Adjoint equation} \\ \frac{\partial \mathcal{J}^*}{\partial u}(q,u) + \frac{\partial \mathcal{B}^*}{\partial u}(q,u)q^* &= 0 & \text{Design equation} \end{split}$$







Discrete adjoint

▶ Linearized discretization around $\hat{q}' = \hat{q}(\hat{u})$

$$\hat{\mathcal{B}}(\hat{q},\hat{u}) \approx \hat{\mathcal{B}}(\hat{q}',\hat{u}) + \frac{\partial \hat{\mathcal{B}}}{\partial \hat{q}}(\hat{q}',\hat{u})(\hat{q} - \hat{q}') = 0$$

is a matrix-vector system







Discrete adjoint

• Linearized discretization around $\hat{q}' = \hat{q}(\hat{u})$

$$\hat{\mathcal{B}}(\hat{q}, \hat{u}) pprox \qquad \qquad \frac{\partial \hat{\mathcal{B}}}{\partial \hat{q}}(\hat{q}', \hat{u})(\hat{q} - \hat{q}') = 0$$

is a matrix-vector system

Adjoint equation

$$\frac{\partial \hat{\mathcal{J}}^{\top}}{\partial \hat{q}}(\hat{q}',\hat{u}) + \frac{\partial \hat{\mathcal{B}}^{\top}}{\partial \hat{q}}(\hat{q}',\hat{u})\hat{q}^{*} = 0$$







Monte Carlo as a matrix

 \blacktriangleright For each particle p and time step τ

$$B_{p,\tau+1}(Q_{p,\tau+1}, Q_{p,\tau}; \hat{u}) = \begin{bmatrix} X_{p,\tau+1} - X_{p,\tau} - \sqrt{2\Delta t}\xi_{p,\tau} \\ W_{p,\tau+1} - W_{p,\tau} \exp\left(-\Delta t \,\hat{u} \left(X_{p,\tau+1}\right)\right) \end{bmatrix} = 0$$

Particle Jacobian

$$\frac{\partial \hat{\mathcal{B}}_p}{\partial \hat{q}_p}(Q_p, \hat{u}) = \begin{bmatrix} \frac{\partial B_{p,1}}{\partial Q_{p,1}} & & \\ \frac{\partial B_{p,2}}{\partial Q_{p,1}} & \frac{\partial B_{p,2}}{\partial Q_{p,2}} & & \\ & \ddots & \ddots & \\ & & \frac{\partial B_{p,T}}{\partial Q_{p,T-1}} & \frac{\partial B_{p,T}}{\partial Q_{p,T}} \end{bmatrix}$$
$$\frac{\partial B_{p,\tau+1}}{\partial Q_{p,\tau+1}} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \frac{\partial B_{p,\tau+1}}{\partial Q_{p,\tau}} = \begin{bmatrix} -1 & 0 \\ 0 & -\exp\left(-\Delta t \, \hat{u} \left(X_{p,\tau+1}\right)\right) \end{bmatrix}$$



Adjoint Monte Carlo

Simulate particles from final state

$$Q_{p,T}^{*} = \begin{bmatrix} X_{p,T}^{*} \\ W_{p,T}^{*} \end{bmatrix} = -\frac{\partial \hat{\mathcal{J}}^{\top}}{\partial Q_{p,T}} = -\begin{bmatrix} 0 \\ \Delta t \hat{\mathcal{T}} (X_{p,T}) \end{bmatrix}$$

Reverse time stepping

$$Q_{p,\tau}^{*} = -\frac{\partial B_{p,\tau+1}}{\partial Q_{p,\tau}} Q_{p,\tau+1}^{*} - \frac{\partial \hat{\mathcal{J}}}{\partial Q_{p,\tau}}$$
$$= \begin{bmatrix} X_{p,\tau+1}^{*} \\ \exp\left(-\Delta t \,\hat{u} \left(X_{p,\tau+1}\right)\right) W_{p,\tau+1}^{*} \end{bmatrix} - \begin{bmatrix} 0 \\ \Delta t \hat{\mathcal{T}}(X_{p,\tau}) \end{bmatrix}$$

• Note that $X^*_{p,\tau} = 0$ for all τ

$$W_{p,\tau}^* = \exp\left(-\Delta t \,\hat{u}\left(X_{p,\tau+1}\right)\right) W_{p,\tau+1}^* - \Delta t \hat{\mathcal{T}}(X_{p,\tau})$$





Matching forward and adjoint simulations

- Same paths in forward/backward simulation
- Challenge: $P \times T$ large
- Solutions:
 - Checkpointing: 2 forward simulations + backward simulation







Reversing a random number generator

- PCG: permuted congruential generator¹
 - internal state ζ_k and constant vectors a, c, m

$$\zeta_{k+1} = a\zeta_k + c \mod m,$$

- 1-way (permutation) function generates output from ζ_k
- Passes TestU01 with flying colors

Reversing modular operations \rightarrow reversed uniform sequence

$$\zeta_k = a^{-1}(\zeta_{k+1} - c) \mod m,$$

$$a^{-1} \equiv a^{m-2} \mod m$$

Exponential distribution through inverse transform:

$$u \sim \mathcal{U}([0,1]) \Rightarrow -\lambda \ln(1-u) \sim \mathcal{E}(\lambda)$$

1: M.E. O'Neill, PCG: A Family of Simple Fast Space-Efficient Statistically Good Algorithms for Random Number Generation. Technical report HMC-CS-2014-0905, Harvey Mudd College (2014)





Normal distribution through Ziggurat



• Uses either 1, 2 or 1 + 2n, n = 1, 2, ... uniform values

- How many depends on the first value
- Solution: Seed second generator





Generator timings









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Optimal cooling



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Fusion example: domain length optimization²



$$\begin{aligned} \mathcal{J}(q, L_{\theta}) &= \frac{1}{2} \left(n_{\mathbf{i}} b_{\theta} u_{\parallel} - \Gamma_d \right)^2 \Big|_{L_{\theta}} + \frac{\kappa}{2} \left(L_{\theta} - L_0 \right)^2 \\ q &= \left(n_{\mathbf{i}}, u_{\parallel}, f_{\mathbf{n}} \right)^{\top} \end{aligned}$$

 $\begin{array}{ll} n_{\mathbf{i}} & \text{plasma density} \\ u_{\parallel} & \text{plasma velocity} \\ f_{\mathbf{n}} & \text{neutral position-velocity} \end{array}$

2: W. Dekeyser, Optimal Plasma Edge Configurations for Next-Step Fusion Reactors. PhD thesis (2014)



Preliminary results





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Can all simulations be reversed?

In theory yes!

. . .

- ... but at what cost?
 - Reflections
 - Collisions in batched simulations



Løvbak, E., Blondeel, F., Lee, A., Vanroye, L., Van Barel, A., Samaey, G., *Reversible random number generation for adjoint Monte Carlo simulation of the heat equation.* Monte Carlo and Quasi-Monte Carlo Methods - MCQMC 2022. Submitted (2023) arXiv:2302.02778

Løvbak, E., Multilevel and adjoint Monte Carlo methods for plasma edge neutral particle models. PhD thesis (2023)





Plasma edge model

▶ Plasma
$$\Rightarrow$$
 Finite volume

$$\frac{\partial}{\partial \theta} \left(n_{\mathbf{i}} b_{\theta} u_{\parallel} \right) = \mathbf{S}_{n_{\mathbf{i}}} - K_{\mathsf{d}} n_{\mathbf{i}}$$
$$\frac{\partial}{\partial \theta} \left(m n_{\mathbf{i}} b_{\theta} u_{\parallel}^{2} - \nu_{\mathsf{d}} \frac{\partial u_{\parallel}}{\partial \theta} \right) = \mathbf{S}_{u_{\parallel}} - b_{\theta} \frac{\partial p}{\partial \theta}$$

 $S_{\psi} = \int f_{\mathbf{n}}(\theta, v) \Psi(\theta, v) \mathrm{d}v, \quad \psi \in \{n_{\mathbf{i}}/u_{\parallel}\} \quad \Rightarrow \quad \text{Low-dimensinal}$

Neutrals \Rightarrow Monte Carlo





