



Numerical analysis of pattern formation in auxin transport models

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Outline

- ▶ Introduction and motivation
- ▶ Concentration-based transport models
- ▶ Pattern formation in an unbounded tissue
- ▶ Pattern formation in a bounded tissue
- ▶ Pattern formation in a growing tissue
- ▶ Conclusions and outlook



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Introduction and motivation

Pattern formation



Regularity and mathematical properties





Introduction and motivation

IAA

- ▶ Indole-3-acetic acid
- ▶ Plant hormone
- ▶ Member of the auxin family

Transport of IAA

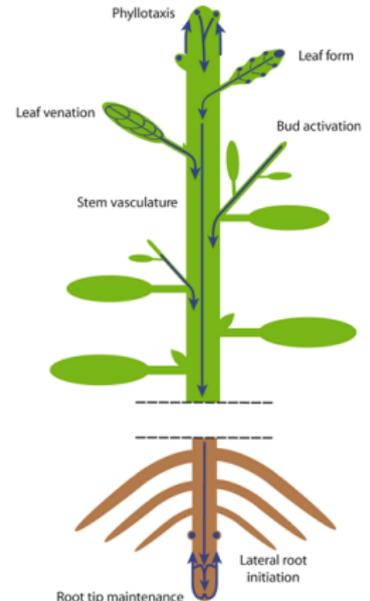
- ▶ Leads to accumulation points of IAA
- ▶ Plays a central role in pattern formation

Examples

P.Prusinkiewicz and A.Runions.

Computational models of plant development and form.

New Phytologist, 193(3):549-569,2012.



How is auxin (IAA) transported throughout a plant and how do auxin peaks arise?



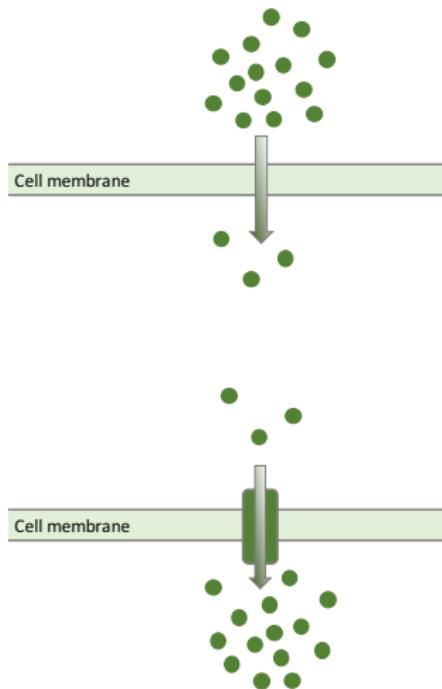
Passive transport

- ▶ Diffusion
- ▶ From high to low concentration
- ▶ Requires no energy

Active transport

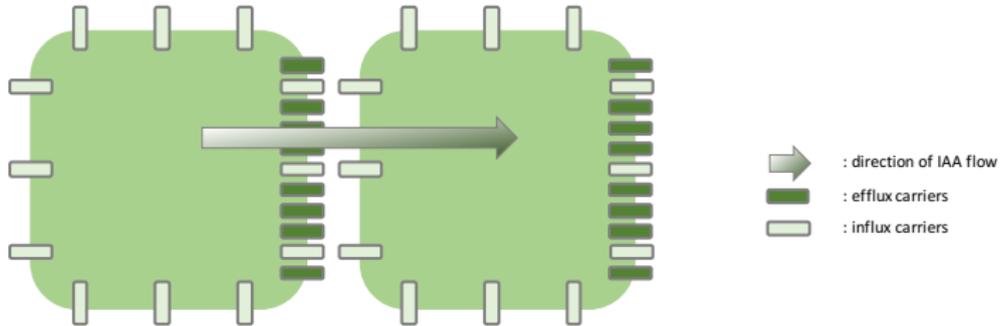
- ▶ Most IAA is polarly charged
- ▶ From low to high concentration
- ▶ Requires auxin carriers

IAA transport





Active auxin transport



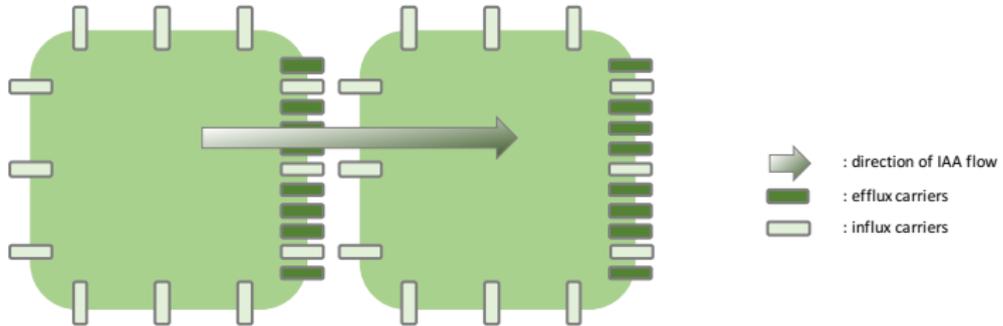
Auxin exporter PIN1

- ▶ Protein
- ▶ Member of the PIN family
- ▶ Main auxin efflux carrier
- ▶ Polar localization
 - ▶ Influenced by IAA

! complete feedback loop between IAA and PIN1



Active auxin transport



Auxin exporter PIN1

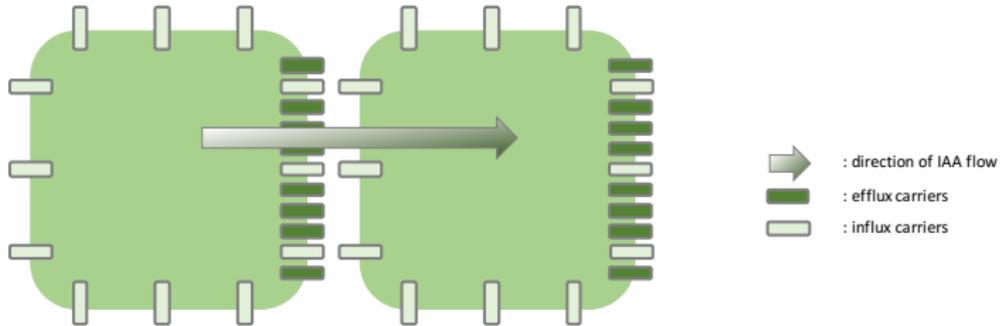
- ▶ Protein
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Different hypotheses

! complete feedback loop between IAA and PIN1



Active auxin transport



Auxin importer AUX/LAX

- ▶ Protein
- ▶ Limited role in comparison with PIN1
- ▶ Uniformly distributed on cell membrane



Outline

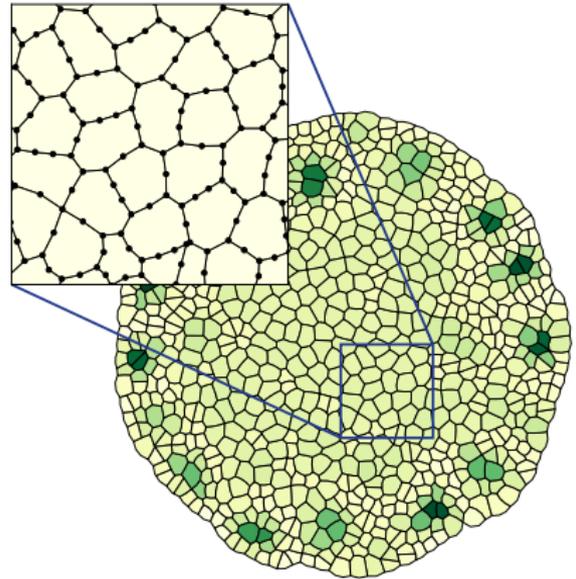
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Geometric representation of tissue

A graph H :

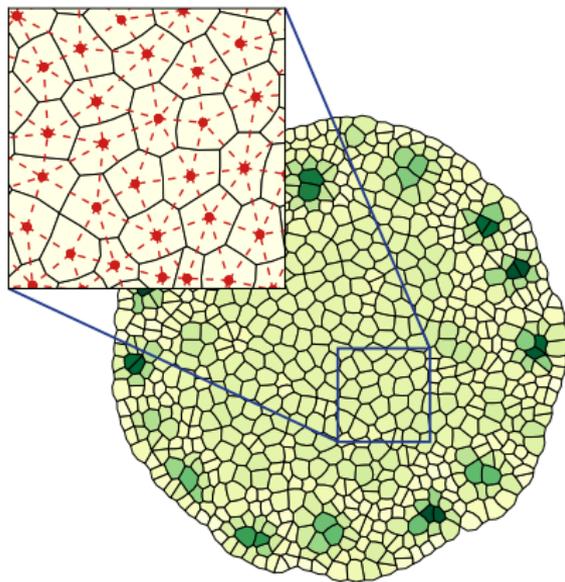
- ▶ Cell walls are represented by the edges e
- ▶ Cell vertices are the vertices v
- ▶ Cells are represented as polygons, the faces of the graph
- ▶ Neighboring cells have common edges



Topological representation of tissue

A graph H^* :

- ▶ Dual graph of H
- ▶ Cells $i \in \{1, \dots, n\}$: vertices
- ▶ Connection between neighboring cells: edges
- ▶ \mathcal{N}_i : cells up to distance 1 from cell i
- ▶ Weighted graph: labelling each edge with relevant information
- ▶ State variables per cell (m)





The transport model

General transport model

Definition (concentration-based model)

A concentration-based model is a set of $m \times n$ ODEs of the form

$$\begin{aligned}\dot{\mathbf{y}}_i &= \pi(\mathbf{y}_i) - \delta(\mathbf{y}_i) + \frac{\mathbf{D}}{V_i} \sum_{j \in \mathcal{N}_i} l_{ij}(\mathbf{y}_j - \mathbf{y}_i) \\ &\quad + \frac{T}{V_i} \sum_{j \in \mathcal{N}_i} \nu_{ji}(\mathbf{y}_1, \dots, \mathbf{y}_n | H^*) - \nu_{ij}(\mathbf{y}_1, \dots, \mathbf{y}_n | H^*)\end{aligned}$$

for $i = 1, \dots, n$ and $\pi, \delta: \mathbb{R}_+^m \rightarrow \mathbb{R}_+^m$, the production and decay functions, $\mathbf{D} \in \mathbb{R}^{m \times m}$ is a diagonal diffusion matrix, $T \in \mathbb{R}_+$, is the active transport parameter, and $\nu_{ij}: \mathbb{R}_+^m \times \dots \times \mathbb{R}_+^m \rightarrow \mathbb{R}_+^m$ are the active transport functions.



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Example: model of Smith et al.

$\mathbf{y}_i = (a_i, p_i)'$: a_i : IAA concentration in cell i
 p_i : PIN1 concentration in cell i



The transport model

Example: model of Smith et al.

$$\begin{aligned} \frac{da_i}{dt} = & \pi(\mathbf{y}_i) - \delta(\mathbf{y}_i) + \frac{D}{V_i} \sum_{j \in \mathcal{N}_i} l_{ij}(\mathbf{y}_j - \mathbf{y}_i) \\ & + \frac{T}{V_i} \sum_{j \in \mathcal{N}_i} \nu_{ji}(\mathbf{y}_1, \dots, \mathbf{y}_n | H^*) - \nu_{ij}(\mathbf{y}_1, \dots, \mathbf{y}_n | H^*) \end{aligned}$$

$$\frac{dp_i}{dt} = \pi(\mathbf{y}_i) - \delta(\mathbf{y}_i)$$



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$$\frac{dp_i}{dt} = \frac{\rho_{PIN_0} + \rho_{PIN} a_i}{1 + \kappa_{PIN} p_i} - \delta(\mathbf{y}_i)$$



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$$\begin{aligned} \frac{da_i}{dt} = & \frac{\rho_{IAA}}{1 + \kappa_{IAA} a_i} - \mu_{IAA} a_i + \frac{D}{V_i} \sum_{j \in \mathcal{N}_i} l_{ij} (\mathbf{y}_j - \mathbf{y}_i) \\ & + \frac{T}{V_i} \sum_{j \in \mathcal{N}_i} \nu_{ji}(\mathbf{y}_1, \dots, \mathbf{y}_n | H^*) - \nu_{ij}(\mathbf{y}_1, \dots, \mathbf{y}_n | H^*) \end{aligned}$$

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$$\frac{dp_i}{dt} = \frac{\rho_{PIN_0} + \rho_{PIN} a_i}{1 + \kappa_{PIN} p_i} - \mu_{PIN} p_i$$

with

$$P_{ij}(\mathbf{a}, \mathbf{p}) = p_i \frac{l_{ij} \exp(c_1 a_j)}{\sum_{k \in \mathcal{N}_i} l_{ik} \exp(c_1 a_k)}$$



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Hypothesis (Active transport functions)

The active transport functions can be expressed as

$$(\nu_{ij})_l = \psi_l(\mathbf{y}_i, \mathbf{y}_j | H^*) \frac{l_{ij} \varphi_l(\mathbf{y}_j)}{\sum_{k \in \mathcal{N}_i} l_{ik} \varphi_l(\mathbf{y}_k)}, \quad \text{for } l = 1, \dots, m$$



An example

Model of Smith et al.

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$$\nu_{ij} = P_{ij}(\mathbf{a}, \boldsymbol{\rho}) \frac{a_i^2}{1 + \kappa_T a_j^2} = \rho_i \frac{l_{ij} \exp(c_1 a_j)}{\sum_{k \in \mathcal{N}_i} l_{ik} \exp(c_1 a_k)} \frac{a_i^2}{1 + \kappa_T a_j^2}$$



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$$\nu_{ij} = P_{ij}(\mathbf{a}, \mathbf{p}) \frac{a_i^2}{1 + \kappa_T a_j^2} = p_i \frac{l_{ij} \exp(c_1 a_j)}{\sum_{k \in \mathcal{N}_i} l_{ik} \exp(c_1 a_k)} \frac{a_i^2}{1 + \kappa_T a_j^2}$$

So

$$\psi: \left(\begin{bmatrix} a_i \\ p_i \end{bmatrix}, \begin{bmatrix} a_j \\ p_j \end{bmatrix} \right) \mapsto p_i \frac{a_i^2}{1 + \kappa_T a_j^2}, \quad \varphi: \begin{bmatrix} a_j \\ p_j \end{bmatrix} \mapsto \exp(c_1 a_j)$$



Type of solutions

System

- ▶ Dynamical system

$$\dot{\mathbf{y}} = F(\mathbf{y}, \lambda)$$

- ▶ Fixed geometry

Steady state solutions

- ▶ Motivation
 - ▶ Transport and diffusion measured in seconds
 - ▶ One cell cycle: 24 hours
- ▶ $\dot{\mathbf{y}} = F(\mathbf{y}, \lambda) = 0$
- ▶ Dynamical systems approach
 - ▶ Find steady state solution space in function of the parameters
 - ▶ Use continuation methods and bifurcation analysis



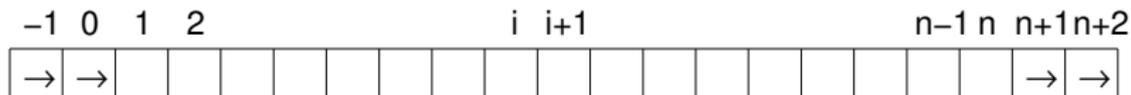
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Pattern formation in an unbounded tissue

Unbounded regular domain



- ▶ $V_i = V^* \quad \forall i$
- ▶ $I_{ij} = I^* \quad \forall i \text{ and } j \in \mathcal{N}_i$
- ▶ Unbounded: $|\mathcal{N}_i| = |\mathcal{N}_j| \quad \forall i, j$

Homogeneous solution

- ▶ $\mathbf{y}^* = \mathbf{y}_i$
- ▶ Steady state problem: $0 = \pi(\mathbf{y}^*) - \delta(\mathbf{y}^*)$



Homogeneous steady state

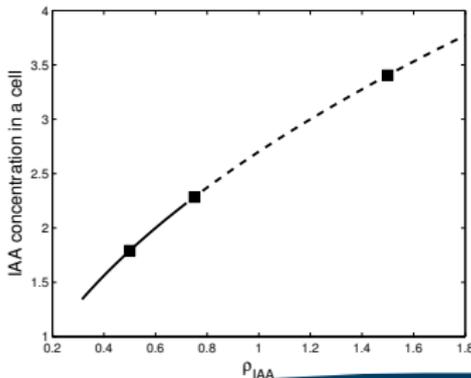
Example: model of Smith et al.

- ▶ Unbounded regular domain

- ▶
$$a^* = \frac{-1 + \sqrt{1 + 4\kappa_{IAA}\rho_{IAA}/\mu_{IAA}}}{2\kappa_{IAA}}$$

$$p^* = \frac{-1 + \sqrt{1 + 4\kappa_{PIN}(\rho_{PIN0} + \rho_{PIN}^*)/\mu_{PIN}}}{2\kappa_{PIN}}$$

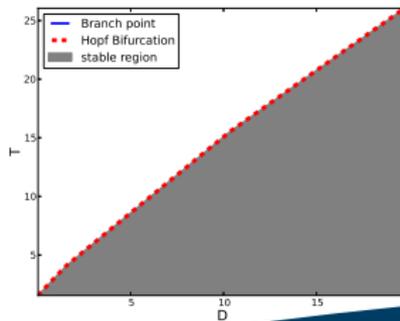
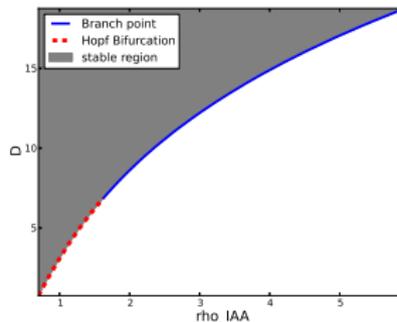
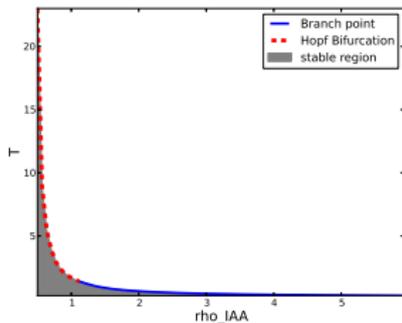
- ▶ Example:
 - ▶ File of 20 regular cells
 - ▶ Zero Neumann BC





Homogeneous steady state

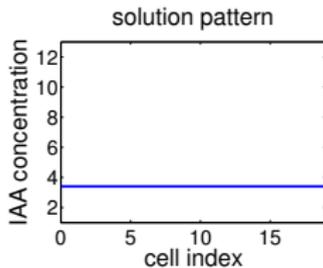
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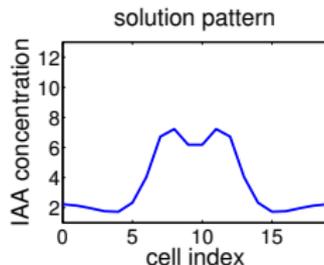
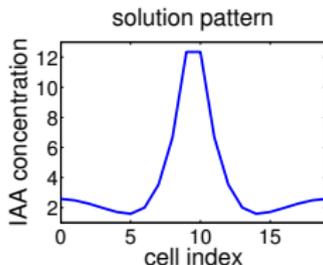
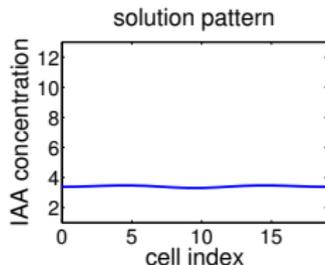


Pattern formation in an unbounded tissue

Homogeneous solution exists



Solutions with IAA peaks exist



→ Peaks form with a Turing instability



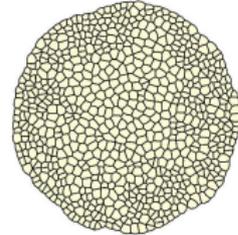
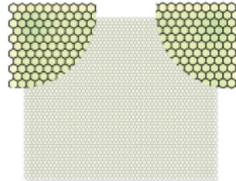
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Pattern formation in a bounded tissue

Bounded domain



Main results

- ▶ Homogeneous steady state
- ▶ Origin of IAA peaks
- ▶ Formation of stable IAA spots



Homogeneous steady state

Steady state problem

$$0 = \pi(\mathbf{y}^*) - \delta(\mathbf{y}^*) + \frac{D}{V_i} \sum_{j \in \mathcal{N}_i} l_{ij}(\mathbf{y}^* - \mathbf{y}^*) \\ + \frac{T}{V_i} \sum_{j \in \mathcal{N}_i} \left(\psi(\mathbf{y}^*, \mathbf{y}^* | H^*) \odot l_{ij} \varphi(\mathbf{y}^*) \oslash \sum_{k \in \mathcal{N}_j} l_{jk} \varphi(\mathbf{y}^*) \right. \\ \left. - \psi(\mathbf{y}^*, \mathbf{y}^* | H^*) \odot l_{ij} \varphi(\mathbf{y}^*) \oslash \sum_{k \in \mathcal{N}_i} l_{ik} \varphi(\mathbf{y}^*) \right)$$

Homogeneous solution

- ▶ $T = 0 : \forall i : \mathbf{y}_i = \mathbf{y}^*$ is steady state solution
- ▶ $T \neq 0$: Homogeneous distribution is NOT always a steady state solution
 - Peaks do not form with a Turing bifurcation



Origin of IAA peaks

Steady state problem, zero diffusion

$$0 = \pi(\mathbf{y}_i) - \delta(\mathbf{y}_i) + \frac{T}{V_i} \sum_{j \in \mathcal{N}_i} \left(\psi(\mathbf{y}_j, \mathbf{y}_i) \odot l_{ij} \varphi(\mathbf{y}_i) \ominus \sum_{k \in \mathcal{N}_j} l_{jk} \varphi(\mathbf{y}_k) \right. \\ \left. - \psi(\mathbf{y}_i, \mathbf{y}_j) \odot l_{ij} \varphi(\mathbf{y}_j) \ominus \sum_{k \in \mathcal{N}_j} l_{ik} \varphi(\mathbf{y}_k) \right)$$

Steady state solution for $0 < T \ll 1 \mu\text{m}^3/\text{s}$



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Steady state solution for $0 < T \ll 1 \mu\text{m}^3/\text{s}$

- ▶ $\mathbf{y}_i = \mathbf{y}^* + T\boldsymbol{\eta}_i + \mathcal{O}(T^2)$ for $i = 1, \dots, n$ and $(\boldsymbol{\eta}_i)_j = \mathcal{O}(1)$
- ▶ Taylor expansion around $(\mathbf{y}^*, \dots, \mathbf{y}^*)^T \in \mathbb{R}^{nm}$



Irregular domains

$$\forall i: \mathbf{y}_i = \mathbf{y}^* + \xi_i T \left(\pi'(\mathbf{y}^*) - \delta'(\mathbf{y}^*) \right)^{-1} \psi(\mathbf{y}^*, \mathbf{y}^*)$$

$$\xi_i = \frac{1}{V_i} \left(1 - \sum_{j \in \mathcal{N}_i} \frac{l_{ij}}{\sum_{k \in \mathcal{N}_j} l_{jk}} \right)$$

→ Purely geometric mechanism

Regular domains

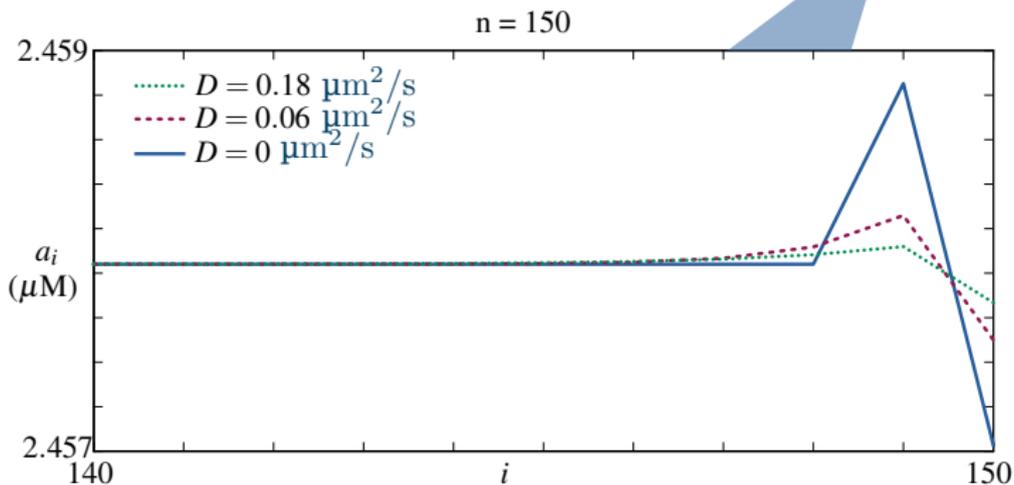
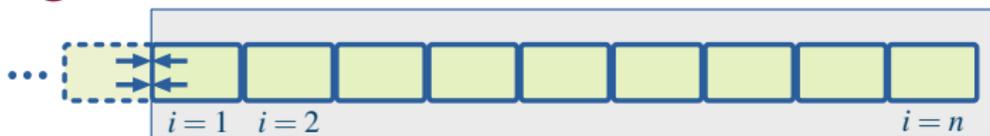
- ▶ $V_i = V^*$, $l_{ij} = l^*$
- ▶ Peaks form at the boundary

$$\xi_i = \frac{1}{V^*} \left(1 - \sum_{j \in \mathcal{N}_i} \frac{1}{|\mathcal{N}_j|} \right)$$



Origin of IAA peaks in regular domains

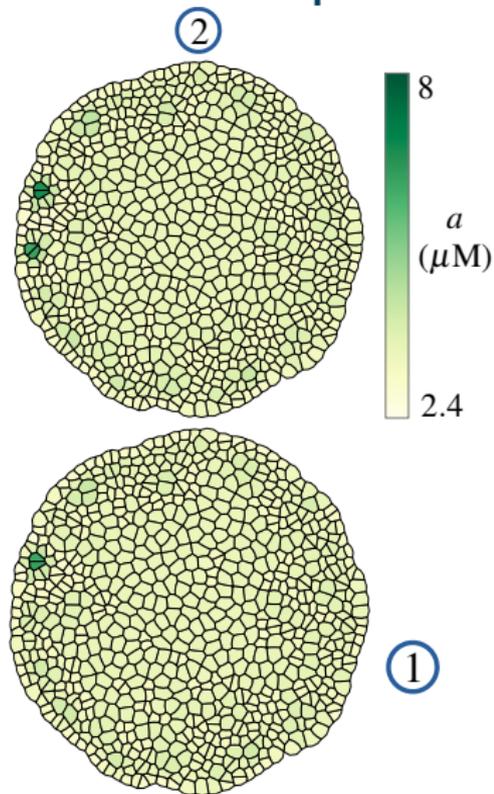
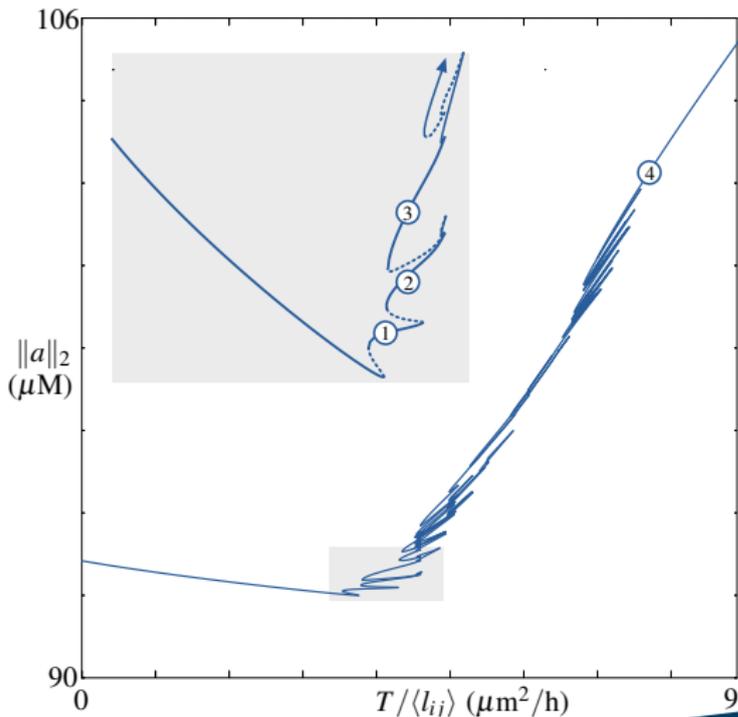
1D regular





2D irregular

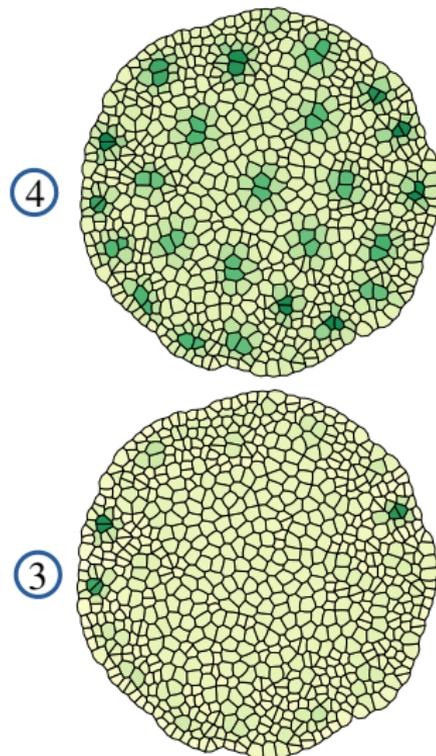
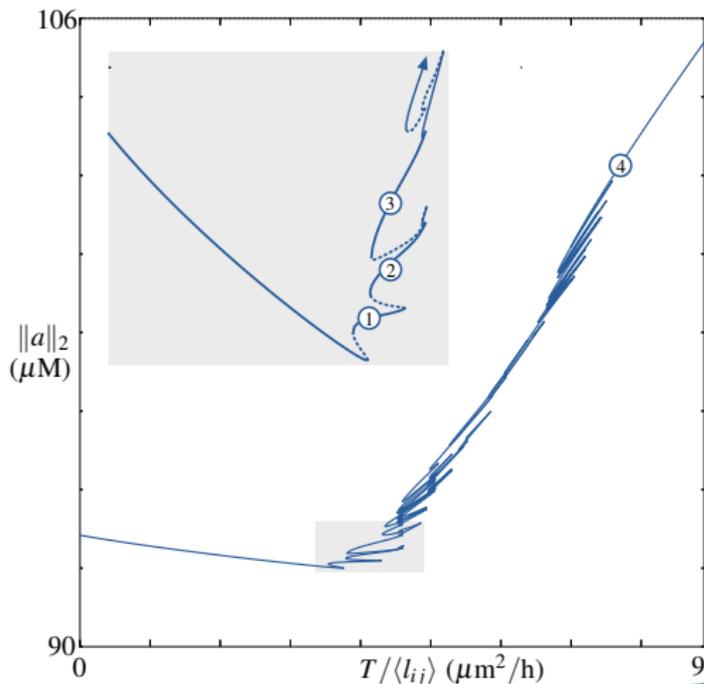
Formation of stable IAA spots





Formation of stable IAA spots

2D irregular





Outline

- ▶ Introduction and motivation
- ▶ Concentration-based transport models
- ▶ Pattern formation in an unbounded tissue
- ▶ Pattern formation in a bounded tissue
- ▶ **Pattern formation in a growing tissue**
- ▶ Conclusions and outlook



Pattern formation in a growing tissue

Assumptions

- ▶ Consider only external layer
 - ▶ Layer of irregular cells curved in 3D space
- ▶ Assume sequential order of processes



Model

- ▶ Physically based Mass Spring System
- ▶ Auxin transport models
- ▶ Material to a cell wall is added when wall is under tension



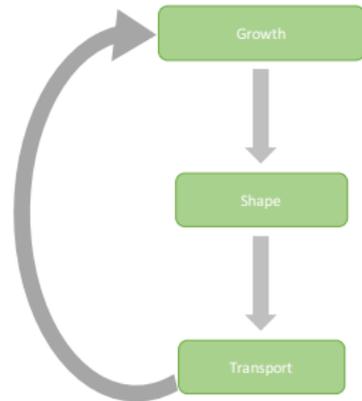
Pattern formation in a growing tissue

Assumptions

- ▶ Consider only external layer
 - ▶ Layer of irregular cells curved in 3D space
- ▶ Assume sequential order of processes

Model

- ▶ Physically based Mass Spring System
- ▶ Auxin transport models
- ▶ Material to a cell wall is added when wall is under tension





Pattern formation in a growing tissue

Assumptions

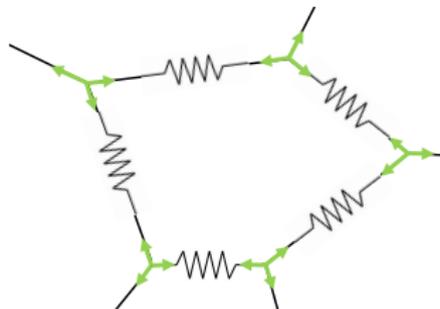
- ▶ Consider only external layer
- ▶ Assume sequential order of processes

Model

- ▶ Physically based Mass Spring System
 - ▶ Tissue is a damped elastic system
 - ▶ Each edge e is associated with a spring
 - ▶ Each vertex v is attached with a mass

Relate forces acting on the springs with displacement of vertices

- ▶ Auxin transport models
- ▶ Material to a cell wall is added when wall is under tension





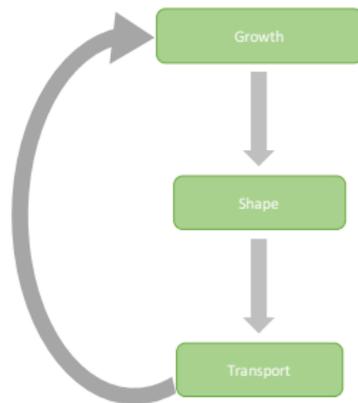
Pattern formation in a growing tissue

Assumptions

- ▶ Consider only external layer
- ▶ Assume sequential order of processes

Model

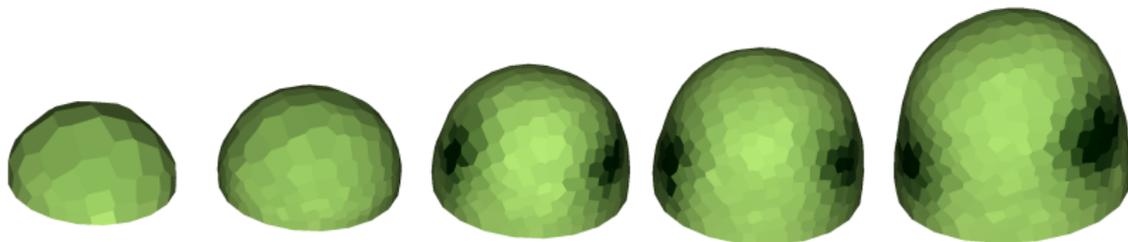
- ▶ Physically based Mass Spring System
- ▶ Auxin transport models
- ▶ Material to a cell wall is added when wall is under tension
 - ▶ Relate with changing restlength over time
 - ▶ Dependent on IAA concentration





Pattern formation in a growing tissue

Domains



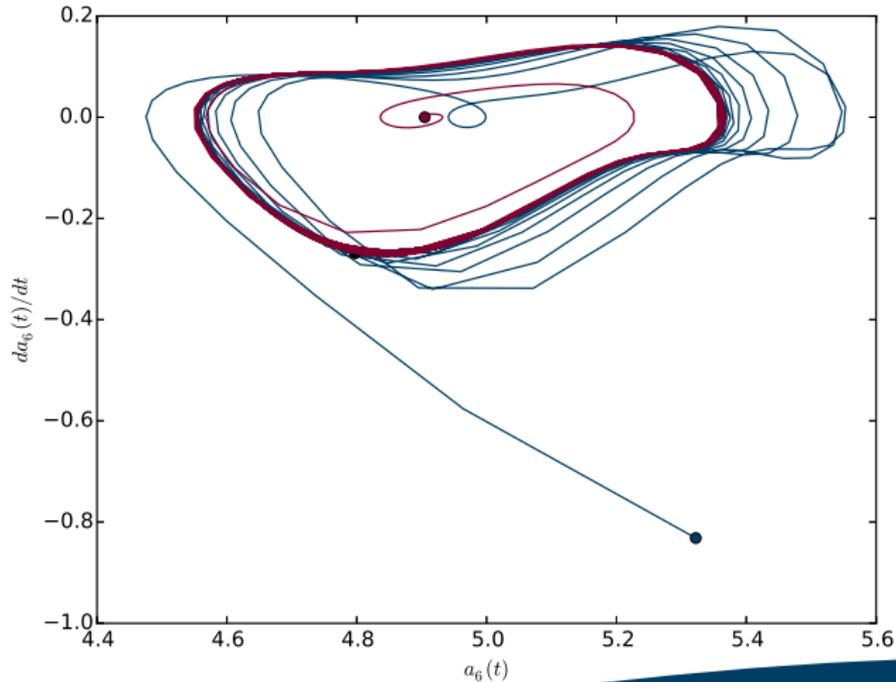
Main results

- ▶ Timeframe till steady state
- ▶ Periodic or quasi periodic solutions



Trajectory

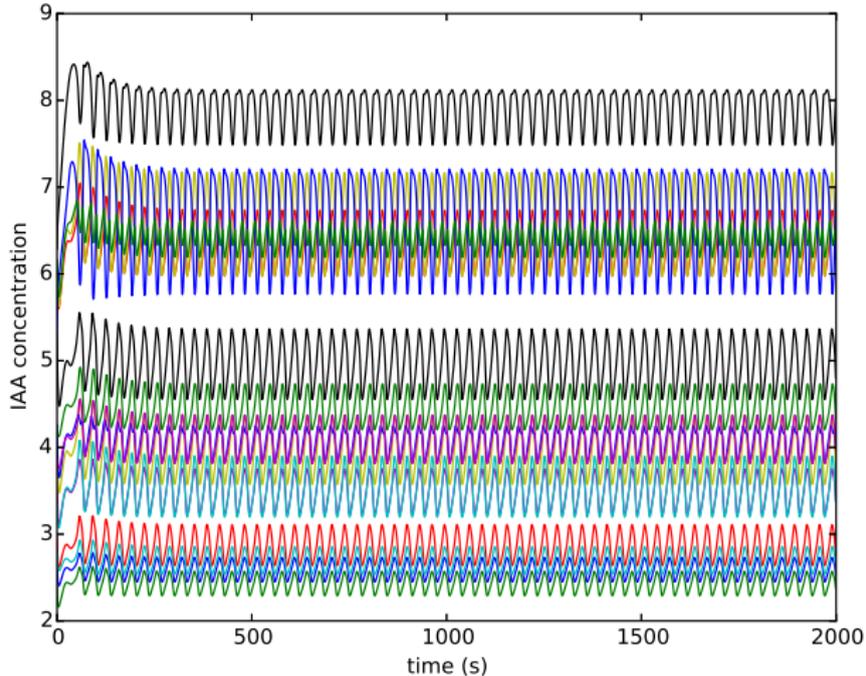
Timeframe till steady state





Periodic solution

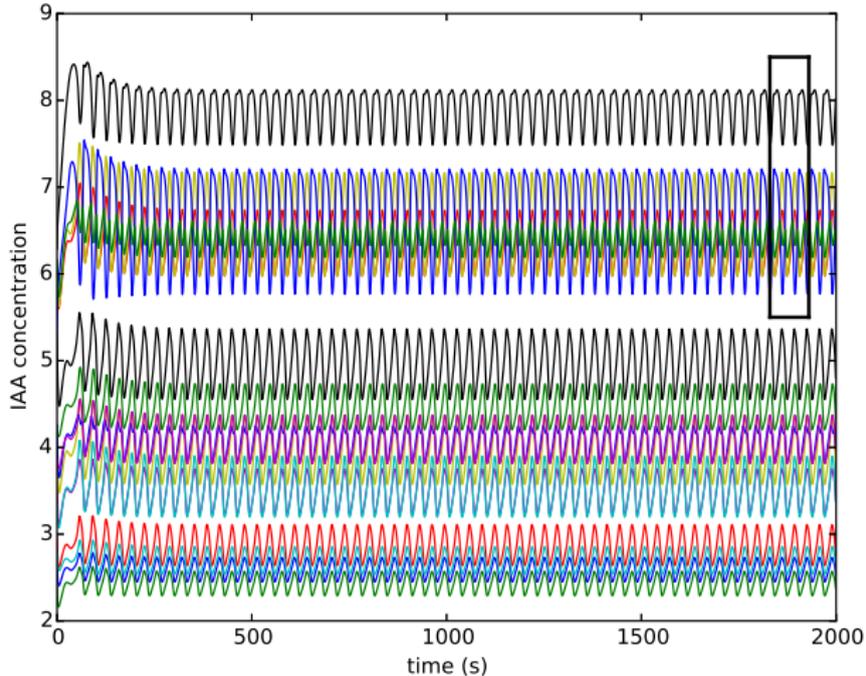
Time evolution in several cells





Periodic solution

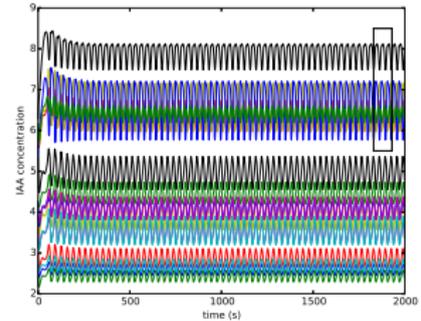
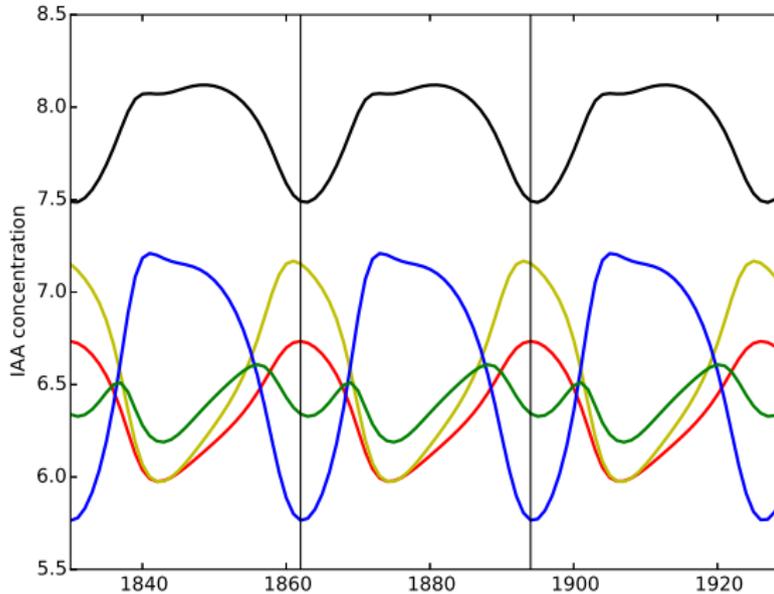
Time evolution in several cells





Periodic solution

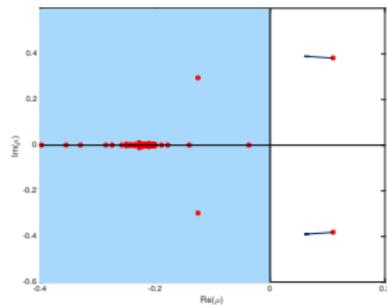
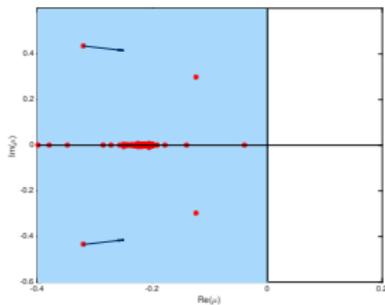
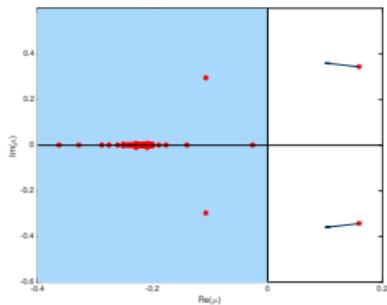
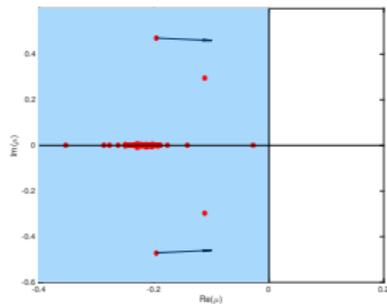
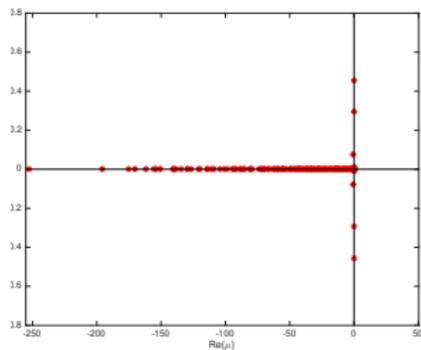
Time evolution in several cells





Spectrum

Periodic solution





Outline

- ▶ Introduction and motivation
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- ▶ Pattern formation in a bounded tissue
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Conclusions and Outlook

Conclusions

- ▶ Formulated a mathematical description of auxin transport models
 - ▶ Introduced a general definition and hypothesis
 - ▶ Studied auxin transport models as dynamical systems
- ▶ Developed PyNCT
 - ▶ Numerical Continuation Toolbox in Python
 - ▶ Based on sparse linear algebra
- ▶ Examined steady state solutions as a function of model parameters
 - ▶ Calculated a homogeneous solution
 - ▶ Proved the formation of IAA peaks
 - ▶ Revealed a snaking bifurcation scenario
- ▶ Studied a growth model with a complete feedback loop between growth and IAA



Conclusions and Outlook

Outlook

- ▶ Compare and improve auxin transport models
 - ▶ Classify existing and new auxin transport models
 - ▶ Transform models to models with dimensionless parameters
 - ▶ Calculate the complete solution space in function of parameters
 - ▶ Extend functionalities PyNCT
 - ▶ Study automatically the behaviour of new and existing models when parameters are changed
- ▶ Improve growth model
 - ▶ Study the influence of IAA on growth
 - ▶ Investigate cell division mechanism
 - ▶ Eliminate separation of time-scales
 - ▶ Create interface between PyNCT and existing software to model growth



Selected publications

- [P1]** Draelants D., Vanroose W., Broeckhove J., Beemster G.T.S.: *Influence of an exogeneous model parameter on the steady states in an auxin transport model*, Proceedings PMA, 2012.
- [A1]** Draelants D., Broeckhove J., Beemster G.T.S., Vanroose W.: *Pattern formation in a cell based auxin transport model with numerical bifurcation analysis*, J Math Biol, 2013.
- [A1]** Draelants D.¹, Avitabile D.¹, Vanroose W.: *Localized auxin peaks in concentration-based transport models of the shoot apical meristem*, J. R. Soc. Interface, 2015.
- [P1]** Draelants D., Kłosiewicz P., Broeckhove J., Vanroose W.: *Solving general auxin transport models with a numerical continuation toolbox in Python: PyNCT*, LNCS, 2015.

¹These authors contributed equally and should be considered as joint first authors.