On accelerated iterative schemes for neutron transport using residual minimization

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joint work with Riccardo Bardin (U Twente)

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### Outline

Introduction

The transport equation and main theoretical result

Convergence analysis for a weak formulation

Numerical realization via Galerkin approximation

Numerical tests

Conclusions

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# Motivating examples

#### Nuclear reactors



#### Core of reactor CROCUS (EPFL); picture from wikipedia

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# Further applications

- biomedical imaging [Arridge et al 2009, Ntziachristos et al 2003]
- radiation therapy: [Swan et al 2020, St.Aubin et al 2016]
- climate simulation: [Thomas et al '99]



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# The stationary radiative transfer equation (RTE)

a balance equation for streaming, absorption and scattering of a density

$$\begin{split} \hat{\mathbf{s}} \cdot \nabla u(\mathbf{r}, \hat{\mathbf{s}}) + \sigma_t(\mathbf{r})u(\mathbf{r}, \hat{\mathbf{s}}) &= \sigma_s(\mathbf{r})(\Theta u)(\mathbf{r}, \hat{\mathbf{s}}) + q(\mathbf{r}, \hat{\mathbf{s}}) \\ u &= q_\partial \quad \text{on } \Gamma_- := \{(\mathbf{r}, \hat{\mathbf{s}}) \in \partial R \times S \text{ such that } \hat{\mathbf{s}} \cdot \hat{\mathbf{n}}(\mathbf{r}) < 0\} \end{split}$$

 $S \subset \mathbb{R}^{d-1}$  the unit sphere,  $R \subset \mathbb{R}^d$  a Lipschitz domain  $u(\mathbf{r}, \hat{\mathbf{s}})$  directionally resolved density at  $\mathbf{r} \in R$  in direction  $\hat{\mathbf{s}} \in S$  $\sigma_a \ge 0$  absorption rate,  $\sigma_s \ge 0$  scattering rate,  $\sigma_t = \sigma_s + \sigma_a$ 

$$(\Theta u)(\mathbf{r}, \hat{\mathbf{s}}) = \int_{\mathcal{S}} heta(\hat{\mathbf{s}} \cdot \hat{\mathbf{s}}') u(\mathbf{r}, \hat{\mathbf{s}}') d\hat{\mathbf{s}}'$$

scattering from  $\hat{\boldsymbol{s}}' \rightarrow \hat{\boldsymbol{s}}$  with probability

$$heta(\hat{f s}\cdot\hat{f s}') = rac{1}{4\pi}rac{1-g^2}{\left[1-2g(\hat{f s}\cdot\hat{f s}')+g^2
ight]^{3/2}}$$

q and  $q_{\partial}$  internal and boundary sources

[Chandrasekhar ('50)] [Case+Zweifel ('67)] [Ishimaru ('78)] ...

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#### Well-posedness of the stationary RTE

$$\hat{\mathbf{s}} \cdot \nabla u + \sigma_t u = \sigma_s \Theta u + q \quad \text{in } R \times S$$
$$u = q_\partial \qquad \text{on } \Gamma_-$$

**Theorem.** Let  $\sigma_a, \sigma_s \geq 0, q \in L^2(R \times S), q_\partial \in L^2(\Gamma_-; |\hat{\mathbf{s}} \cdot \hat{\mathbf{n}}|)$ . Then the RTE has a unique solution  $u \in L^2(R \times S)$  with

$$\begin{split} \|\hat{\mathbf{s}} \cdot \nabla u\|_{L^2(R \times S)} + \|u\|_{L^2(R \times S)} + \|u\|_{L^2(\Gamma_+;|\hat{\mathbf{s}} \cdot \hat{\mathbf{n}}|)} \\ & \leq C(\|q\|_{L^2(R \times S)} + \|q_\partial\|_{L^2(\Gamma_-;|\hat{\mathbf{s}} \cdot \hat{\mathbf{n}}|)}). \end{split}$$

**Proof (idea)** Consider the mapping  $T : L^2 \to L^2$ ,  $u_k \mapsto u_{k+1}$ , defined by

$$\hat{\mathbf{s}} \cdot \nabla u_{k+1} + \sigma_t u_{k+1} = \sigma_s \Theta u_k + q \quad \text{in } R \times S$$
$$u_{k+1} = q_\partial \qquad \text{on } \Gamma_-.$$

#### Verify conditions of Banach's fixed-point theorem.

[Case Zweifel '63] [Dautray Lions '93] [Agoshkov '98] [Bal Jollivet 2008] [Egger S 2013]

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Verify conditions of Banach's fixed-point theorem.

[Case Zweifel '63] [Dautray Lions '93] [Agoshkov '98] [Bal Jollivet 2008] [Egger S 2013]

Remarks on convergence of source iteration

 $\hat{\mathbf{s}} \cdot \nabla u_{k+1} + \sigma_t u_{k+1} = \sigma_s \Theta u_k + q \text{ in } R \times S, \quad u_{k+1} = q_\delta \text{ on } \Gamma_-.$ 

Convergence rate:  $\rho = \|\sigma_s / \sigma_t\|_{\infty} \approx 1$  for optically thick problems<sup>\*</sup>

Aim: Accelerate the scheme

- Anderson acceleration [Willert et al 2015] [Olivier et al 2022]
- preconditioning using diffusion problems [Adams Larsen 02]
- $\hookrightarrow$  consistent discretization of diffusion problem (e.g., [Warsa et al 2018])
- → subspace correction [Palii S, 2020, Dölz Palii S 2022, Bardin S 2025]

#### Focus here:

- anisotropic scattering and arbitrary dimension
- avoid inner-outer iterations
- higher-order diffusion (or ...)

<sup>[</sup>Adams Larsen 2002], see (\*) [Egger S 2013] for convergence if ho = 1.

#### Modified iteration and main theoretical results

**Step 1.** Source iteration: Given  $u_k \in W$ , compute  $u_{k+\frac{1}{2}} \in W$  solution to

$$\hat{\mathbf{s}} \cdot \nabla u_{k+\frac{1}{2}} + \sigma_t u_{k+\frac{1}{2}} = \sigma_s \Theta u_k + q \text{ in } R \times S, \quad u_{k+\frac{1}{2}} = q_\partial \text{ on } \Gamma_-$$

**Result 1:** 
$$\left\| \mathcal{R}(u_{k+\frac{1}{2}}) \right\|_{\sigma_t} \leq \rho \| \mathcal{R}(u_k) \|_{\sigma_t}$$
 with  $\mathcal{R}(u_k) = u_{k+\frac{1}{2}} - u_k$ .

Step 2. Modify iterate using a correction

$$u_{k+1} := u_{k+\frac{1}{2}} + u_{k+\frac{1}{2}}^{c}$$

obtained by residual minimization over N-dimensional space  $W_N \subset W$ :

$$u_{k+\frac{1}{2}}^{c} := \operatorname{argmin}_{v \in W_{N}} \left\| \mathcal{R}(u_{k+\frac{1}{2}} + v) \right\|_{\sigma_{t}}, \quad \text{with } \|v\|_{\sigma_{t}} := \|\sqrt{\sigma_{t}}v\|_{L^{2}(R \times S)}.$$

**Result 2:** 
$$\|u - u_k\|_{\sigma_t} \leq \frac{\rho^k}{1-\rho} \|\mathcal{R}(u_0)\|_{\sigma_t}$$
 for  $k \geq 0$  and any  $u_0$ .

**Todos:** Proof of results, choice of  $W_N$ , numerical realization.

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Even-odd splitting of the transport equation

Even-odd parities  $u^{\pm}(\hat{\mathbf{s}}) = \frac{1}{2}(u(\hat{\mathbf{s}}) \pm u(-\hat{\mathbf{s}}))$ 

Observations

• 
$$u = u^+ + u^-$$
 is an  $L^2(S)$ -orthogonal splitting

Parity transformation

$$\hat{\mathbf{s}} \cdot \nabla u^+$$
 is odd,  $\Theta u^+$  is even.

Transport equation is equivalent to the system

$$\begin{split} \hat{\mathbf{s}} \cdot \nabla u^{-} + \sigma_t u^{+} &= \sigma_s \Theta u^{+} + q^{+} &\text{in } R \times S \\ \hat{\mathbf{s}} \cdot \nabla u^{+} + \sigma_t u^{-} &= \sigma_s \Theta u^{-} + q^{-} &\text{in } R \times S \\ u^{+} + u^{-} &= q_{\partial} &\text{on } \Gamma_{-} \end{split}$$

[Vladimirov 91] [Egger S 2012]

#### Towards a weak formulation

Multiplying the first equation with smooth function  $v^+$  yields

$$(\hat{\mathbf{s}} \cdot \nabla u^{-}, v^{+})_{R \times S} + (\sigma_{t} u^{+}, v^{+})_{R \times S} = (\sigma_{s} \Theta u^{+}, v^{+})_{R \times S} + (q^{+}, v^{+})_{R \times S}.$$

Apply divergence theorem to first term:

$$(\hat{\mathbf{s}} \cdot \nabla u^-, \mathbf{v}^+)_{R imes S} = -(u^-, \hat{\mathbf{s}} \cdot \nabla \mathbf{v}^+)_{R imes S} + (\hat{\mathbf{s}} \cdot \hat{\mathbf{n}} u^-, \mathbf{v}^+)_{\partial R imes S}$$

**Observation:**  $\hat{\mathbf{s}} \mapsto \hat{\mathbf{s}} \cdot \hat{\mathbf{n}} u^- v^+$  is even. Since  $u^+ + u^- = q_\partial$  on  $\Gamma_-$ :

$$(\hat{\mathbf{s}}\cdot\hat{\mathbf{n}}u^{-},v^{+})_{\partial R imes S}=2(u^{-},v^{+}\hat{\mathbf{s}}\cdot\hat{\mathbf{n}})_{\Gamma_{-}}=2(q_{\partial}-u^{+},v^{+}\hat{\mathbf{s}}\cdot\hat{\mathbf{n}})_{\Gamma_{-}}.$$

Collecting all terms yields

$$(u^+, v^+ | \hat{\mathbf{s}} \cdot \hat{\mathbf{n}} |)_{\Gamma} - (u^-, \hat{\mathbf{s}} \cdot \nabla v^+)_{R \times S} + (\sigma_t u^+, v^+)_{R \times S} = (\sigma_s \Theta u^+, v^+)_{R \times S} + (q^+, v^+)_{R \times S} + 2(q_\partial, v^+ \hat{\mathbf{s}} \cdot \hat{\mathbf{n}})_{\Gamma_-}.$$

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#### Mixed variational framework

Find  $u \in W$  such that for all  $v \in W$ 

$$t(u,v) = s(u,v) + \ell(v),$$

with  $t, s : W \times W \rightarrow \mathbb{R}$ , and  $\ell : W \rightarrow \mathbb{R}$  defined by

$$t(u, v) = (\sigma_t u, v) + (|\hat{\mathbf{s}} \cdot \hat{\mathbf{n}}| u^+, v^+)_{\Gamma} + (\hat{\mathbf{s}} \cdot \nabla u^+, v^-) - (u^-, \hat{\mathbf{s}} \cdot \nabla v^+)$$
  

$$s(u, v) = (\sigma_s \Theta u, v)$$
  

$$\ell(v) = (q, v) - 2(\hat{\mathbf{s}} \cdot \hat{\mathbf{n}} q_\partial, v^+)_{\Gamma_-}$$

▶ odd part 
$$u^- \in L^2(R imes S)^- =: V^-$$

- even part  $u^+ \in W^+$  has more regularity:  $\hat{\mathbf{s}} \cdot \nabla u^+ \in L^2$ , regular trace
- mixed regularity space  $W = W^+ \oplus V^-$ .
- ▶  $\exists ! u \in W$  solution, such that [Egger S 2012, Egger S 2014]

$$\|u\|_{W} \leq C(\inf \sigma_{a}, \|\sigma_{t}\|_{\infty})(\|q\| + \|q_{\partial}\|_{L^{2}(\Gamma_{-};|\hat{\mathbf{s}}\cdot\hat{\mathbf{n}}|)})$$

boundary conditions are incorporated naturally

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#### Convergence analysis

Proof of Result 1 (contraction of residuals). Step 1. Error reduction

**Step 1** becomes: Given  $u_k \in W$ , compute  $u_{k+\frac{1}{2}} \in W$  such that

$$t(u_{k+\frac{1}{2}},v)=s(u_k,v)+\ell(v), \quad \forall v\in W.$$

**Result** (well-known) 
$$\left\| u - u_{k+\frac{1}{2}} \right\|_{\sigma_t} \le \rho \|u - u_k\|_{\sigma_t}$$
, with  $\rho = \|\sigma_s/\sigma_t\|_{\infty}$ .

**Proof.** For  $e_{k+\frac{1}{2}} = u - u_{k+\frac{1}{2}}$  and  $e_k = u - u_k$  we have that

$$t(e_{k+\frac{1}{2}},v)=s(e_k,v), \quad \forall v\in W.$$

Setting  $v = e_{k+\frac{1}{2}}$  and using the Cauchy-Schwarz inequality:

$$\begin{split} \left\| \boldsymbol{e}_{k+\frac{1}{2}} \right\|_{\sigma_{t}}^{2} &= (\sigma_{t} \boldsymbol{e}_{k+\frac{1}{2}}, \boldsymbol{e}_{k+\frac{1}{2}}) \leq t(\boldsymbol{e}_{k+\frac{1}{2}}, \boldsymbol{e}_{k+\frac{1}{2}}) = \boldsymbol{s}(\boldsymbol{e}_{k}, \boldsymbol{e}_{k+\frac{1}{2}}) \\ &\leq \rho \left\| \boldsymbol{e}_{k+\frac{1}{2}} \right\|_{\sigma_{t}} \| \boldsymbol{e}_{k} \|_{\sigma_{t}}. \end{split}$$

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#### Convergence analysis

Proof of Result 1 (contraction of residuals). Step 2. Residuals

Preconditioned residual operator  $\mathcal{R}: \mathcal{W} \to \mathcal{W}$  defined by

$$t(\mathcal{R}(w), v) = \ell(v) - (t(w, v) - s(w, v)), \quad \forall v \in W.$$

**Result 1:** 
$$\left\| \mathcal{R}(\boldsymbol{u}_{k+\frac{1}{2}}) \right\|_{\sigma_t} \leq \rho \| \mathcal{R}(\boldsymbol{u}_k) \|_{\sigma_t}$$
 with  $\| \boldsymbol{v} \|_{\sigma_t} := \| \sqrt{\sigma_t} \boldsymbol{v} \|_{L^2(R \times S)}$ .

#### Convergence analysis

Proof of Result 1. Step 2. The actual proof

Claim: 
$$\mathcal{R}(u_k) = u_{k+\frac{1}{2}} - u_k.$$
  
 $t(\mathcal{R}(u_k), v) = \ell(v) - (t(u_k, v) - s(u_k, v))$   
 $= t(e_k, v) - s(e_k, v) = t(e_k, v) - t(e_{k+\frac{1}{2}}, v)$   
 $= t(u_{k+\frac{1}{2}} - u_k, v), \quad \forall v \in W.$ 

Using the claim:

$$\begin{split} t(\mathcal{R}(u_{k+\frac{1}{2}}),v) &= \ell(v) - (t(u_{k+\frac{1}{2}},v) - s(u_{k+\frac{1}{2}},v)) \\ &= t(e_{k+\frac{1}{2}},v) - s(e_{k+\frac{1}{2}},v) = s(e_k,v) - s(e_{k+\frac{1}{2}},v) \\ &= s(u_{k+\frac{1}{2}} - u_k,v) = s(\mathcal{R}(u_k),v). \end{split}$$

Hence, as in the proof of error reduction:  $\left\| \mathcal{R}(u_{k+\frac{1}{2}}) \right\|_{\sigma_t} \leq \rho \|\mathcal{R}(u_k)\|_{\sigma_t}$ , which is *Result 1*.

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#### Minimization problem

Let  $W_N \subset W$  be a subspace of finite dimension N, compute

$$u_{k+\frac{1}{2}}^{c} := \operatorname{argmin}_{w \in W_{N}} \left\| \mathcal{R}(u_{k+\frac{1}{2}} + w) \right\|_{\sigma_{t}}$$

**Lemma.** The minimization problem has a unique solution  $u_{k+\frac{1}{2}}^{c} \in W_{N}$ .

The new iterate of the scheme is then defined as

$$u_{k+1} = u_{k+\frac{1}{2}} + u_{k+\frac{1}{2}}^{c}.$$

Corollary.  $\|\mathcal{R}(u_{k+1})\|_{\sigma_t} \leq \rho \|\mathcal{R}(u_k)\|_{\sigma_t}$ .

**Remark.** We do not know whether  $||u - u_{k+1}||_{\sigma_t} \leq \rho ||u - u_k||_{\sigma_t}$ .

#### Proof of result 2

Error residual relationship and convergence

**Result 2:** 
$$\|u - u_k\|_{\sigma_t} \leq \frac{\rho^k}{1-\rho} \|\mathcal{R}(u_0)\|_{\sigma_t}$$
 for  $k \geq 0$  and any  $u_0$ .

**Lemma.** For the solution  $u \in W$  it holds that

$$\|u-w\|_{\sigma_t} \leq \frac{1}{1-\rho} \|\mathcal{R}(w)\|_{\sigma_t} \quad \forall w \in W.$$

**Proof of Result 2:** We have for  $w = u_k$ , using Result 1,

$$(1-\rho)\|u-u_k\|_{\sigma_t} \leq \|\mathcal{R}(u_k)\|_{\sigma_t} \leq \rho^k \|\mathcal{R}(u_0)\|_{\sigma_t}.$$

**Remark.** The 'art' here, is to show the error-residual relationship in an appropriate norm  $(\|\cdot\|_{\sigma_t})$ .

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# Galerkin approximation

#### Approximation space

- $\mathcal{T}_h^R$  shape regular, conforming triangulation of R
- $\mathcal{T}_h^S$  shape regular triangulation of S such that  $-\mathcal{K}^S \in \mathcal{T}_h^S$  for any  $\mathcal{K}^S \in \mathcal{T}_h^S$
- ►  $S_h^{\pm} = S_h^{\pm}(\mathcal{T}_h^S)$  finite element spaces of even piecewise constant (+) and odd piecewise linear (-) functions
- X<sub>h</sub><sup>±</sup> = X<sub>h</sub><sup>±</sup>(T<sub>h</sub><sup>R</sup>) finite element spaces of piecewise constant (−) and continuous piecewise linear (+) functions

$$\blacktriangleright W_h = S_h^+ \otimes X_h^+ + S_h^- \otimes X_h^-$$

**Galerkin approximation**: Find  $u_h \in W_h$  such that

$$t(u_h, v_h) = s(u_h, v_h) + \ell(v_h) \quad \forall v_h \in W_h.$$

Galerkin approximation is well-posed and quasi-optimal [Egger S, 2012],

$$\|u-u_h\|_W\leq C\inf_{v_h\in W_h}\|u-v_h\|_W.$$

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#### **Discrete scheme**

**Step 1:** Given  $u_{h,k} \in W_h$ , compute  $u_{h,k+\frac{1}{2}} \in W_h$  such that  $t(u_{h,k+\frac{1}{2}}, v_h) = s(u_{h,k}, v_h) + \ell(v_h), \quad \forall v_h \in W_h.$ 

Step 2.1: Preconditioned residual operator:  $\mathcal{R}_h : W_h \rightarrow W_h$  defined via

$$t(\mathcal{R}_h(w_h), v_h) = \ell(v_h) - (t(w_h, v_h) - s(w_h, v_h)), \quad \forall v_h \in W_h,$$

Step 2.2: Minimization problem: Choose  $W_{h,N} \subset W_h$ , define

$$u_{h,k+\frac{1}{2}}^{c} := \operatorname{argmin}_{w_{h} \in W_{h,N}} \left\| \mathcal{R}_{h}(u_{h,k+\frac{1}{2}} + w_{h}) \right\|_{\sigma_{t}}.$$

Step 2.3: Update

$$u_{h,k+1} = u_{h,k+\frac{1}{2}} + u_{h,k+\frac{1}{2}}^{c}.$$

**Theorem.** For any  $u_{h,0} \in W_h$ , the sequence  $\{u_{h,k}\}$  defined above converges linearly to the discrete solution  $u_h$ , i.e.,

$$\|u_h-u_{h,k}\|_{\sigma_t}\leq \frac{\rho^k}{1-\rho}\|\mathcal{R}_h(u_{h,0})\|_{\sigma_t}.$$

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#### Matrix formulation of mixed formulation

Coefficients **u** of discrete solution  $u_h$  are determined through

Tu = Su + I.

$$\begin{split} \mathbf{T} &:= \begin{bmatrix} \mathbf{B} + \mathbf{M}^+ & -\mathbf{A}^T \\ \mathbf{A} & \mathbf{M}^- \end{bmatrix}, \qquad \mathbf{S} := \begin{bmatrix} \mathbf{S}^+ \\ \mathbf{S}^- \end{bmatrix}, \qquad \mathbf{I} := \begin{bmatrix} \mathbf{I}^+ \\ \mathbf{I}^- \end{bmatrix}, \\ \mathbf{S}^+ &:= \mathbf{\Theta}^+ \otimes \mathbf{M}_{\sigma_s}^+, \qquad \mathbf{S}^- &:= \mathbf{\Theta}^- \otimes \mathbf{M}_{\sigma_s}^-, \\ \mathbf{M}^+ &:= \mathbf{M} \otimes \mathbf{M}_{\sigma_t}^+, \qquad \mathbf{M}^- &:= \mathbf{M}^- \otimes \mathbf{M}_{\sigma_t}^-, \\ \mathbf{A} &:= \sum_{i=1}^d \mathbf{A}_i \otimes \mathbf{D}_i, \qquad \mathbf{B} := \text{blkdiag}(\mathbf{B}_1, \dots, \mathbf{B}_{n_s^+}), \end{split}$$

**Remark.** All matrices are sparse, except  $\Theta^+$  and  $\Theta^-$  (compression [Dölz Palii S, 2020]).

#### Matrix formulation of the iterative scheme

**Step 1** becomes: given  $\mathbf{u}_k$ , compute  $\mathbf{u}_{k+\frac{1}{2}}$ 

$$\mathsf{Tu}_{k+\frac{1}{2}} = \mathsf{Su}_k + \mathsf{I},$$

**Residual operator.** Coordinate vector  $\mathbf{R}(\mathbf{w})$  of  $\mathcal{R}_h(w_h)$  is determined by

$$\mathsf{T}\,\mathsf{R}(\mathsf{w}) = \mathsf{I} - (\mathsf{T} - \mathsf{S})\mathsf{w}.$$

Additionally, define linear map  $\mathbf{R}_0 \mathbf{w} = \mathbf{R}(w) - \mathbf{R}(0)$ .

**Subspace.**  $W_{h,N}$  is a matrix, corresponding to a basis for  $W_{h,N}$ .

Residuals of the subspace:  $\mathbf{R}_0^N = \mathbf{R}_0 \mathbf{W}_{h,N}$ 

$$\begin{array}{ll} \text{Minimization} & (\mathbf{R}_0^N)^T \mathbf{M} \mathbf{R}_0^N w^* = -(\mathbf{R}_0^N)^T \mathbf{M} \, \mathbf{R}(\mathbf{u}_{k+\frac{1}{2}}), \\ \text{New iterate} & \mathbf{u}_{k+1} = \mathbf{u}_{k+\frac{d}{2}} + \mathbf{u}_{k+\frac{1}{2}}^c, \quad \text{with } \mathbf{u}_{k+\frac{1}{2}}^c = \mathbf{W}_{h,N} w^* \\ \text{New residual} & \mathbf{R}(\mathbf{u}_{k+1}) = \mathbf{R}(\mathbf{u}_{k+\frac{1}{2}}) + \mathbf{R}_0^N w^*. \end{array}$$

#### Remarks on solving the linear systems

Solving for  $\mathbf{u}_{k+\frac{1}{2}}$  can be done in two steps:

(i) Solve the symmetric positive definite system

$$(\mathbf{A}^{T}(\mathbf{M}^{-})^{-1}\mathbf{A} + \mathbf{M}^{+} + \mathbf{B})\mathbf{u}_{k+\frac{1}{2}}^{+} = \mathbf{S}^{+}\mathbf{u}_{k}^{+} + \mathbf{I}^{+} + \mathbf{A}^{T}(\mathbf{M}^{-})^{-1}(\mathbf{I}^{-} + \mathbf{S}^{-}\mathbf{u}_{k}^{-}).$$

**Remark.** Block diagonal system with  $n_S^+$  many sparse blocks of size  $n_R^+ \times n_R^+$  and can be solved in parallel, with straightforward parallelization over each element of  $\mathcal{T}_h^S$ .

(ii) Retrieve the odd part by solving the block-diagonal system

$$\mathbf{M}^{-}\mathbf{u}_{k+\frac{1}{2}}^{-} = \mathbf{S}^{-}\mathbf{u}_{k}^{+} - \mathbf{A}\mathbf{u}_{k+\frac{1}{2}}^{+} + \mathbf{I}^{-}.$$

### Space for residual minimization

via Galerkin projection of correction equation

#### Recall:

$$t(u_h, v_h) = s(u_h, v_h) + \ell(v_h) \quad \forall v_h \in W_h,$$
  
$$t(u_{h,k+\frac{1}{2}}, v_h) = s(u_{h,k}, v_h) + \ell(v_h) \quad \forall v_h \in W_h.$$

#### Error equation:

$$t(u_h - u_{h,k+\frac{1}{2}}, v_h) = s(u_h - u_{h,k+\frac{1}{2}}, v_h) + s(u_{h,k+\frac{1}{2}} - u_{h,k}, v_h) \quad \forall v_h \in W_h.$$

**Galerkin projection of error:** onto space  $Y_{h,K} \subset W_h$ :

$$t(u_{h,k+\frac{1}{2}}^{c},v_{h}) = s(u_{h,k+\frac{1}{2}}^{c},v_{h}) + s(u_{h,k+\frac{1}{2}} - u_{h,k},v_{h}) \quad \forall v_{h} \in Y_{h,K}.$$

Correction space for minimization: Define

$$W_{h,N}^{c} := \operatorname{span}\{u_{h,k+\frac{1}{2}}^{c}\} \subset W_{h}.$$

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### Choice of subspace for projected error equation

approximate spherical harmonics

Let  $H_{h,k}^+ \neq 0$  solve the generalized eigenvalue problem

$$(\Theta H_{h,k}^+, v_h^+) = \gamma_k(H_{h,k}^+, v_h^+)$$

for eigenvalues  $\gamma_k \geq 0$  ordered non-increasingly.

Further define  $H^-_{h,k,i} \in S^-_h$  by the relation

$$(H^-_{h,k,i},\psi_l) = (\hat{\mathbf{s}}_i H^+_{h,k},\psi_l)$$
 for all  $l = 1,\ldots,n_S^-, 1 \le i \le d$ .

Define the spaces

$$H_{K}^{+} = \operatorname{span} \{ H_{h,k}^{+} : 1 \leq k \leq K \}$$
  

$$H_{K}^{-} = \operatorname{span} \{ H_{h,k,i}^{-} : 1 \leq k \leq K, \ 1 \leq i \leq d \}$$
  

$$Y_{h,K} = H_{K}^{+} \otimes X_{h}^{+} + H_{K}^{-} \otimes X_{h}^{-} \subset W_{h}.$$

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## Setup of the lattice problem [Brunner (2005)]



 $\sigma_s = 0$  and  $\sigma_a = 1$  in the black regions

 $\sigma_s =$  10 and  $\sigma_a =$  0.01 else  $\rightsquigarrow \rho \approx$  0.999

q = 1 in the grey region (middle) and q = 0 else

### Iteration counts and contraction rates

#### **Discretization parameters**

- R is triangulated using 100 352 elements
- S is triangulated using 1 024 elements
- Number of dofs: 360 121 344
- dimension of W<sup>c</sup><sub>h,N</sub> in residual minimization: 1
- to compute basis of  $W_{h,N}^c$ , we use K functions  $H_{h,k}^+$ .
- stopping criterion  $\|\mathcal{R}_h(u_k)\|_{\sigma_t} < 10^{-6}$

	g							
Κ	0.1	0.3	0.5	0.7	0.9			
0 1 6 15	1018 (0.990) 62 (0.817) 20 (0.532) 12 (0.312)	863 (0.988) 58 (0.805) 25 (0.603) 10 (0.245)	701 (0.984) 54 (0.795) 14 (0.377) 8 (0.157)	531 (0.979) 57 (0.809) 13 (0.371) 8 (0.216)	358 (0.967) 97 (0.882) 31 (0.706) 18 (0.657)			

### Graphical visualization of residual convergence



From left to right, first row g = 0.1, 0.3, 0.5; second row, g = 0.7, 0.9 for K = 0 densely dotted; K = 1 solid; K = 6 dotted; K = 15 dashed.

# Timings

Subspace correction with high-order discrete spherical harmonics pays off

Average time in seconds per iteration for different anisotropy parameters g and order K (total time in hours).

	g							
Κ	0.1	0.3	0.5	0.7	0.9			
0	66 (18.72)	66 (15.93)	68 (13.32)	67 (9.98)	66 (6.63)			
1	156 (2.70)	153 (2.48)	153 (2.30)	155 (2.46)	153 (4.14)			
6	151 (0.84)	158 (1.10)	157 (0.61)	159 (0.57)	156 (1.35)			
15	163 ( 0.54)	168 ( 0.47)	170 ( 0.38)	168 (0.37)	164 (0.82)			

# Grid dependency study

Iteration counts are robust upon mesh refinement

#### Parameters

- ▶ *g* = 0.7
- K = 0 (left) and K = 6 (right)
- >  $n_R^+$  vertices of triangulation of R
- $n_S^+$  elements of triangulation of S

<i>K</i> = 0	$n_S^+$			•	<i>K</i> = 6	$n_S^+$				
$n_R^+$	16	64	256	1024		$n_R^+$	16	64	256	1024
841	475	483	487	488		841	8	8	9	9
3249	499	509	514	515		3 249	8	9	10	10
12769	509	520	525	526		12769	8	10	11	11
50 625	513	524	529	531		50 625	9	11	12	13

# Outline

Introduction

The transport equation and main theoretical result

Convergence analysis for a weak formulation

Numerical realization via Galerkin approximation

Numerical tests

#### Conclusions

### Conclusions

Developed and analyzed an acceleration strategy for the source iteration

- provably convergent
- based on residual minimization over subspaces:
  - similarities to GMRES (if subspace consists of (all) previous iterates)
  - subspaces can be constructed using Galerkin projections
  - improved convergence rates, even for low dimensional correction spaces

Possible extensions and open questions

- Is it possible to quantify the error reduction observed numerically?
- Combine the outlined methodology with a multilevel scheme.
- ls there a better correction for  $g \rightarrow 1$ ?

Riccardo Bardin, Matthias Schlottbom: On accelerated iterative schemes for anisotropic radiative transfer using residual minimization.

accepted at SISC, https://arxiv.org/abs/2407.13356

code: zenodo 14753969