On the diameter and the circuit-diameter of polytopes

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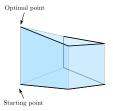


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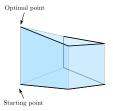
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• Other pivoting rules?

- Many pivoting rules have been proposed in the literature in the past decades
 - Dantzig's rule
 - Greatest improvement
 - Bland's rule
 - Steepest-edge

- Random pivot rules
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• The Simplex algorithm (with e.g. Dantzig's rule) can 'implicitly' solve hard problems [Adler,Papadimitriou&Rubinstein'14, Skutella&Disser'15, Fearnley&Savani'15]

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Related Question: What is the maximum length of a 'shortest path' between two extreme points of a polytope?

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 - the vertices correspond to the extreme points of P
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Remark: In order for a polynomial pivoting rule to exist, a necessary condition is a polynomial bound on the value of the diameter!

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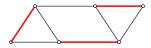
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- [S.'18]: Computing the diameter of a polytope is strongly NP-hard. Computing a pair of vertices at maximum distance is APX-hard.
- \rightarrow This latter result holds for half-integral polytopes with a very easy description (fractional matching polytope).

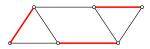
In this talk

- Characterization of the diameter of the fractional matching polytope
- Discuss hardness and algorithmic implications
- Recent generalization: circuit-diameter
- Final remarks and open questions

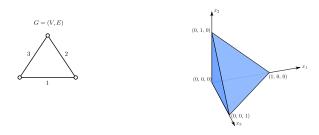
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• The matching polytope (\mathcal{P}_M) is given by the convex hull of characteristic vectors of matchings of G.



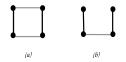
• [Edmonds'65] gave an LP-description of \mathcal{P}_M :

$$\begin{array}{ll} \mathcal{P}_{\mathcal{M}} := \{ x \in \mathbb{R}_{\geq 0}^{m} : & \sum_{e \in E: e \supset v} x_{e} \leq 1 & \forall v \in V, \\ & \sum_{e \in E[S]} x_{e} \leq \frac{|S| - 1}{2} & \forall S \subseteq V : \ |S| \text{ odd} \}. \end{array}$$

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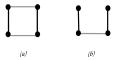
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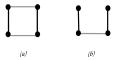
• As a consequence, they showed that the diameter of \mathcal{P}_M is equal to the size of a maximum matching of G, i.e.

$$\textit{diameter}(\mathcal{P}_{M}) = \max_{x \in \textit{vertices}(\mathcal{P}_{M})} \{1^{\mathsf{T}}x\}$$

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$$diameter(\mathcal{P}_M) = \max_{x \in vertices(\mathcal{P}_M)} \{1^T x\} \quad \rightarrow \mathsf{computable in polynomial time}$$

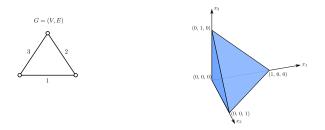
• The fractional matching polytope is given by a standard *LP-relaxation*:

$$\mathcal{P}_{FM} := \{x \in \mathbb{R}^E: \ \sum_{e \in E: e \supset v} x_e \leq 1 \ \forall v \in V, \ x \geq 0\}$$

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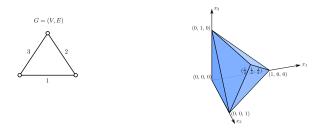
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 - ▶ the edges $\{e \in E : x_e = 1\}$ → induce a matching (\mathcal{M}_x)
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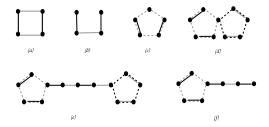
 $diameter(\mathcal{P}_{FM}) = \max_{x \in vertices(\mathcal{P}_{FM})} \{ \mathbf{1}^T x + \frac{|\mathcal{C}_x|}{2} \}$

• **Obs:** For a bipartite graph $C_x = \emptyset \rightarrow diameter(\mathcal{P}_{FM}) = diameter(\mathcal{P}_M)$.

To prove the result, we show that the value max_{x∈vertices(P_{FM})} {1^Tx + |C_x|/2}
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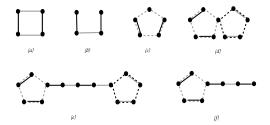
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Note: In all cases, $\left(\# \text{ of degree-1 nodes} + \# \text{ of odd cycles} \right) \leq 2$

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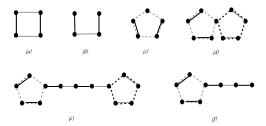


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 - ▶ Note: $(\# \text{ of degree-1 nodes} + \# \text{ of odd cycles}) = 2(1^T w + \frac{|C_w|}{2})$
 - Show: At each move, the above quantity can decrease by at most 2

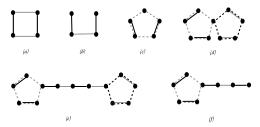


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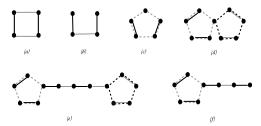
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• Note: An easy "attempt" to go from z to y would be to define:

- ▶ (i) a path from z to a 0/1-vertex \bar{z} by removing one $C \in C_z$ at each step
- (ii) a path from y to a 0/1-vertex \bar{y} by removing one $C \in C_y$ at each step
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...but unfortunately this may lead to paths longer than the claimed bound!

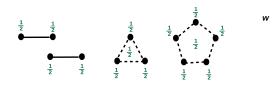
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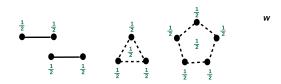
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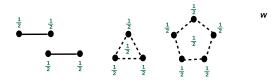
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 - ▶ Rely on a token argument: assign a token of value $\frac{1}{2}$ to each node v and each cycle C in support(w) (Note: total token value = $1^T w + \frac{|C_w|}{2}$)



- Given two distinct vertices z and y of \mathcal{P}_{FM} , we
 - ▶ Define a path of the form: $z \to w \to y$ for some "maximal" vertex w of \mathcal{P}_{FM} satisfying: support(w) \subseteq support(z) \cup support(y)
 - ▶ Rely on a token argument: assign a token of value $\frac{1}{2}$ to each node v and each cycle C in support(w) (Note: total token value = $1^T w + \frac{|C_w|}{2}$)
 - Show: each move on the path can be payed using two tokens of nodes/cycles



Hardness

Theorem [S.'18]

Computing the diameter of a polytope is a strongly NP-hard problem.

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- Reduction from the (strongly) NP-hard problem Partition Into Triangles.
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- With some extra effort, we can strengthen the result to show APX-hardness.

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Given a vertex of a bipartite matching polytope and an objective function, deciding if there exists a neighboring optimal vertex is NP-hard.

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Corollary

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- **Consequences** (unless P=NP):
 - For any efficient pivoting rule, an edge-walking algorithm (like Simplex) can't reach the optimum with a min number of augmentations.

• What if we "relax" the setting by enlarging the set of directions?

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- One interesting way to enlarge the set of directions is to look at circuits: all potential edge-directions that can arise by translating some facets of \mathcal{P} .

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- [Borgwardt, Finhold, Hemmecke'14] formalized the notion of circuit-diameter.

Circuit-diameter: max-value of a shortest path between two extreme points, assuming that at any given point we can move *maximally* along *any* circuit.

• This (more powerful) notion of diameters can be used to get new insights on long-standing conjectures in the literature.

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Corollary [De Loera, Kafer, S.'19]

There exists a polynomial function $f(m, \alpha)$ that bounds the circuit-diameter of any rational polyhedron $\mathcal{P} = \{x \in \mathbb{R}^n : Ax = b, Bx \leq d\}$ with m constraints and maximum encoding length of a coefficient equal to α .

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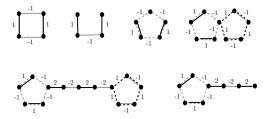
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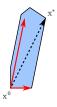
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Proof idea:

- Main ingredient: Showing that moving along a steepest-edge direction yields an n-approximation of moving along a greatest-improvement circuit.
- Improve the analysis relying on the technique of [Frank, Tardos'87], to make the above number strongly polynomial.

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Thank you!