Nando Leijenhorst Joint works with Henry Cohn, David de Laat and Willem de Muinck Keizer

Delft University of Technology, The Netherlands

October 2024

Contents

• Kissing number problem

D. de Laat, N. M. Leijenhorst, and W. H. H. de Muinck Keizer. Optimality and uniqueness of the D₄ root system. arXiv:2404.18794. Apr. 2024.

Contents

- Kissing number problem
- Rounding optimal solutions of large semidefinite programs

D. de Laat, N. M. Leijenhorst, and W. H. H. de Muinck Keizer. Optimality and uniqueness of the D₄ root system. arXiv:2404.18794. Apr. 2024. H. Cohn, D. de Laat, and N. Leijenhorst. Optimality of spherical codes via exact semidefinite programming bounds. arXiv:2403.16874. Mar. 2024.

The kissing number $k(n)$ is the maximum number of unit spheres that simultaneously touch a central unit sphere.

• The 'cannonball packing' shows that $k(3) \ge 12$, and is rigid.

- The 'cannonball packing' shows that $k(3) \ge 12$, and is rigid.
- However, letting spheres touch at the vertices of the regular icosahedron gives a non-rigid configuration of size 12.

- The 'cannonball packing' shows that $k(3) \ge 12$, and is rigid.
- However, letting spheres touch at the vertices of the regular icosahedron gives a non-rigid configuration of size 12.
- The D_4 root system (vertices of the 24-cell) shows that $k(4) \ge 24$, and is rigid.

- The 'cannonball packing' shows that $k(3) \ge 12$, and is rigid.
- However, letting spheres touch at the vertices of the regular icosahedron gives a non-rigid configuration of size 12.
- The D_4 root system (vertices of the 24-cell) shows that $k(4) \ge 24$, and is rigid.
- $k(4) = 24$ by O. Musin in 2008

- The 'cannonball packing' shows that $k(3) \ge 12$, and is rigid.
- However, letting spheres touch at the vertices of the regular icosahedron gives a non-rigid configuration of size 12.
- The D_4 root system (vertices of the 24-cell) shows that $k(4) \ge 24$, and is rigid.
- $k(4) = 24$ by O. Musin in 2008
- Q: can something similar as in dimension 3 happen?

- • The 'cannonball packing' shows that $k(3) \ge 12$, and is rigid.
- However, letting spheres touch at the vertices of the regular icosahedron gives a non-rigid configuration of size 12.
- The D_4 root system (vertices of the 24-cell) shows that $k(4) \ge 24$, and is rigid.
- $k(4) = 24$ by O. Musin in 2008
- Q: can something similar as in dimension 3 happen?
- A: No, we prove that the D_4 root system is the unique optimal kissing configuration in dimension 4, and is an optimal spherical code.

D. de Laat, N. M. Leijenhorst, and W. H. H. de Muinck Keizer. Optimality and uniqueness of the D₄ root system. arXiv:2404.18794. Apr. 2024.

The Lasserre hierarchy for the kissing number problem is a sequence of optimization problems

 $\textsf{las}_1(n) \geq \textsf{las}_2(n) \geq ... \geq \textsf{las}_{k(n)}(n) = k(n).$

The Lasserre hierarchy for the kissing number problem is a sequence of optimization problems

$$
las_1(n) \geq las_2(n) \geq \ldots \geq las_{k(n)}(n) = k(n).
$$

Each of these problem can be approximated using sums-of-squares polynomials and semidefinite programming.

The Lasserre hierarchy for the kissing number problem is a sequence of optimization problems

$$
las_1(n) \geq las_2(n) \geq \ldots \geq las_{k(n)}(n) = k(n).
$$

Each of these problem can be approximated using sums-of-squares polynomials and semidefinite programming.

• In dimension $n = 8$ and $n = 24$, $\log_1(n) = k(n)$ (Delsarte LP bound).

The Lasserre hierarchy for the kissing number problem is a sequence of optimization problems

$$
las_1(n) \geq las_2(n) \geq \ldots \geq las_{k(n)}(n) = k(n).
$$

Each of these problem can be approximated using sums-of-squares polynomials and semidefinite programming.

- In dimension $n = 8$ and $n = 24$, $\log_1(n) = k(n)$ (Delsarte LP bound).
- We prove that $\text{las}_2(4) = k(4) = 24$ by giving an exact solution.

The independent set problem

Let $G = (V, E)$ be a graph. A set $I \subseteq V$ is independent if $\{x, y\} \notin E$ for all $x, y \in I$.

The independent set problem

Let $G = (V, E)$ be a graph. A set $I \subseteq V$ is independent if $\{x, y\} \notin E$ for all $x, y \in I$.

Take $V = S^{n-1}$ and distinct $x, y \in V$ adjacent if $x \cdot y > 1/2$.

The independent set problem

Let $G = (V, E)$ be a graph. A set $I \subseteq V$ is independent if $\{x, y\} \notin E$ for all $x, y \in I$.

Take $V = S^{n-1}$ and distinct $x, y \in V$ adjacent if $x \cdot y > 1/2$. Then the kissing number is the maximum size of an independent set in this graph.

• \mathcal{I}_t : independent sets of size at most t

- \mathcal{I}_t : independent sets of size at most t
- $C(\mathcal{I}_t \times \mathcal{I}_t)_{\geq 0}$: the positive definite kernels on \mathcal{I}_t .

- \mathcal{I}_t : independent sets of size at most t
- $C(\mathcal{I}_t \times \mathcal{I}_t)_{\geq 0}$: the positive definite kernels on \mathcal{I}_t .
- \bullet $A_t: \mathcal{C}(\mathcal{I}_t\times \mathcal{I}_t) \to \mathcal{C}(\mathcal{I}_{2t})$ is the operator

$$
A_t(K)(S) = \sum_{\substack{J,J' \in \mathcal{I}_t \\ J \cup J' = S}} K(J,J')
$$

- • \mathcal{I}_t : independent sets of size at most t
- $C(T_t \times T_t)_{\geq 0}$: the positive definite kernels on T_t .
- \bullet $A_t: \mathcal{C}(\mathcal{I}_t\times \mathcal{I}_t) \to \mathcal{C}(\mathcal{I}_{2t})$ is the operator

$$
A_t(K)(S) = \sum_{\substack{J,J' \in \mathcal{I}_t \\ J \cup J' = S}} K(J,J')
$$

Then the t-th step of the Lasserre hierarchy is given by:

minimize
\n
$$
K(\emptyset, \emptyset)
$$
\nsubject to
\n
$$
A_t K(S) \le -\chi_{\mathcal{I}_{-1}}(S) \qquad \forall S \in \mathcal{I}_{2t} \setminus \{\emptyset\}
$$
\n
$$
K \in C(\mathcal{I}_t \times \mathcal{I}_t)_{\ge 0}
$$

D. de Laat and F. Vallentin. "A semidefinite programming hierarchy for packing problems in discrete geometry". en. In: Mathematical Programming 151.2 (July 2015). arXiv: 1311.3789, pp. 529–553. issn: 0025-5610, 1436-4646. doi: [10.1007/s10107-014-0843-4](https://doi.org/10.1007/s10107-014-0843-4). url: <http://arxiv.org/abs/1311.3789> (visited on 10/26/2021).

minimize $K(\emptyset, \emptyset)$ subject to $A_t K(S) \le -\chi_{\mathcal{I}_{=1}}(S)$ $\forall S \in \mathcal{I}_{2t} \setminus \{\emptyset\}$ $K \in C(\mathcal{I}_t \times \mathcal{I}_t)_{\geq 0}$

$$
\sum_{\substack{J,J'\subseteq C\\|J|,|J'|\leq t}}\mathcal{K}(J,J')
$$

minimize $K(\emptyset, \emptyset)$ subject to $A_t K(S) \le -\chi_{\mathcal{I}_{=1}}(S)$ $\forall S \in \mathcal{I}_{2t} \setminus \{\emptyset\}$ $K \in C(\mathcal{I}_t \times \mathcal{I}_t)_{\geq 0}$

$$
0\leq \sum\limits_{\substack{J,J'\subseteq C\\|J|,|J'|\leq t}}K(J,J')
$$

minimize $K(\emptyset, \emptyset)$ subject to $A_t K(S) \le -\chi_{\mathcal{I}_{=1}}(S)$ $\forall S \in \mathcal{I}_{2t} \setminus \{\emptyset\}$ $K \in C(\mathcal{I}_t \times \mathcal{I}_t)_{\geq 0}$

$$
0 \leq \sum_{\substack{J,J' \subseteq C \\ |J|,|J'| \leq t}} K(J,J') = \sum_{\substack{S \subseteq C \\ |S| \leq 2t}} A_t K(S)
$$

minimize
$$
K(\emptyset, \emptyset)
$$

\nsubject to $A_t K(S) \le -\chi_{\mathcal{I}_{-1}}(S)$ $\forall S \in \mathcal{I}_{2t} \setminus \{\emptyset\}$
\n $K \in C(\mathcal{I}_t \times \mathcal{I}_t)_{\ge 0}$

$$
0 \leq \sum_{\substack{J,J' \subseteq C \\ |J|,|J'| \leq t}} K(J,J') = \sum_{\substack{S \subseteq C \\ |S| \leq 2t}} A_t K(S) \leq K(\varnothing,\varnothing) - |C|
$$

Proof that las_t gives an upper bound

minimize
$$
K(\emptyset, \emptyset)
$$

\nsubject to $A_t K(S) \le -\chi_{\mathcal{I}_{-1}}(S) \qquad \forall S \in \mathcal{I}_{2t} \setminus \{\emptyset\}$
\n $K \in C(\mathcal{I}_t \times \mathcal{I}_t)_{\ge 0}$

Let $C \subset S^{n-1}$ be a independent set and K a feasible kernel. Then

$$
0 \leq \sum_{\substack{J,J' \subseteq C \\ |J|,|J'| \leq t}} K(J,J') = \sum_{\substack{S \subseteq C \\ |S| \leq 2t}} A_t K(S) \leq K(\varnothing,\varnothing) - |C|
$$

so $K(\emptyset, \emptyset) \ge |C|$.

Complementary slackness

If $K(\emptyset, \emptyset) = |C|$, all inequalities in the proof need to be equalities.

Complementary slackness

If $K(\emptyset, \emptyset) = |C|$, all inequalities in the proof need to be equalities. In particular,

$$
A_t(K)(\{x,y\})=0 \qquad \forall \, x \neq y \in C.
$$

Complementary slackness

If $K(\emptyset, \emptyset) = |C|$, all inequalities in the proof need to be equalities. In particular,

$$
A_t(K)(\{x,y\})=0 \qquad \forall x \neq y \in C.
$$

So sharp bounds give information about possible configurations!

By complementary slackness, our exact optimal solution to las₂(4) shows that for all sets C of size 24,

 $x \cdot y \in \{-1, -1/2, 0, 1/2\}$ for all $x \neq y \in C$.

By complementary slackness, our exact optimal solution to $\text{las}_{2}(4)$ shows that for all sets C of size 24,

$$
x \cdot y \in \{-1, -1/2, 0, 1/2\} \quad \text{ for all } x \neq y \in C.
$$

This can be used to show that

 \bullet the D_4 root system is the unique optimal kissing configuration in \mathbb{R}^4 .

By complementary slackness, our exact optimal solution to $\text{las}_{2}(4)$ shows that for all sets C of size 24,

$$
x \cdot y \in \{-1, -1/2, 0, 1/2\} \quad \text{for all } x \neq y \in C.
$$

This can be used to show that

- \bullet the D_4 root system is the unique optimal kissing configuration in \mathbb{R}^4 .
- the D_4 root system is the unique optimal spherical code with 24 points in dimension 4.

 \bullet Write the kernels $K \in C(I_t \times I_t)_{\geq 0}^{O(n)}$ $\sum_{i=0}^{\mathcal{O}(n)}$ in terms of positive semidefinite matrices.

- \bullet Write the kernels $K \in C(I_t \times I_t)_{\geq 0}^{O(n)}$ $\sum_{i=0}^{\mathcal{O}(n)}$ in terms of positive semidefinite matrices.
- Use sum-of-squares polynomials to write the problem as a semidefinite program.

- \bullet Write the kernels $K \in C(I_t \times I_t)_{\geq 0}^{O(n)}$ $\sum_{i=0}^{\mathcal{O}(n)}$ in terms of positive semidefinite matrices.
- Use sum-of-squares polynomials to write the problem as a semidefinite program.
- Solve the semidefinite program up to high enough precision.

- \bullet Write the kernels $K \in C(I_t \times I_t)_{\geq 0}^{O(n)}$ $\sum_{i=0}^{\mathcal{O}(n)}$ in terms of positive semidefinite matrices.
- Use sum-of-squares polynomials to write the problem as a semidefinite program.
- Solve the semidefinite program up to high enough precision.
- Round the solution to an exact optimal solution.

- \bullet Write the kernels $K \in C(I_t \times I_t)_{\geq 0}^{O(n)}$ $\sum_{\geq 0}^{O(n)}$ in terms of positive semidefinite matrices. Time: 2 days
- Use sum-of-squares polynomials to write the problem as a semidefinite program.
- Solve the semidefinite program up to high enough precision.
- Round the solution to an exact optimal solution.

- \bullet Write the kernels $K \in C(I_t \times I_t)_{\geq 0}^{O(n)}$ $\sum_{\geq 0}^{O(n)}$ in terms of positive semidefinite matrices. Time: 2 days
- Use sum-of-squares polynomials to write the problem as a semidefinite program.
- Solve the semidefinite program up to high enough precision. Time: 2 weeks
- Round the solution to an exact optimal solution.

- \bullet Write the kernels $K \in C(I_t \times I_t)_{\geq 0}^{O(n)}$ $\sum_{\geq 0}^{O(n)}$ in terms of positive semidefinite matrices. Time: 2 days
- Use sum-of-squares polynomials to write the problem as a semidefinite program.
- Solve the semidefinite program up to high enough precision. Time: 2 weeks
- Round the solution to an exact optimal solution. Time: 4 hours

- \bullet Write the kernels $K \in C(I_t \times I_t)_{\geq 0}^{O(n)}$ $\sum_{\geq 0}^{O(n)}$ in terms of positive semidefinite matrices. Time: 2 days
- Use sum-of-squares polynomials to write the problem as a semidefinite program.
- Solve the semidefinite program up to high enough precision. Time: 2 weeks
- Round the solution to an exact optimal solution. Time: 4 hours

[Rounding SDP solutions](#page-40-0)

What is rounding?

maximize
$$
\langle C, X \rangle
$$

subject to $\langle A_i, X \rangle = b_i, \quad i = 1, ..., m$
 $X \ge 0$

What is rounding?

maximize
$$
\langle C, X \rangle
$$

subject to $\langle A_i, X \rangle = b_i, i = 1,..., m$
 $X \ge 0$

A solver gives $X^* \geq -\varepsilon I$ such that

 $\langle A_i, X\rangle \approx b_i$

and $\langle\, \mathcal{C}, \mathcal{X}^*\,\rangle$ is approximately optimal. We want an exact optimal solution.

What is rounding?

maximize
$$
\langle C, X \rangle
$$

subject to $\langle A_i, X \rangle = b_i, i = 1,..., m$
 $X \ge 0$

A solver gives $X^* \geq -\varepsilon I$ such that

 $\langle A_i, X\rangle \approx b_i$

and $\langle\, \mathcal{C}, \mathcal{X}^*\,\rangle$ is approximately optimal. We want an exact optimal solution. Assumptions:

- Everything can be done over algebraic fields of low degree (in this talk we use $\mathbb O$ for convenience)
- There is a basis of the kernel of an optimal solution X of small bitsize

Procedure:

1 Find the kernel vectors

Intuition:

Procedure:

- **1** Find the kernel vectors
- 2 Do a basis change (facial reduction)

Intuition:

Procedure:

- **1** Find the kernel vectors
- 2 Do a basis change (facial reduction)

Intuition:

1 We first set the almost 0 eigenvalues to exactly 0.

Procedure:

- **1** Find the kernel vectors
- 2 Do a basis change (facial reduction)
- **3** Find an exact solution close to the original solution in the new basis Intuition:
	- **1** We first set the almost 0 eigenvalues to exactly 0.

Procedure:

- **1** Find the kernel vectors
- 2 Do a basis change (facial reduction)
- **3** Find an exact solution close to the original solution in the new basis

Intuition:

- **1** We first set the almost 0 eigenvalues to exactly 0.
- 2 Then we modify the remaining eigenvectors and eigenvalues a little bit to satisfy the constraints, so that strictly positive eigenvalues stay strictly positive.

Finding the kernel vectors

We want to find exact kernel vectors using the numerical kernel vectors $X^{\ast}.$ Previous approaches used the LLL-algorithm for this $(\mathcal{O}(n^6)).$

Finding the kernel vectors

We want to find exact kernel vectors using the numerical kernel vectors $X^{\ast}.$ Previous approaches used the LLL-algorithm for this $(\mathcal{O}(n^6)).$

Let $\,V$ contain the (numerical) kernel vectors of X^* as rows. Let $\,V_R$ be the row-reduced echelon form of V. Now round V_R to $\mathbb Q$ entry-wise.

Finding the kernel vectors

We want to find exact kernel vectors using the numerical kernel vectors $X^{\ast}.$ Previous approaches used the LLL-algorithm for this $(\mathcal{O}(n^6)).$

Let $\,V$ contain the (numerical) kernel vectors of X^* as rows. Let $\,V_R$ be the row-reduced echelon form of V. Now round V_R to $\mathbb Q$ entry-wise. Since there is a basis of the kernel of low bitsize by assumption, this gives relatively nice kernel vectors.

Let the columns of B form a basis of \mathbb{R}^n with the kernel vectors v_i as the first few basis vectors.

Let the columns of B form a basis of \mathbb{R}^n with the kernel vectors v_i as the first few basis vectors. Then for any optimal matrix X ,

$$
B^{\mathsf{T}} X B = \begin{pmatrix} 0 & 0 \\ 0 & \widehat{X} \end{pmatrix}.
$$

Let the columns of B form a basis of \mathbb{R}^n with the kernel vectors v_i as the first few basis vectors. Then for any optimal matrix X ,

$$
B^{\mathsf{T}} X B = \begin{pmatrix} 0 & 0 \\ 0 & \widehat{X} \end{pmatrix}.
$$

Let \widehat{A}_i be the block of $B^{-1}A_iB^{-\mathcal{T}}$ corresponding to \widehat{X} . Then

$$
\langle \widehat{A}_i, \widehat{X} \rangle = \langle A_i, X \rangle = b_i.
$$

Let the columns of B form a basis of \mathbb{R}^n with the kernel vectors v_i as the first few basis vectors. Then for any optimal matrix X ,

$$
B^{\mathsf{T}} X B = \begin{pmatrix} 0 & 0 \\ 0 & \widehat{X} \end{pmatrix}.
$$

Let \widehat{A}_i be the block of $B^{-1}A_iB^{-\mathcal{T}}$ corresponding to \widehat{X} . Then

$$
\langle \widehat{A}_i, \widehat{X} \rangle = \langle A_i, X \rangle = b_i.
$$

So the optimal face is described by

$$
\hat{F} = \{ \widehat{X} \geq 0 : \langle \widehat{A}_i, \widehat{X} \rangle = b_i, i = 1, \ldots, m \}.
$$

Write the affine constraint $\langle\widehat{A_i},\widehat{X}\rangle$ = b_i as Ax = b by vectorizing $\widehat{X}.$ Goal: find a solution x close to the numerical solution x^* .

Write the affine constraint $\langle\widehat{A_i},\widehat{X}\rangle$ = b_i as Ax = b by vectorizing $\widehat{X}.$ Goal: find a solution x close to the numerical solution x^* .

Idea: interpolate between the closest solution and a solution modifying few entries of $x^\ast.$ Use the pseudoinverse (which gives the closest solution) to solve

$$
\tilde{A}\tilde{x}=b-Ax^*
$$

Write the affine constraint $\langle\widehat{A_i},\widehat{X}\rangle$ = b_i as Ax = b by vectorizing $\widehat{X}.$ Goal: find a solution x close to the numerical solution x^* .

Idea: interpolate between the closest solution and a solution modifying few entries of $x^\ast.$ Use the pseudoinverse (which gives the closest solution) to solve

$$
\tilde{A}\tilde{x}=b-Ax^*
$$

where \tilde{A} contains

Write the affine constraint $\langle\widehat{A_i},\widehat{X}\rangle$ = b_i as Ax = b by vectorizing $\widehat{X}.$ Goal: find a solution x close to the numerical solution x^* .

Idea: interpolate between the closest solution and a solution modifying few entries of $x^\ast.$ Use the pseudoinverse (which gives the closest solution) to solve

$$
\tilde{A}\tilde{x} = b - Ax^*
$$

where \tilde{A} contains

• a basis of the column space

Write the affine constraint $\langle\widehat{A_i},\widehat{X}\rangle$ = b_i as Ax = b by vectorizing $\widehat{X}.$ Goal: find a solution x close to the numerical solution x^* .

Idea: interpolate between the closest solution and a solution modifying few entries of $x^\ast.$ Use the pseudoinverse (which gives the closest solution) to solve

$$
\widetilde{A}\widetilde{x}=b-Ax^*
$$

where \tilde{A} contains

- a basis of the column space
- a small number of extra columns (say 10% more columns than strictly needed)

Write the affine constraint $\langle\widehat{A_i},\widehat{X}\rangle$ = b_i as Ax = b by vectorizing $\widehat{X}.$ Goal: find a solution x close to the numerical solution x^* .

Idea: interpolate between the closest solution and a solution modifying few entries of $x^\ast.$ Use the pseudoinverse (which gives the closest solution) to solve

$$
\tilde{A}\tilde{x} = b - Ax^*
$$

where \tilde{A} contains

• a basis of the column space

• a small number of extra columns (say 10% more columns than strictly needed) This is both fast and gives solutions of small size.

Questions?

D. de Laat, N. M. Leijenhorst, and W. H. H. de Muinck Keizer. Optimality and uniqueness of the $D₄$ root system. ar $Xiv:2404.18794$. Apr. 2024 H. Cohn, D. de Laat, and N. Leijenhorst. Optimality of spherical codes via exact semidefinite programming bounds. arXiv:2403.16874. Mar. 2024

> The rounding procedure is available as part of the Julia SDP solver ClusteredLowRankSolver.jl.

